

Embedded Control System Development with Giotto

www.eecs.berkeley.edu/~fresco/giotto

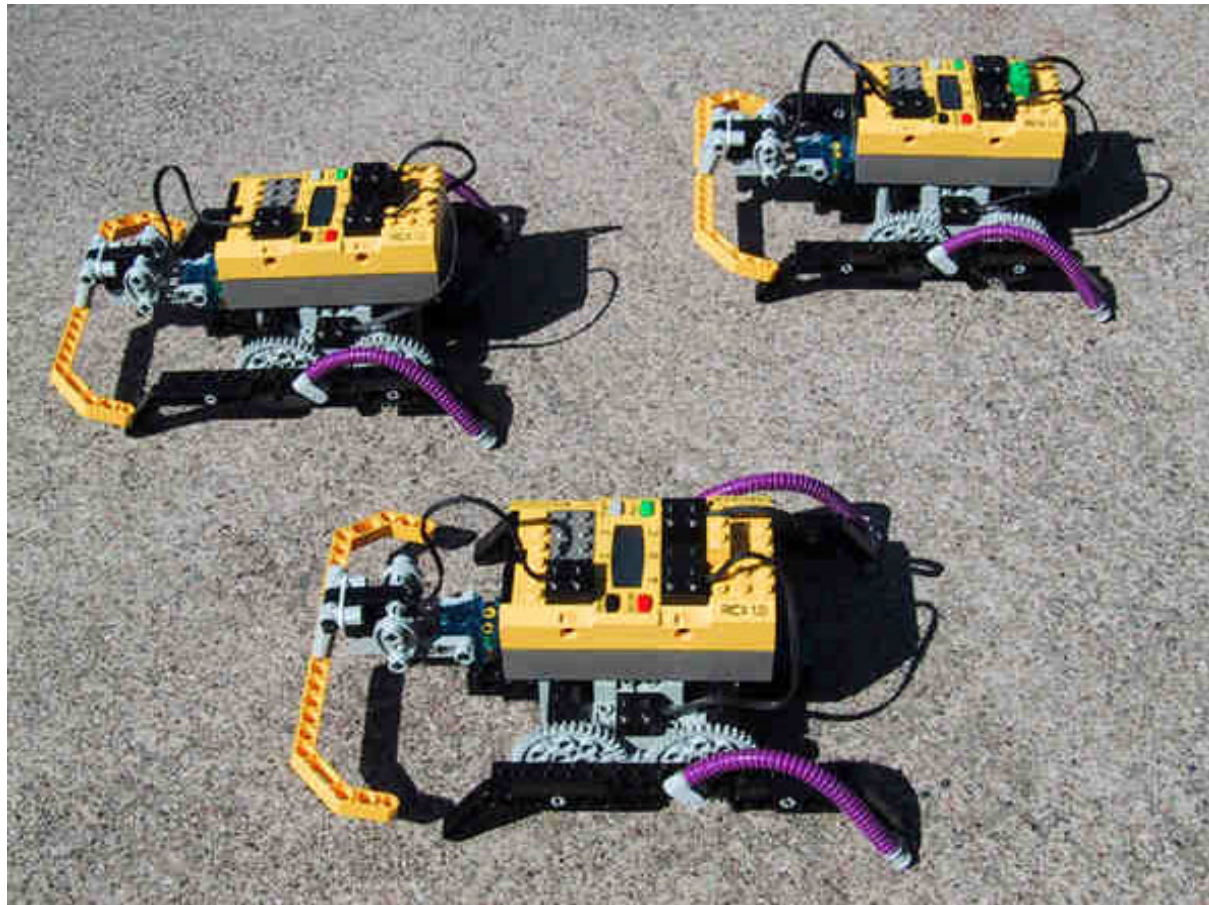
Thomas A. Henzinger, Ben Horowitz, Christoph Meyer Kirsch

UC Berkeley

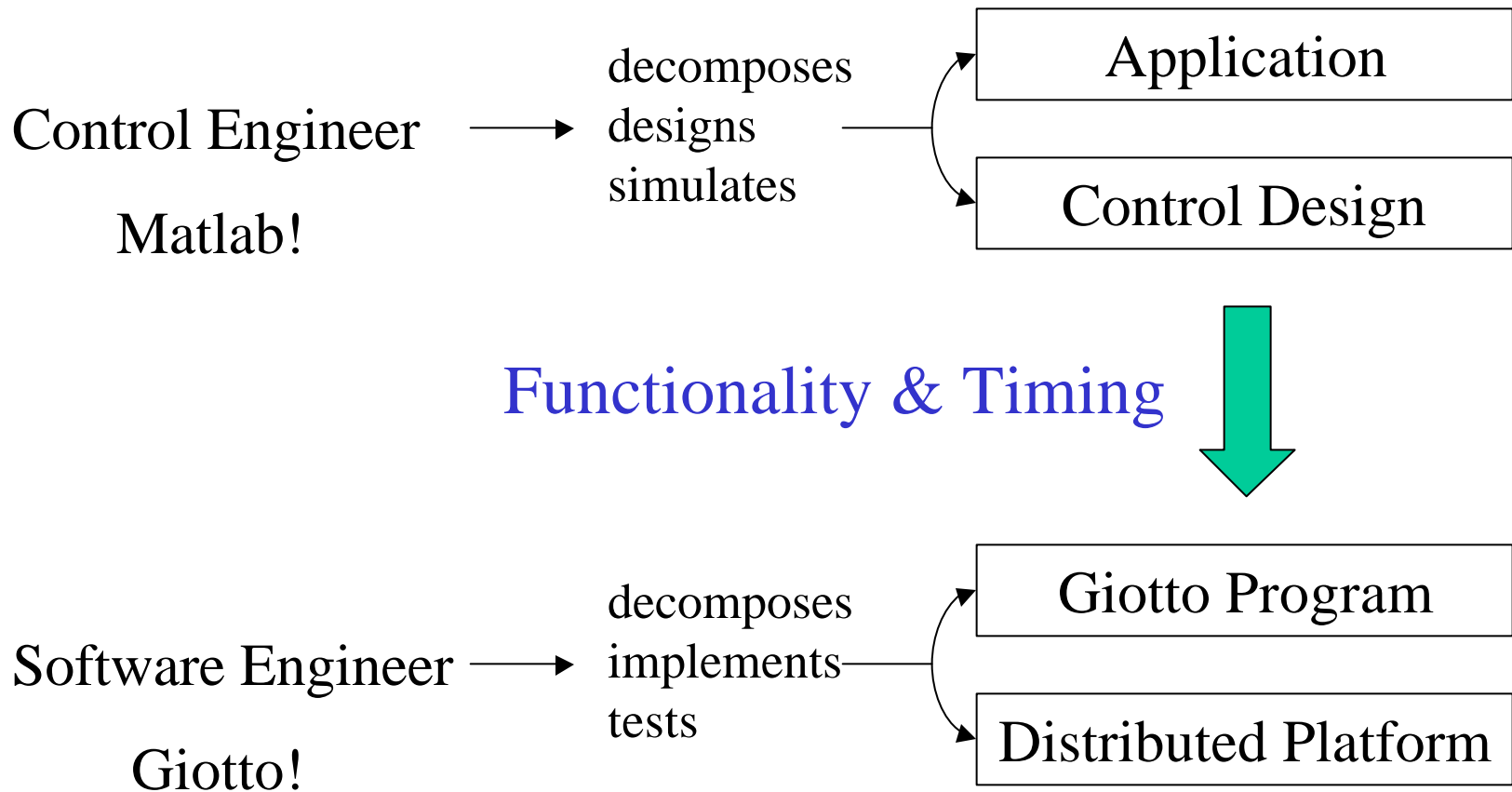
Giotto

- Giotto is a **time-triggered** and **platform independent** programming language + compiler + runtime library
- Giotto aims at **hard real-time** control applications on distributed platforms (safety-critical applications)
- Giotto provides an **abstract** programming model for embedded control system development
- Giotto runtime library for **VxWorks**, model of computation in **Ptolemy II** (Edward Lee, UC Berkeley)

Sneak Preview



Embedded System Development



Decomposition: Giotto Modes

Control Engineer → decomposes

Control Design

Preserving Structure



Software Engineer → decomposes

Giotto Program

The Giotto Compiler

Software Engineer

↓
decomposes
implements
tests

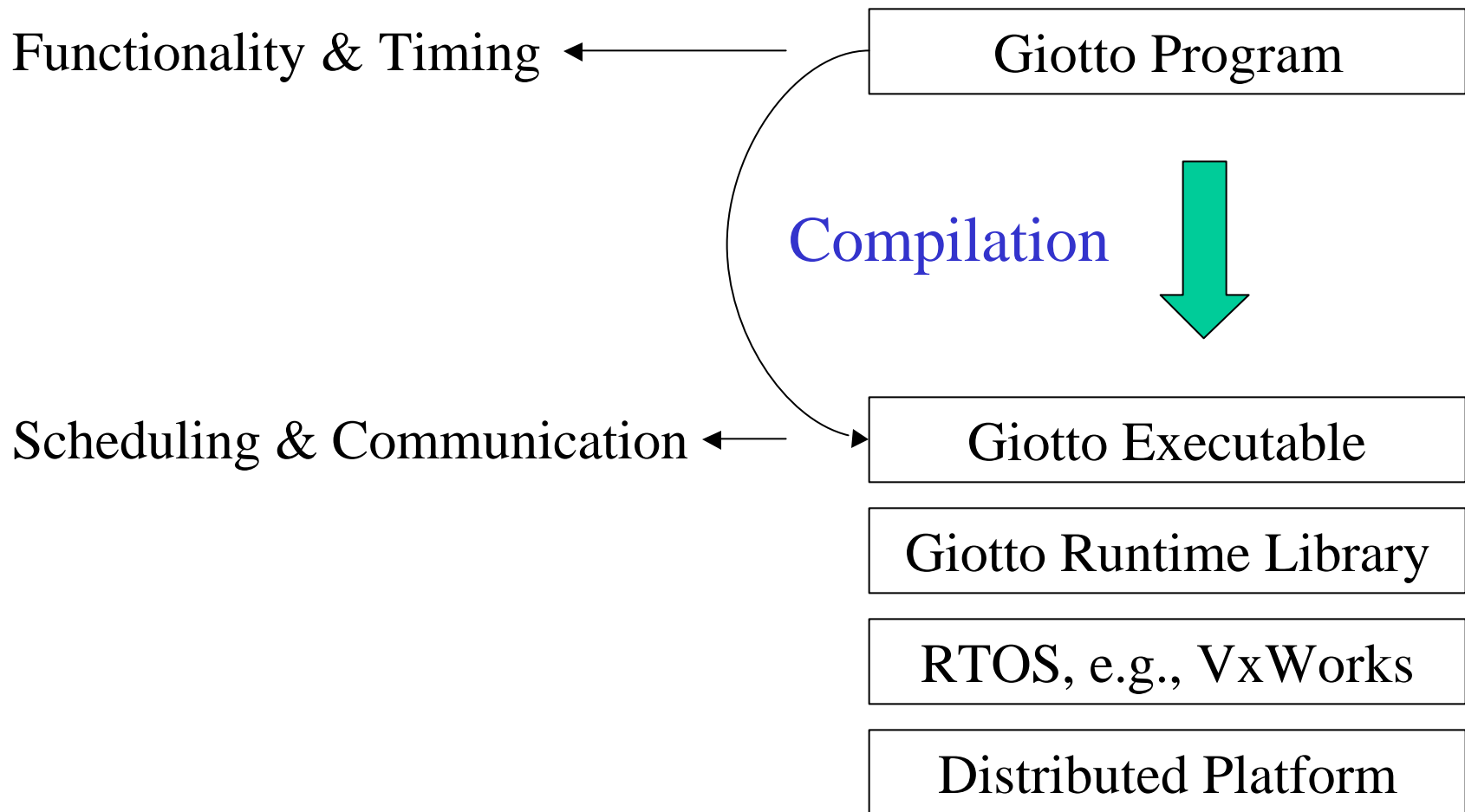
Giotto Program

Compilation

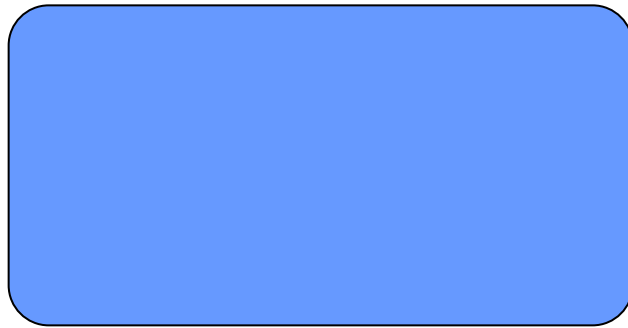
Distributed Platform



The Giotto Compiler



A Task

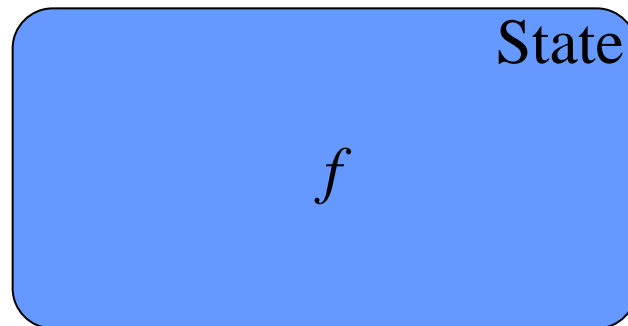


Abstract Syntax of a Task

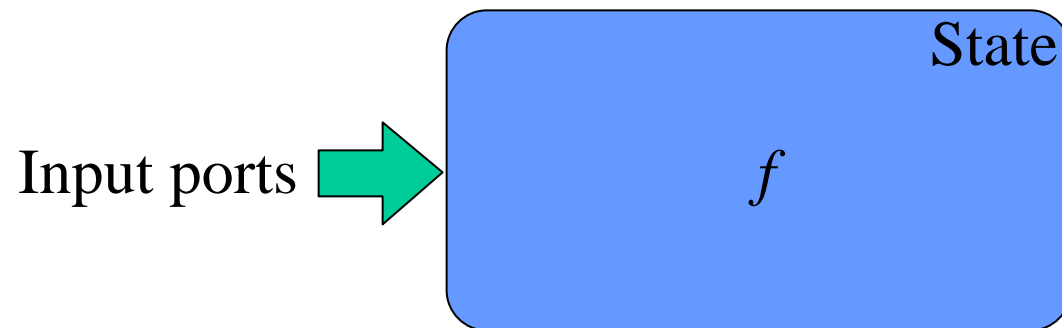


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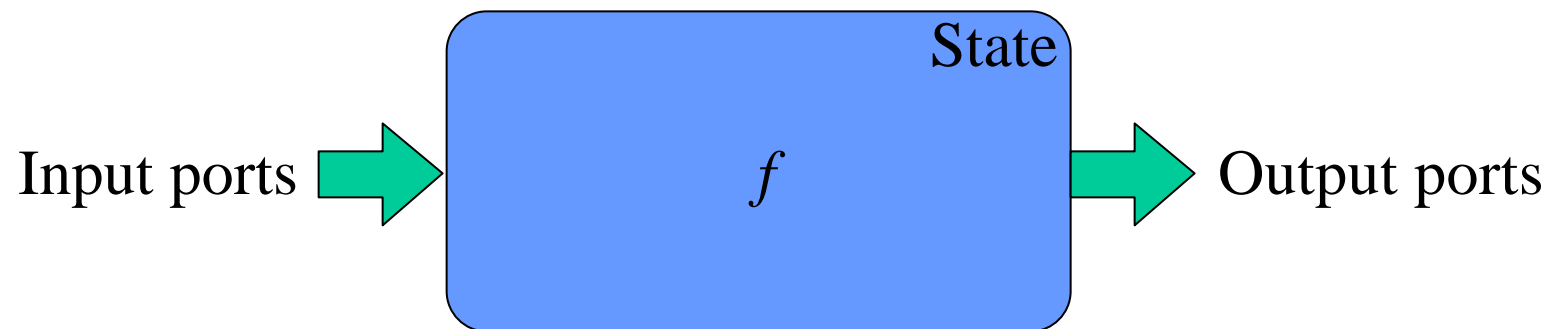
Abstract Syntax of a Task



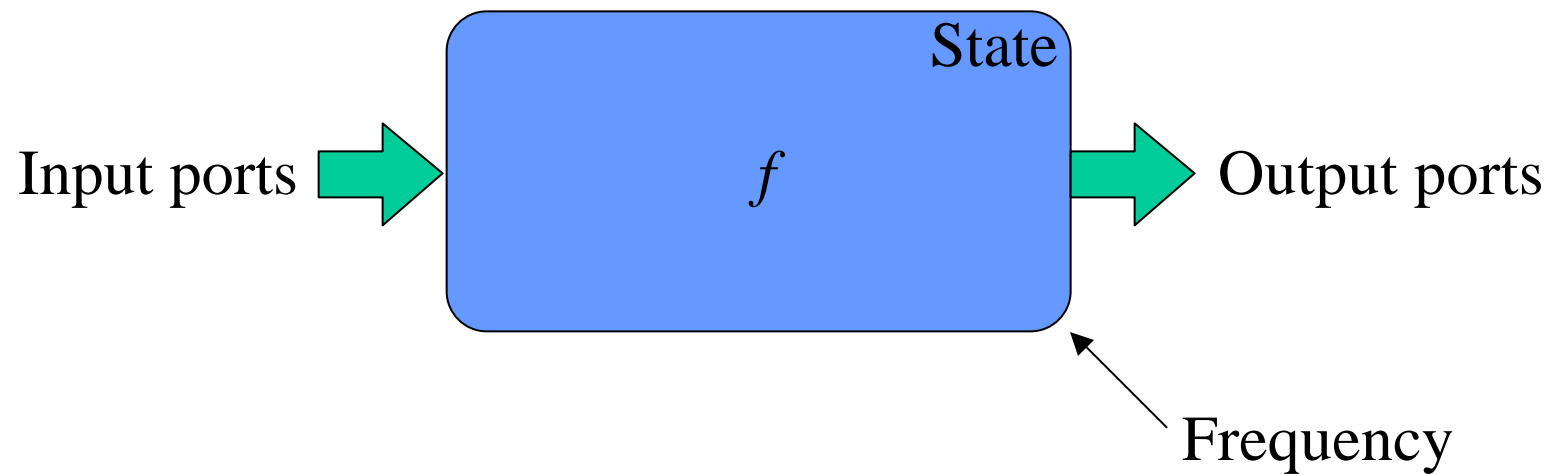
Abstract Syntax of a Task



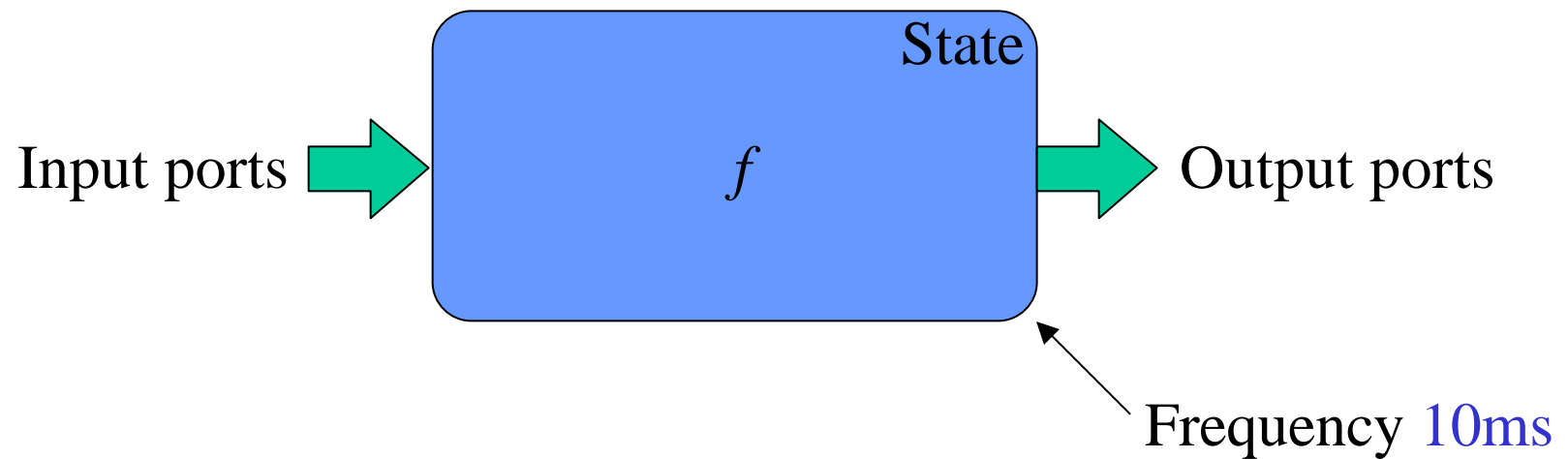
Abstract Syntax of a Task



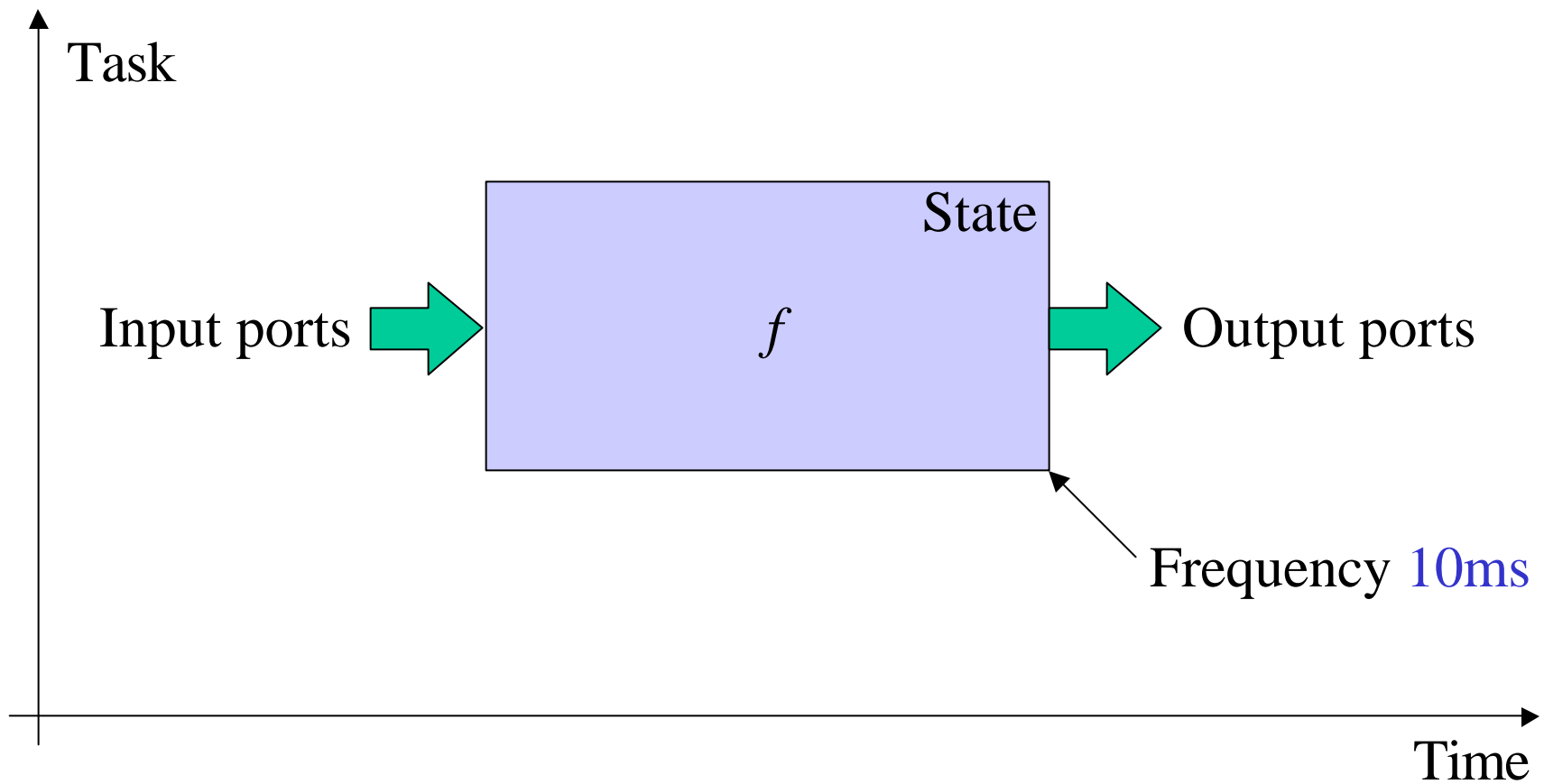
Abstract Syntax of a Task



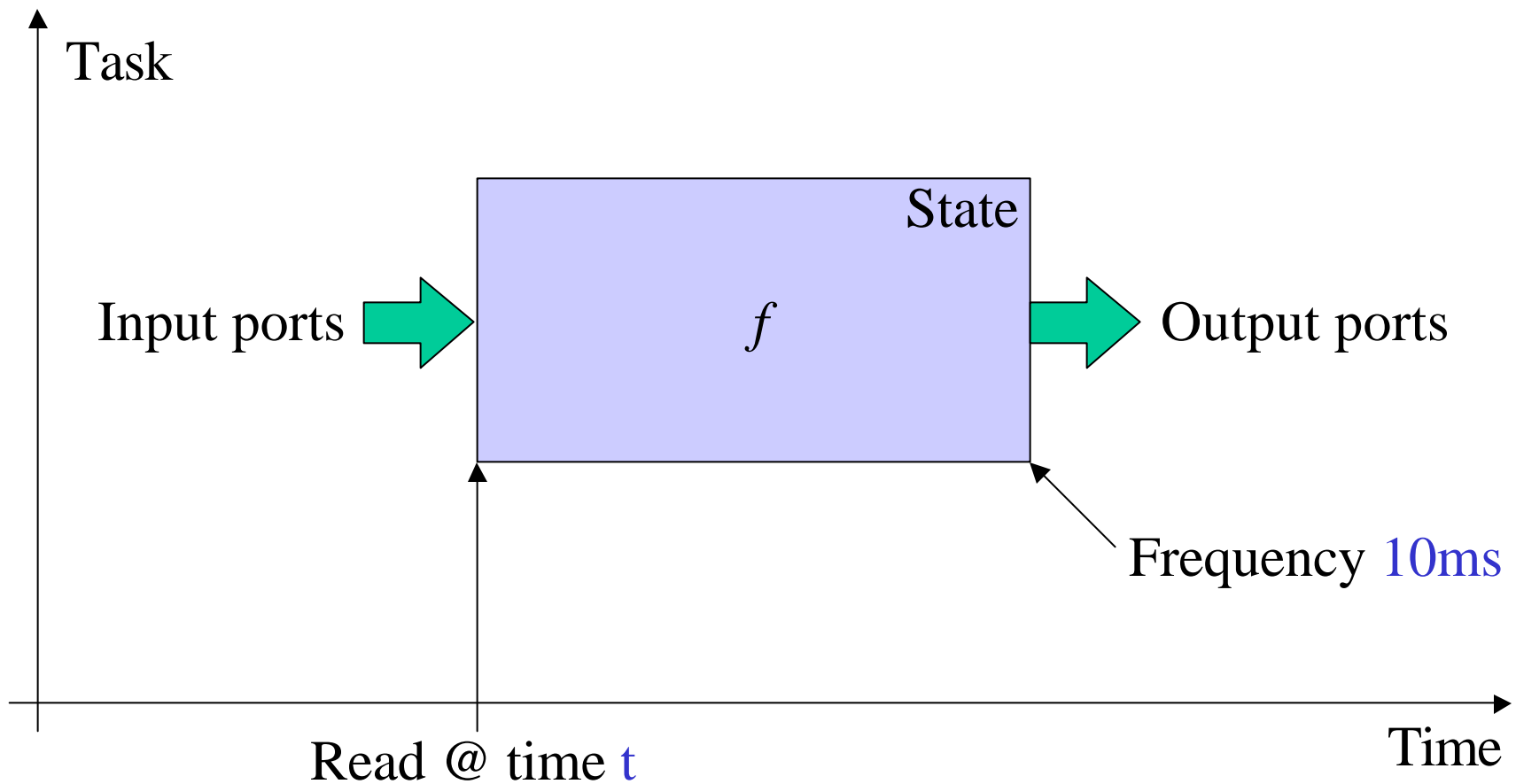
Semantics of a Task



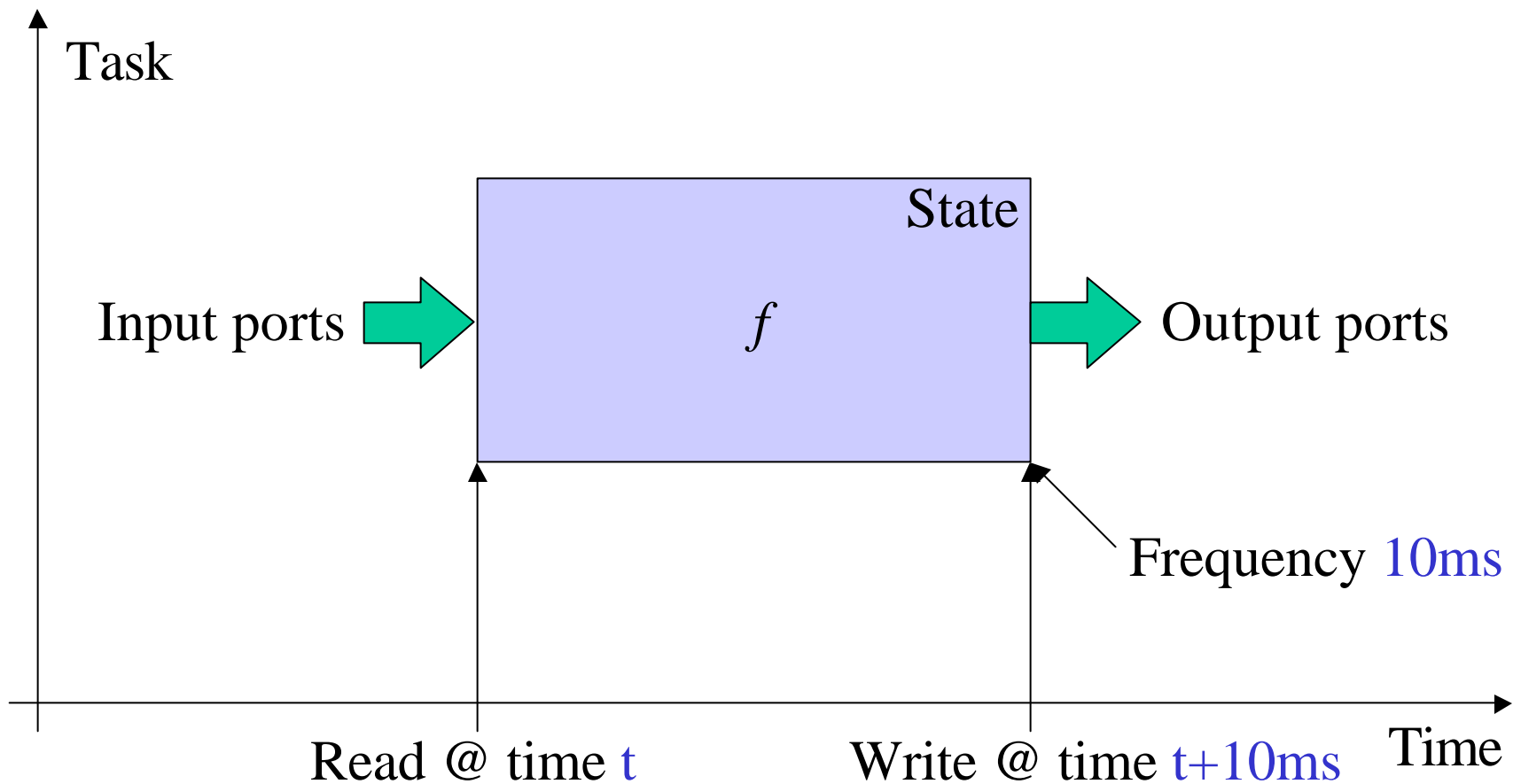
Semantics of a Task



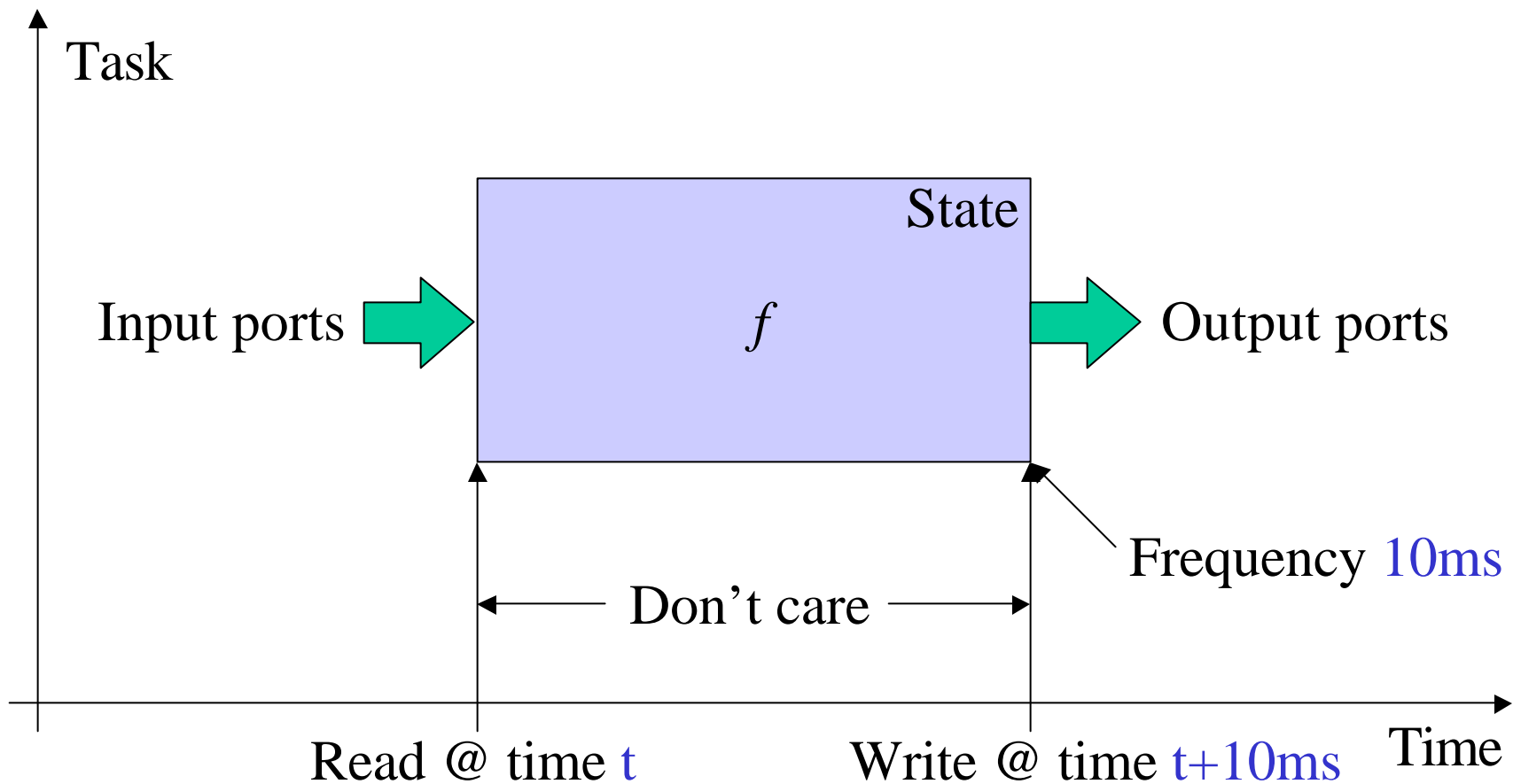
Semantics of a Task



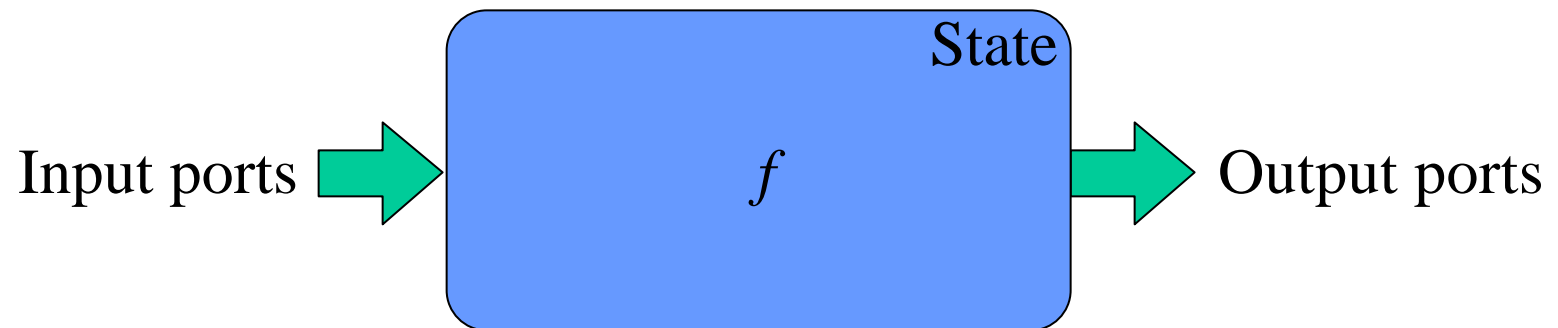
Semantics of a Task



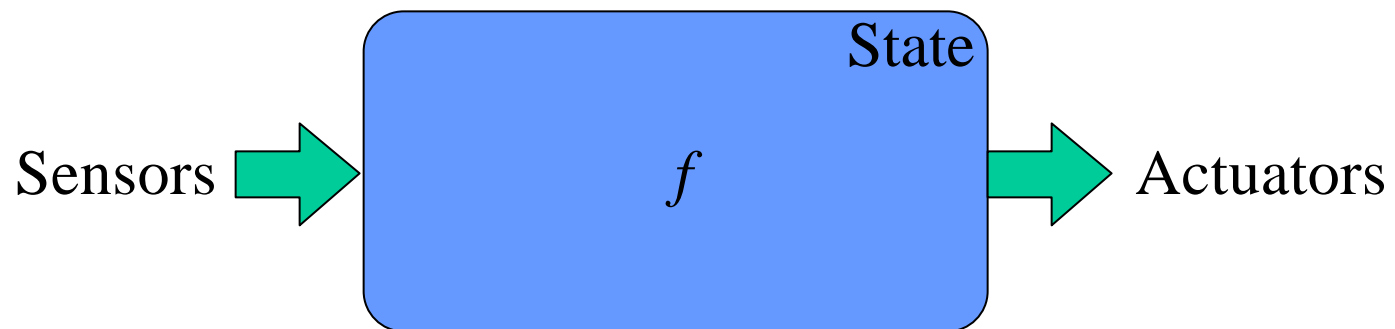
Semantics of a Task



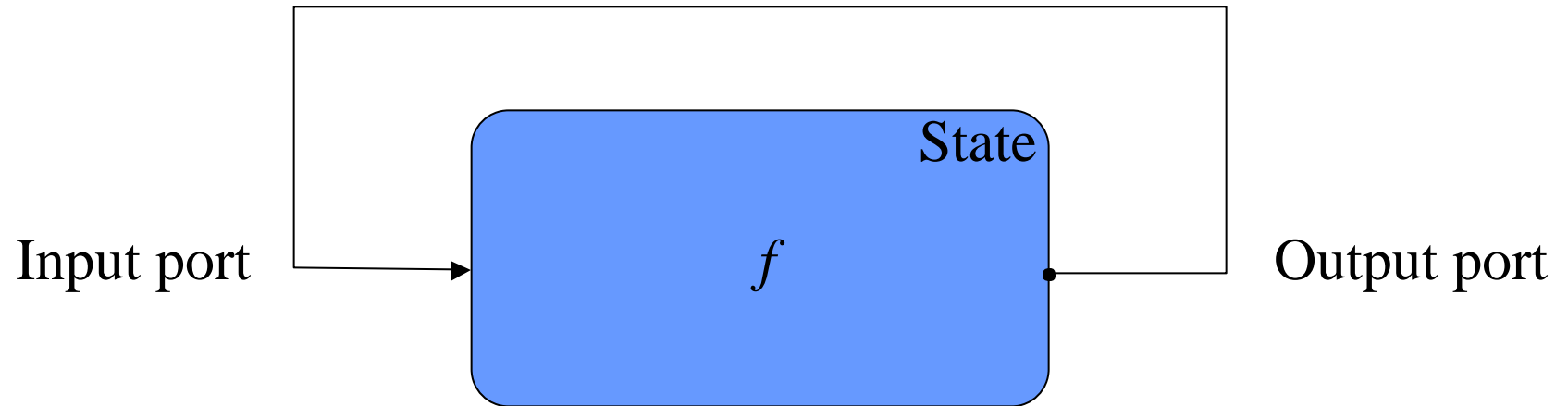
Data Flow



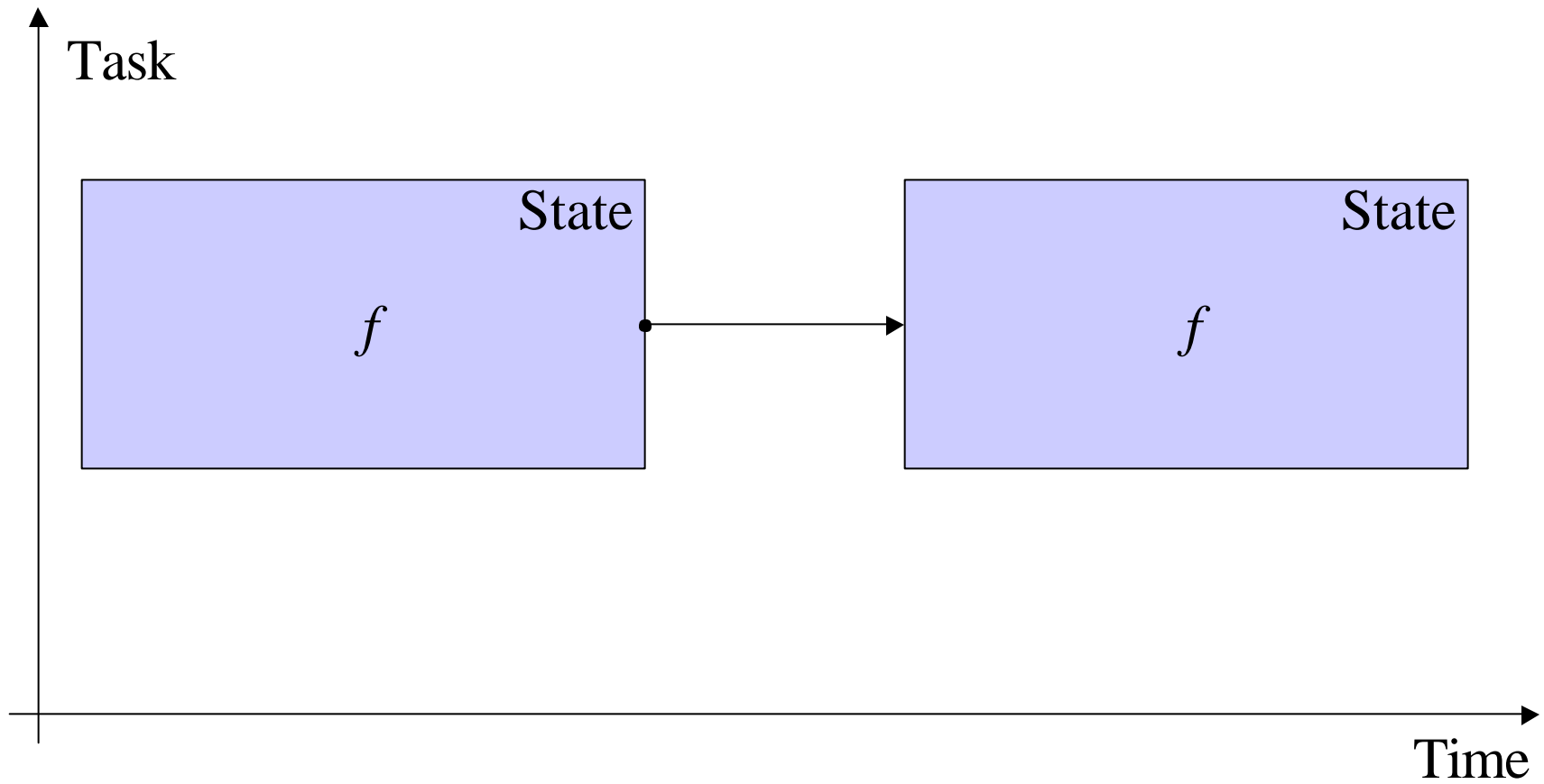
Sensor - Control Law - Actuator



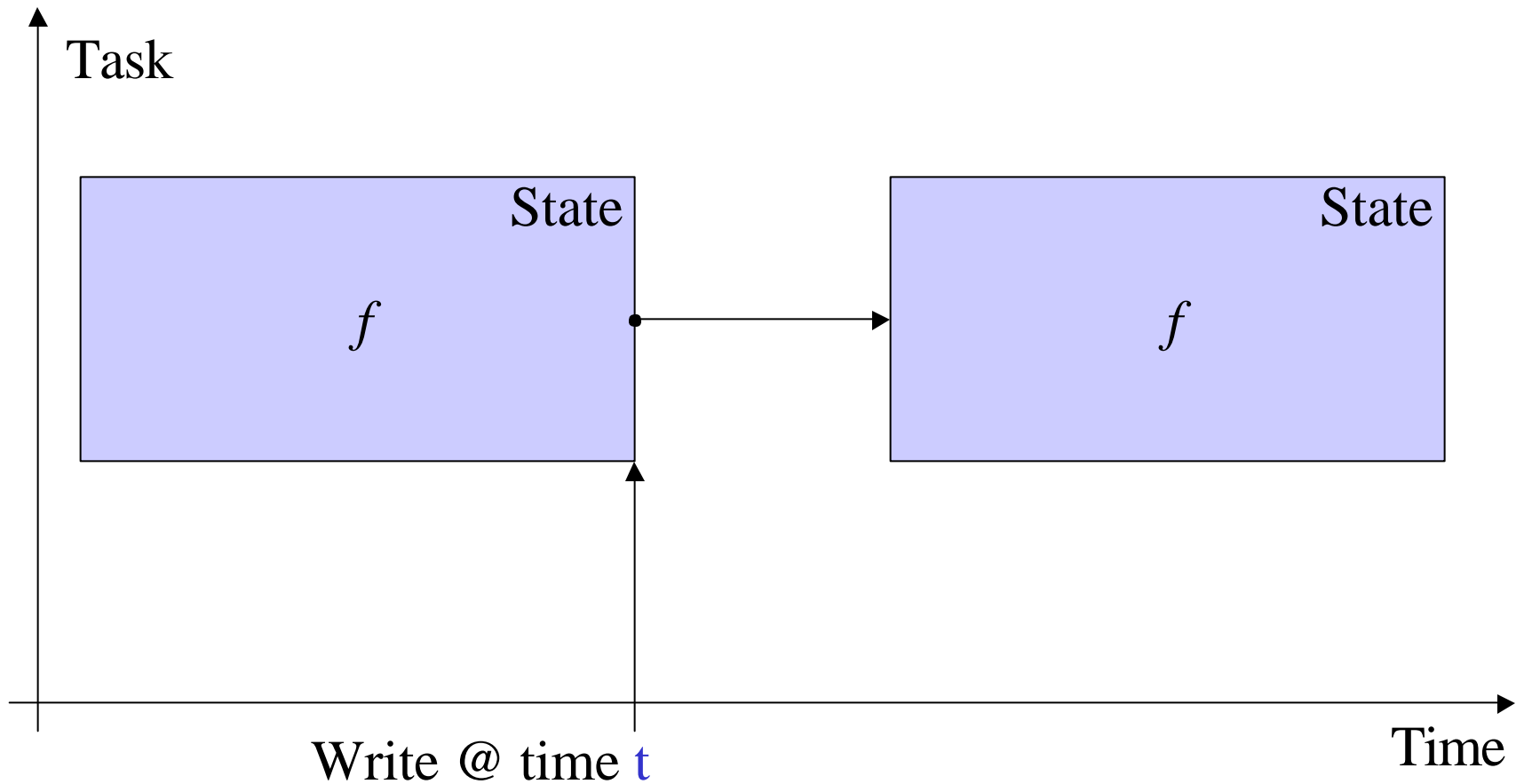
Intertask Communication



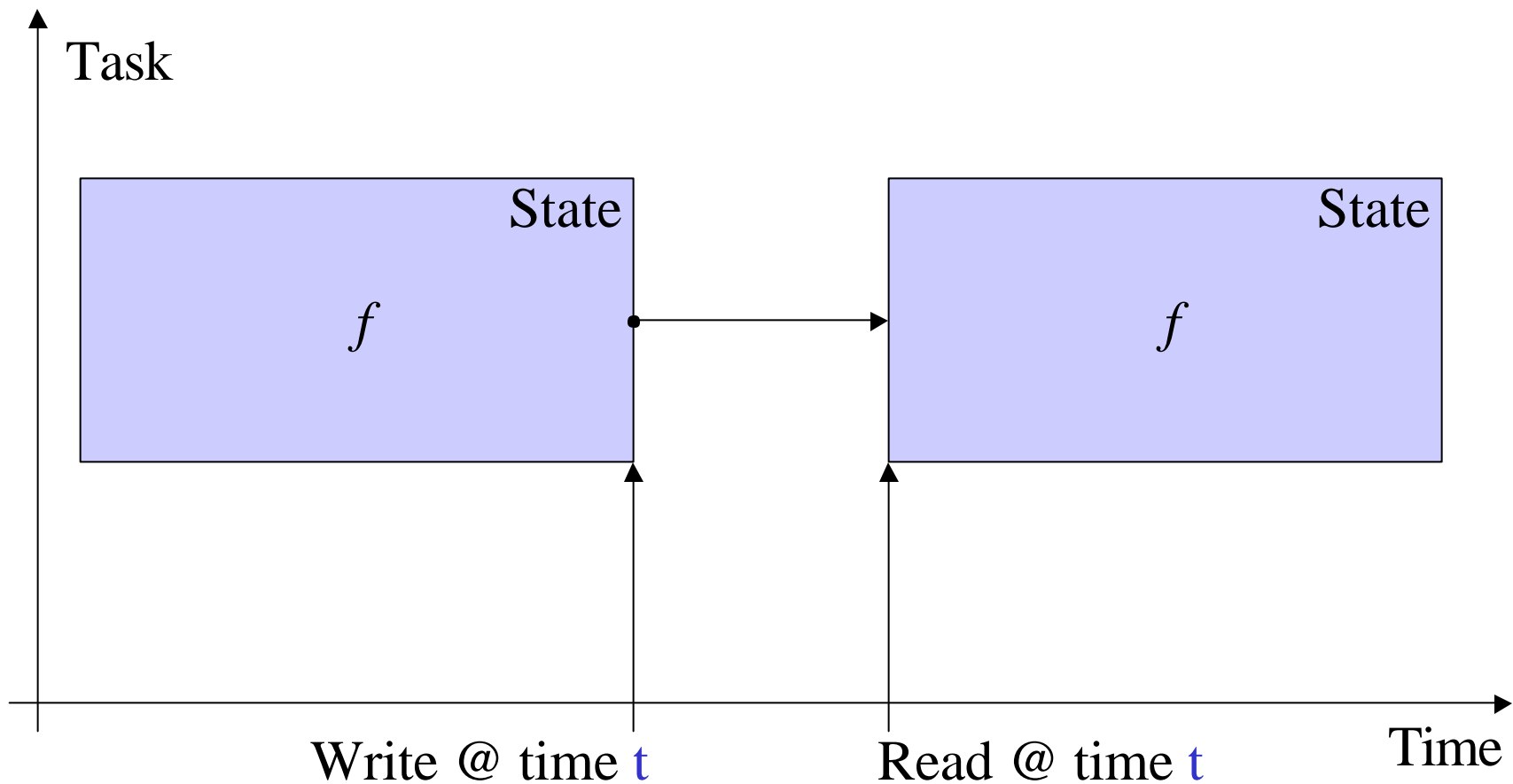
Data Flow Semantics



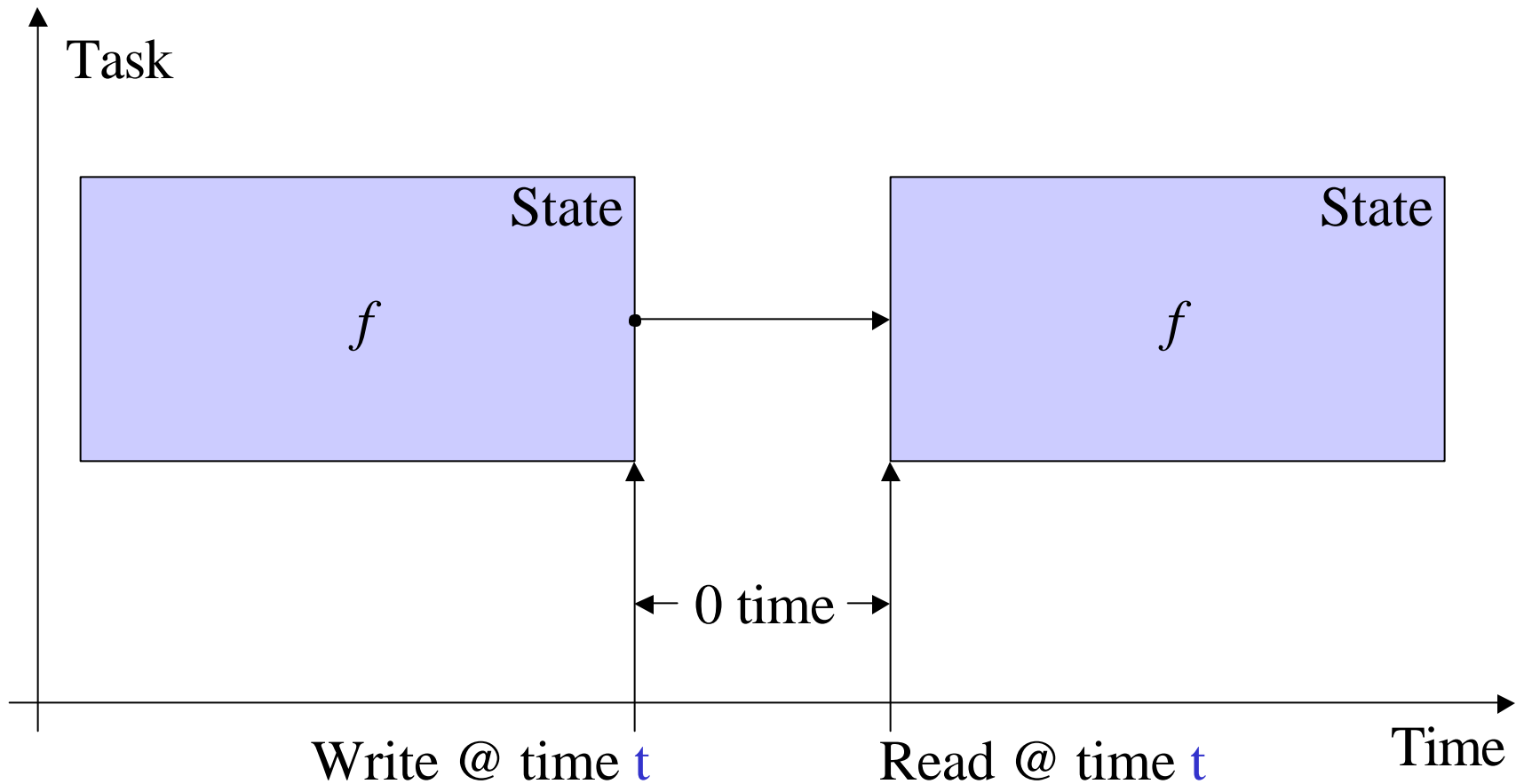
Data Flow Semantics



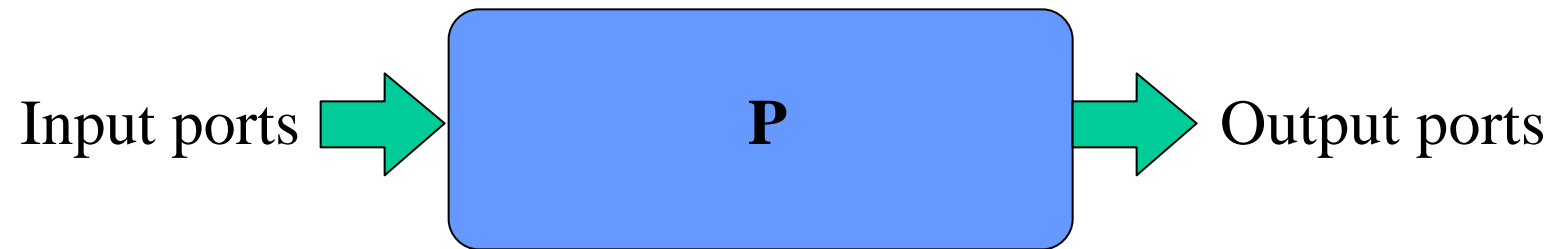
Data Flow Semantics



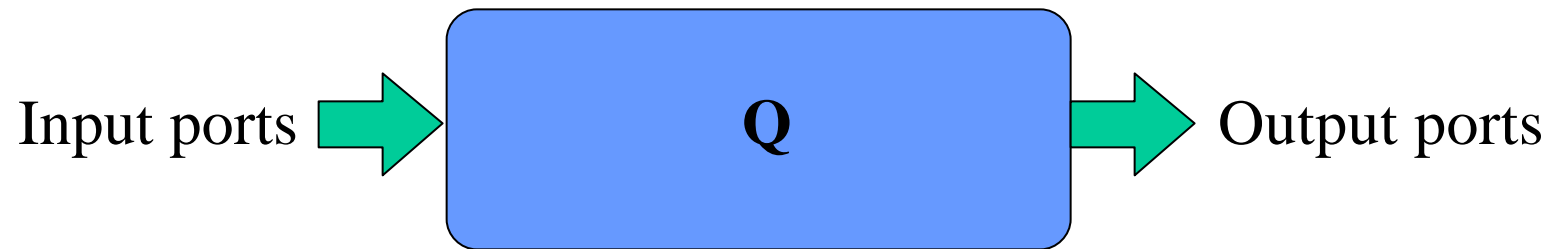
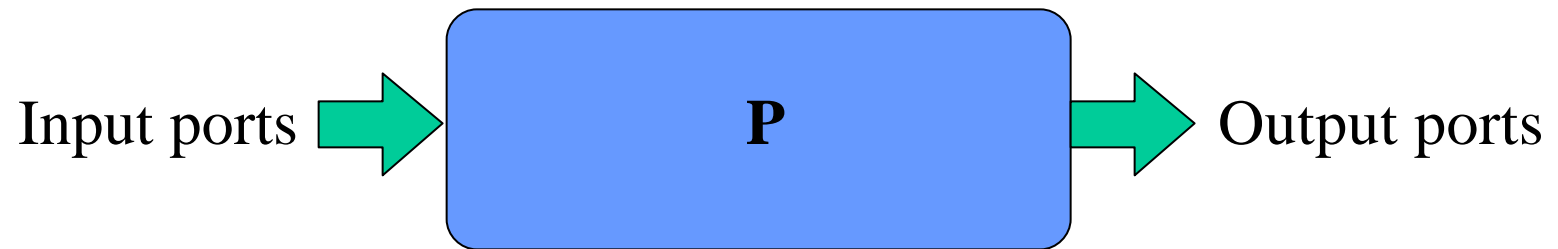
Data Flow Semantics



Two Tasks



Two Tasks

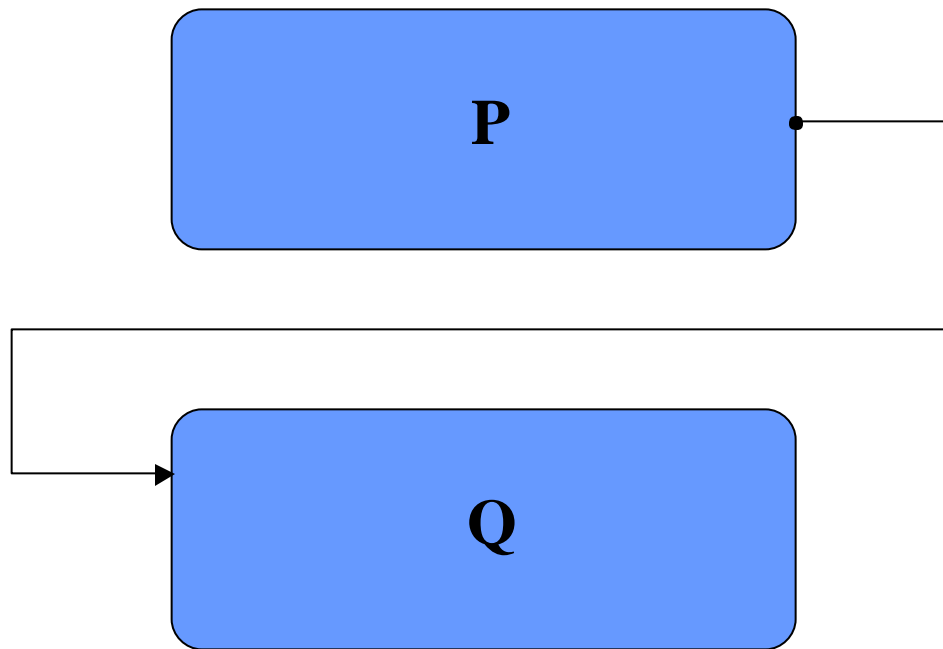


Connections

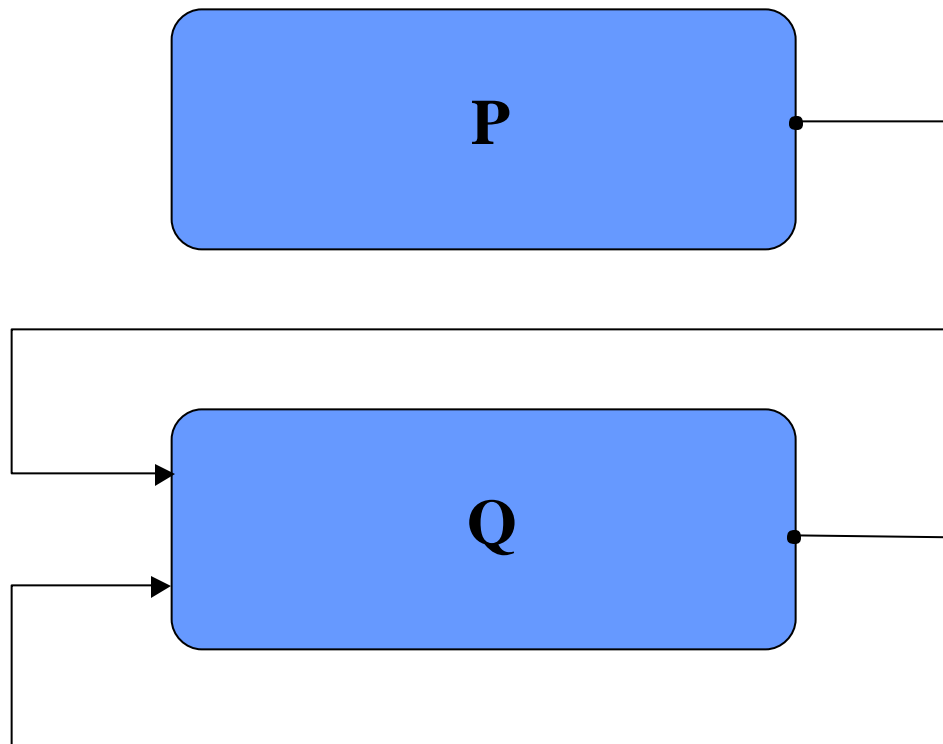
P

Q

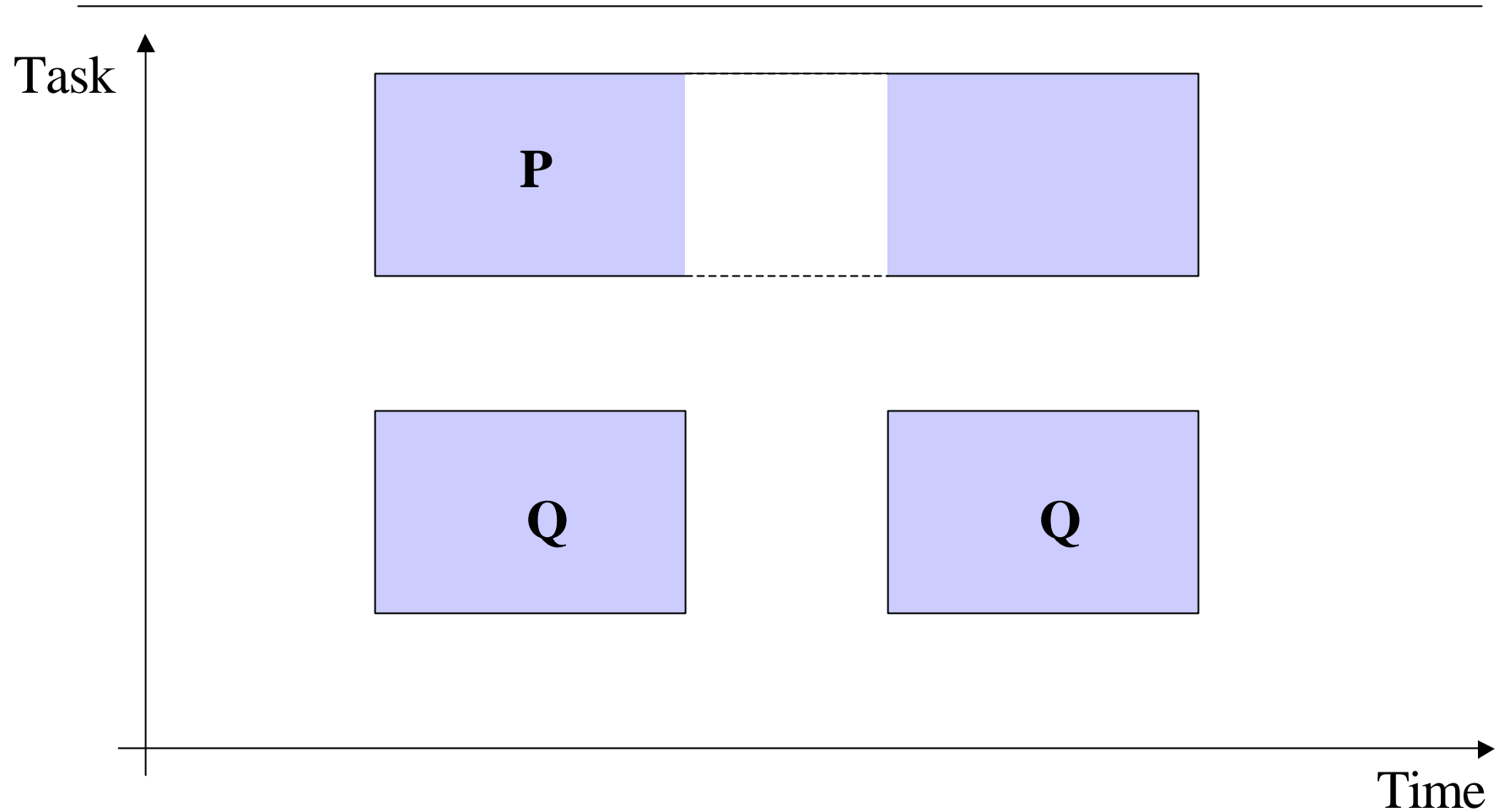
Connections



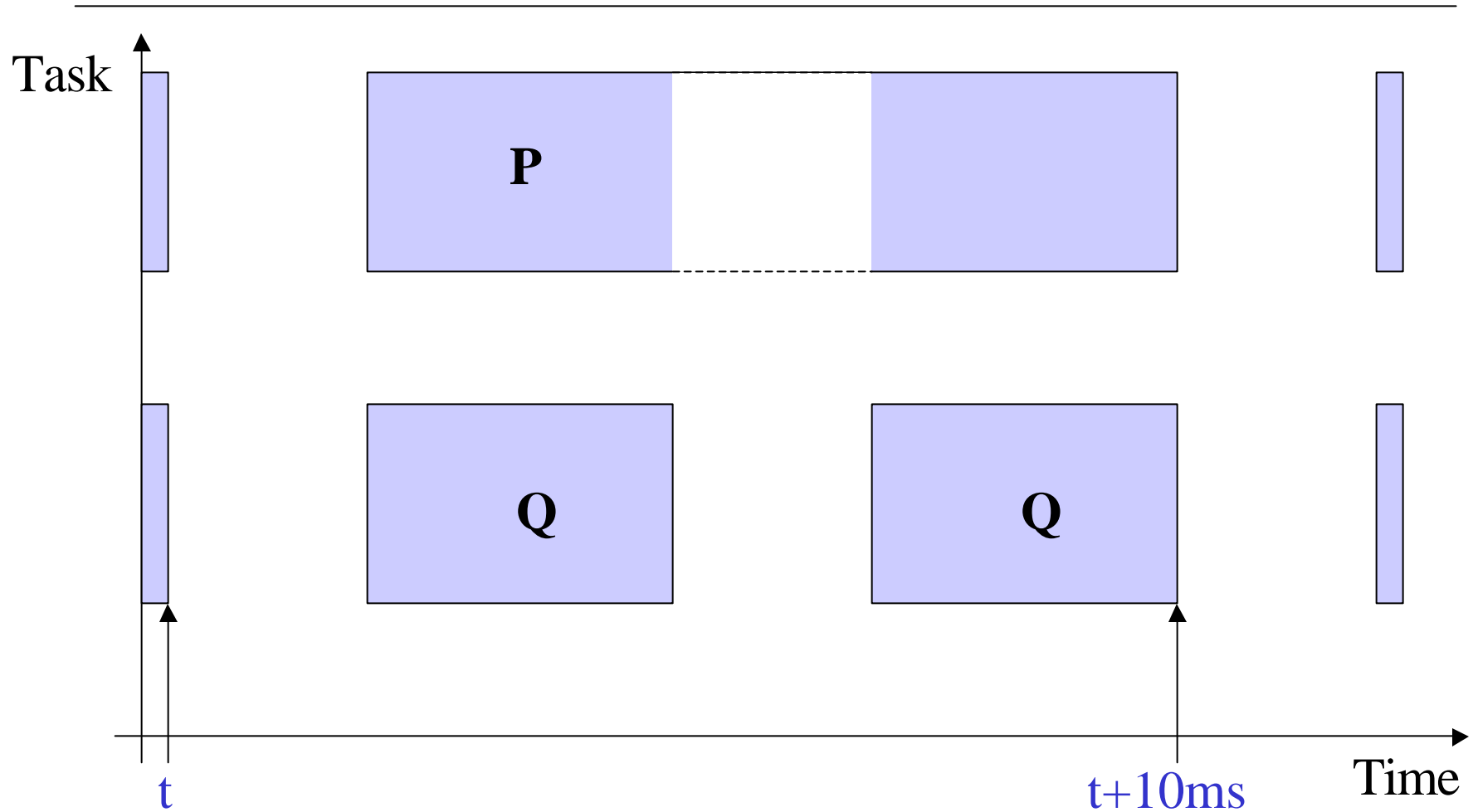
Connections



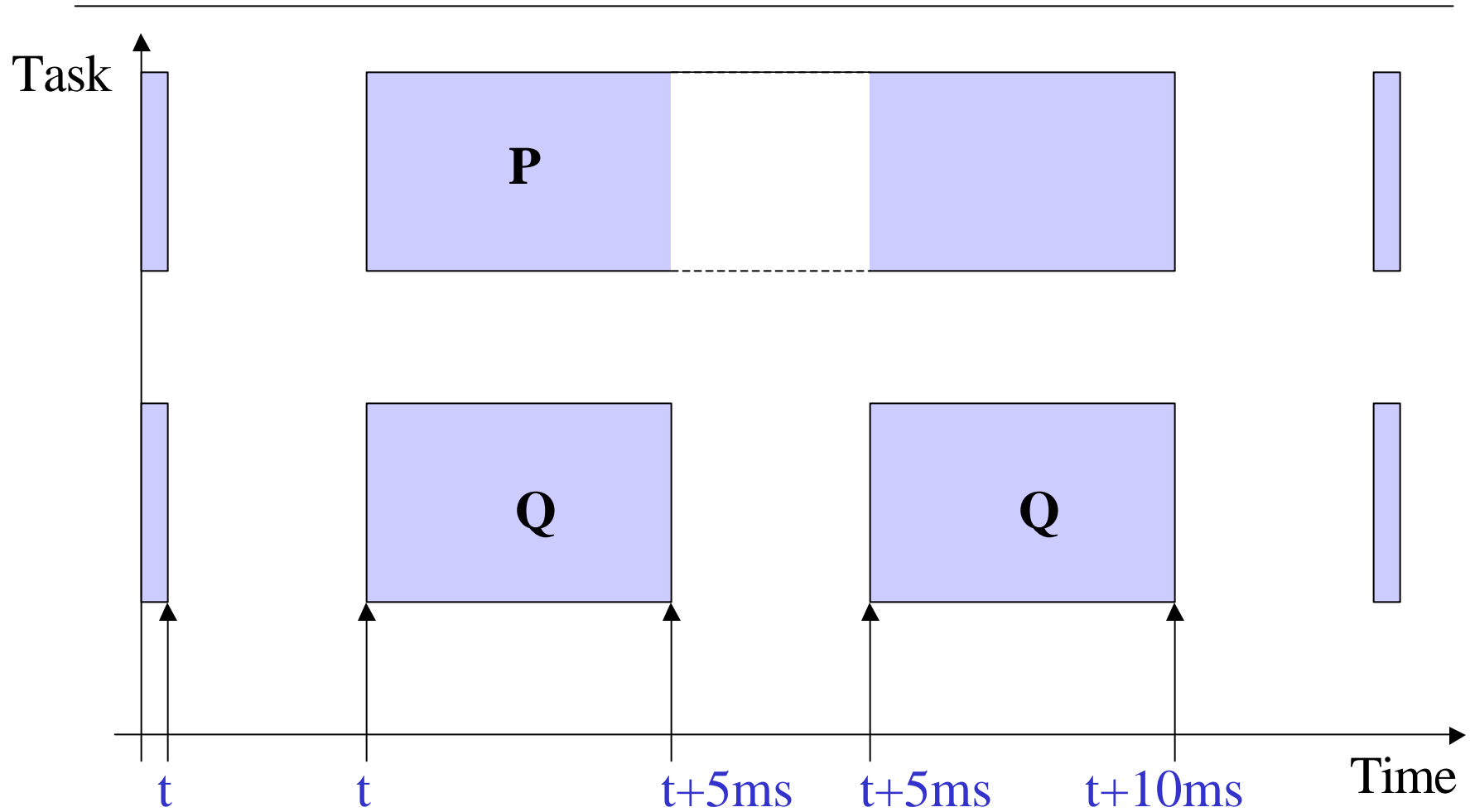
Different Periodicity



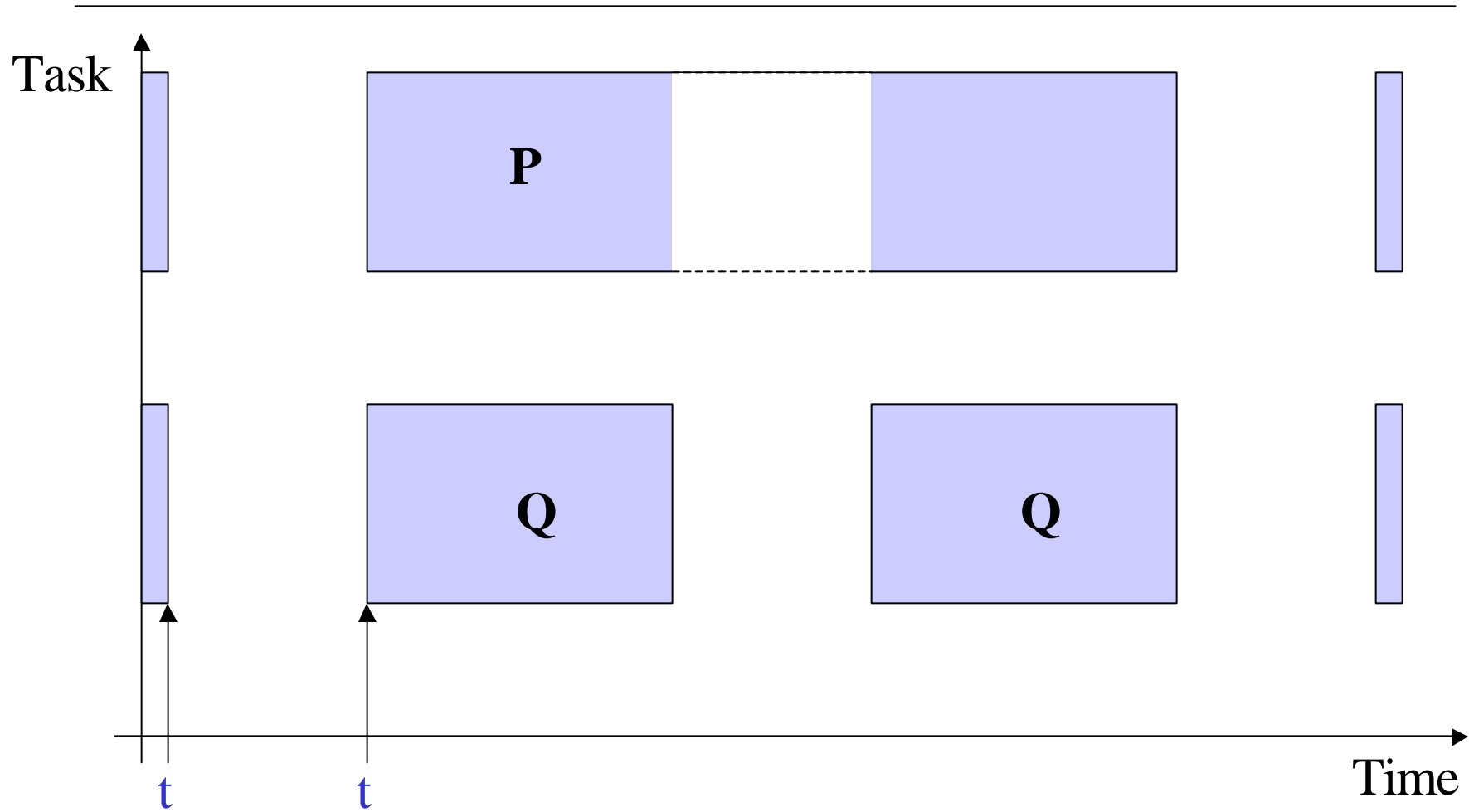
Semantics



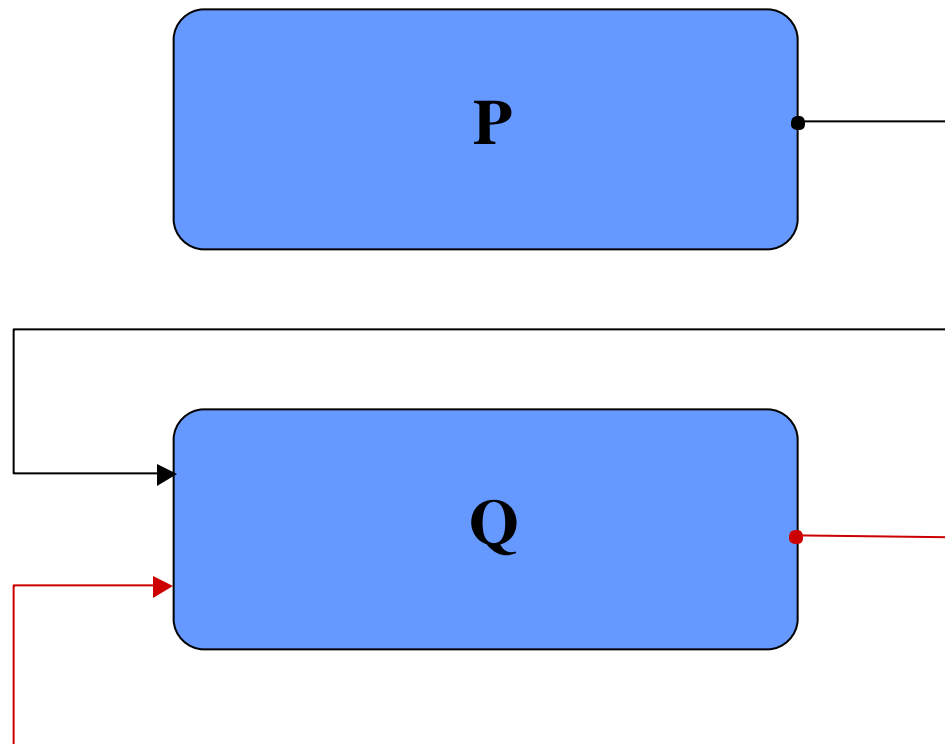
Semantics



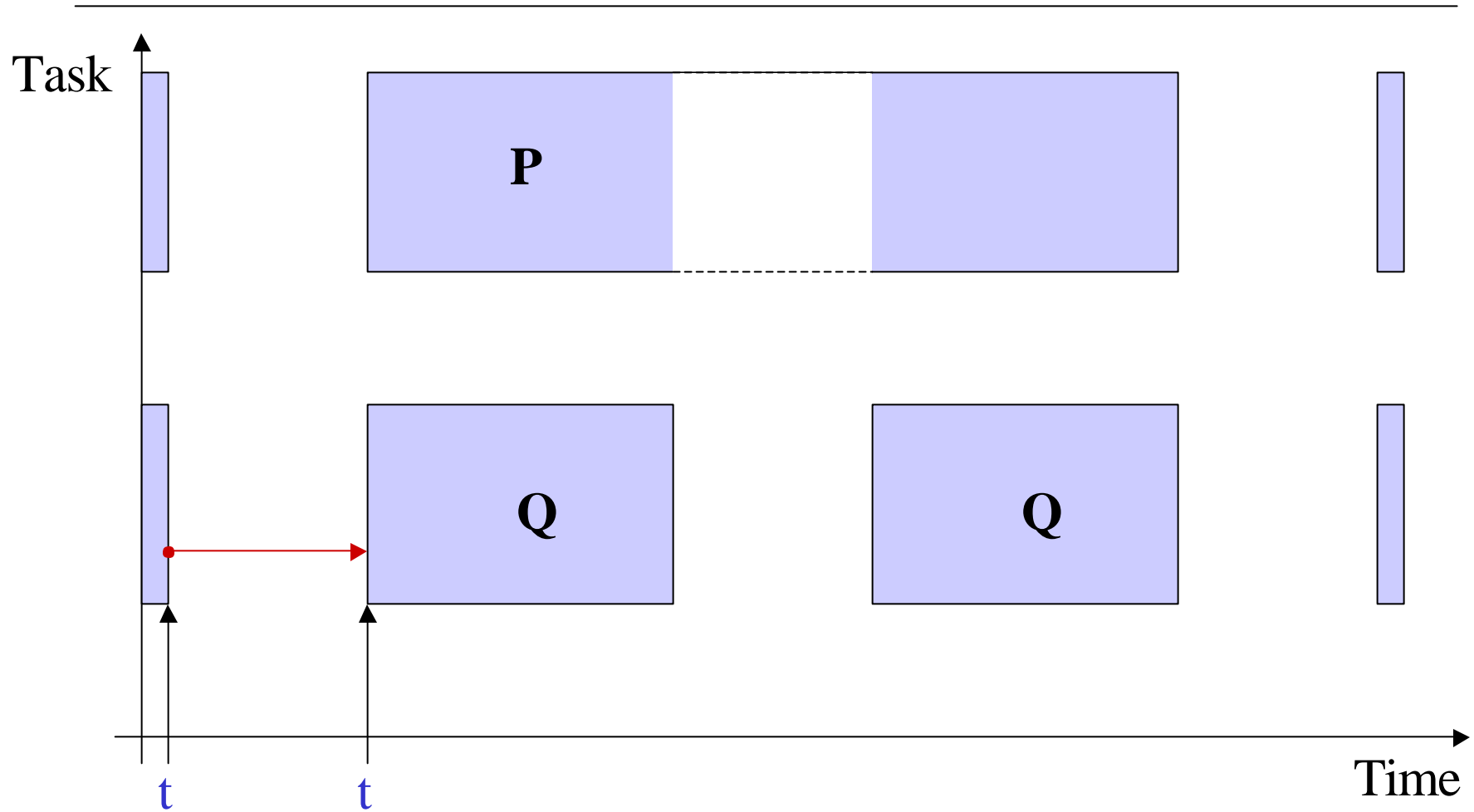
Semantics



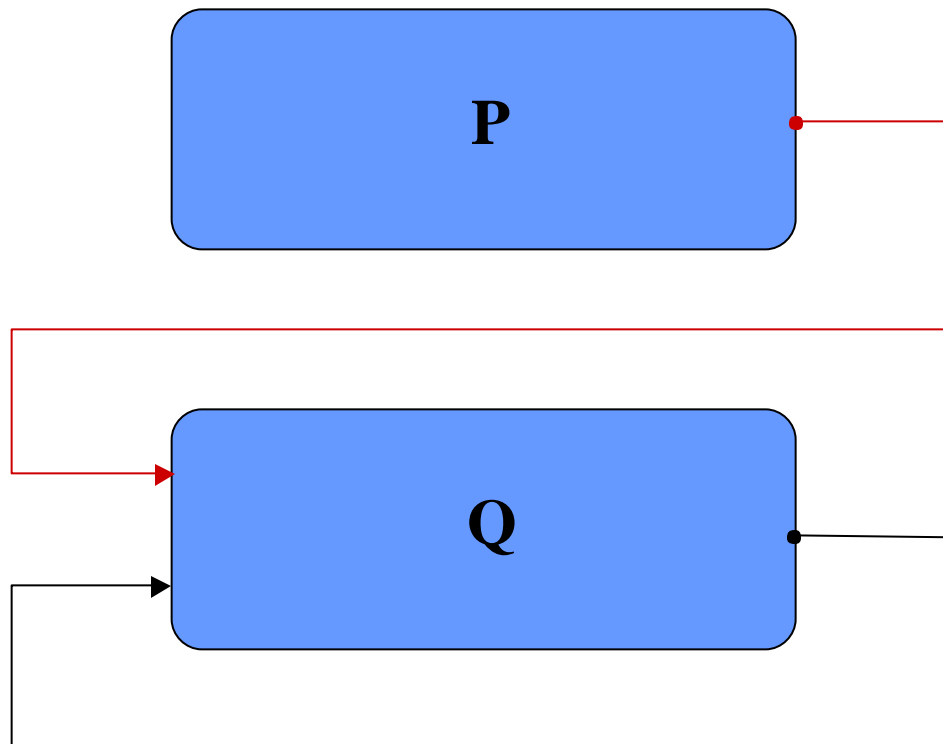
Connections



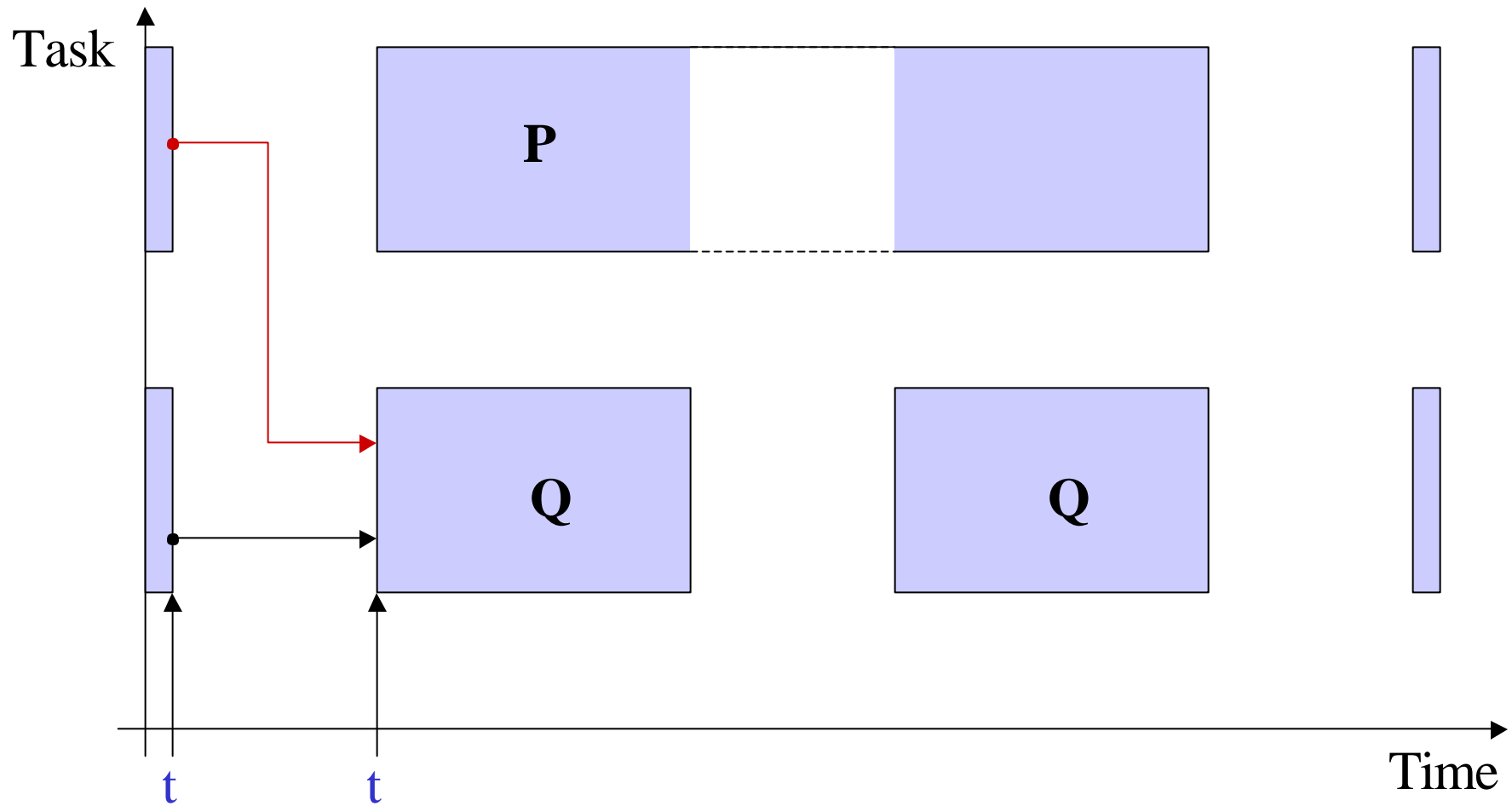
Semantics



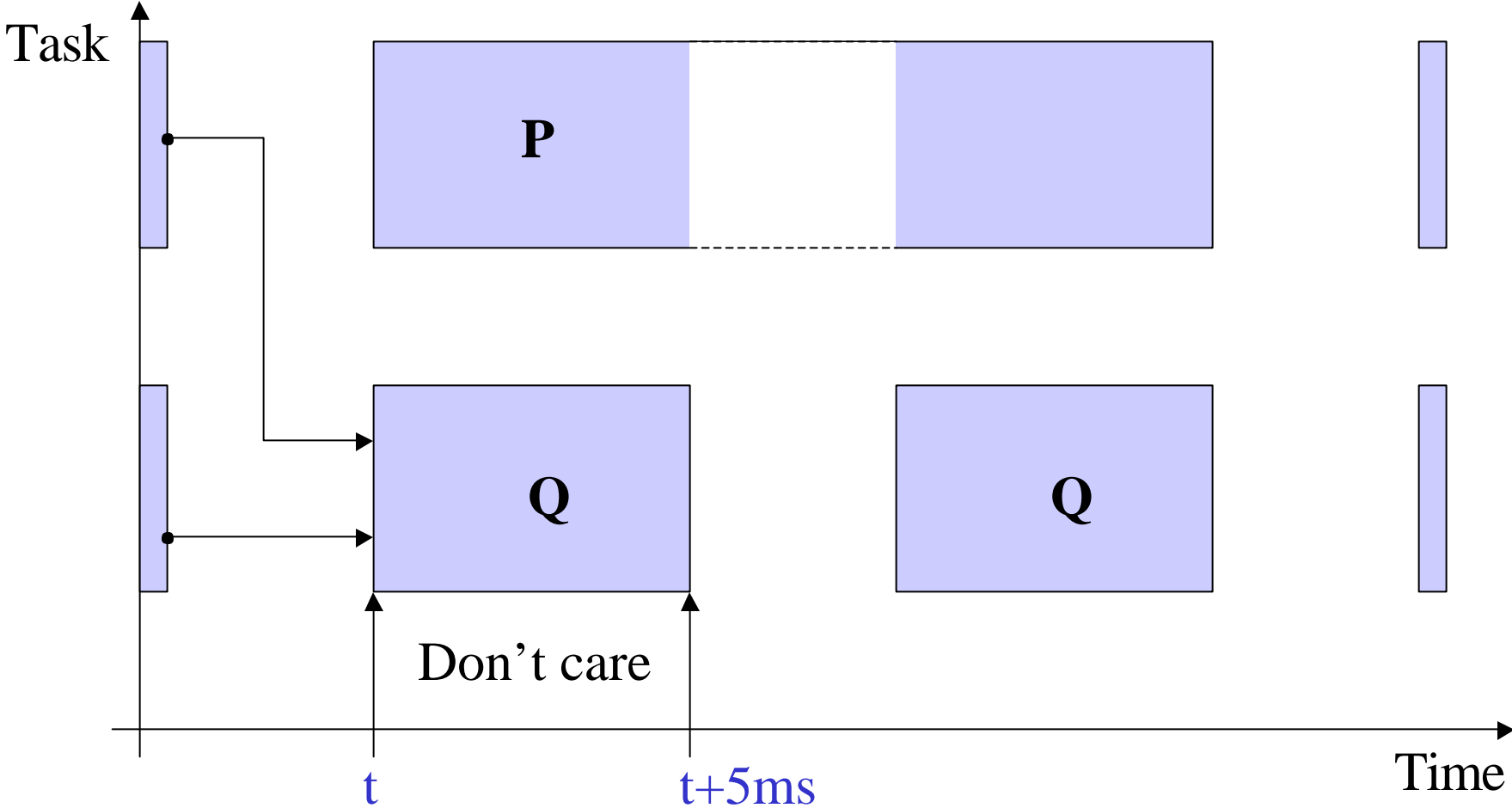
Connections



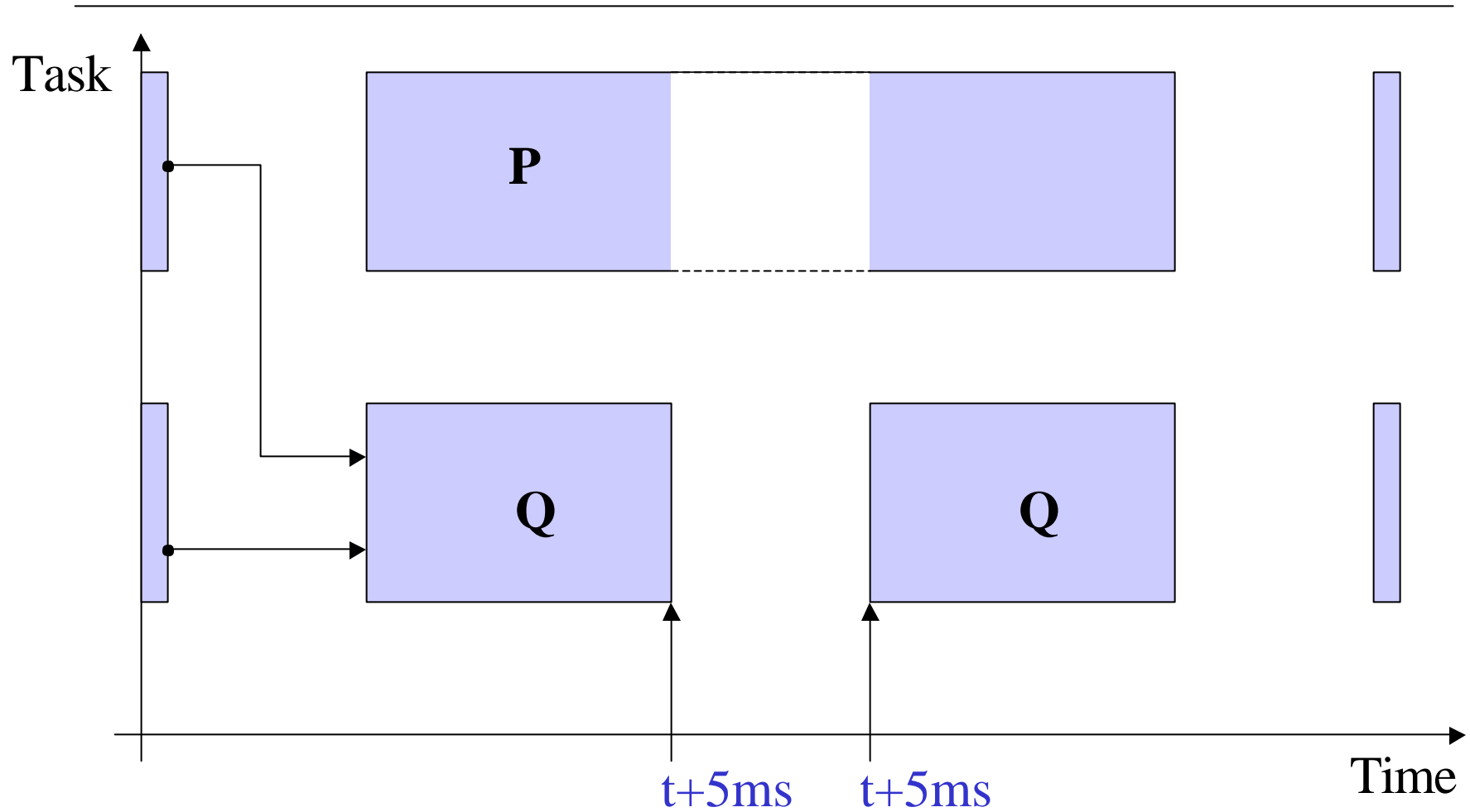
Semantics



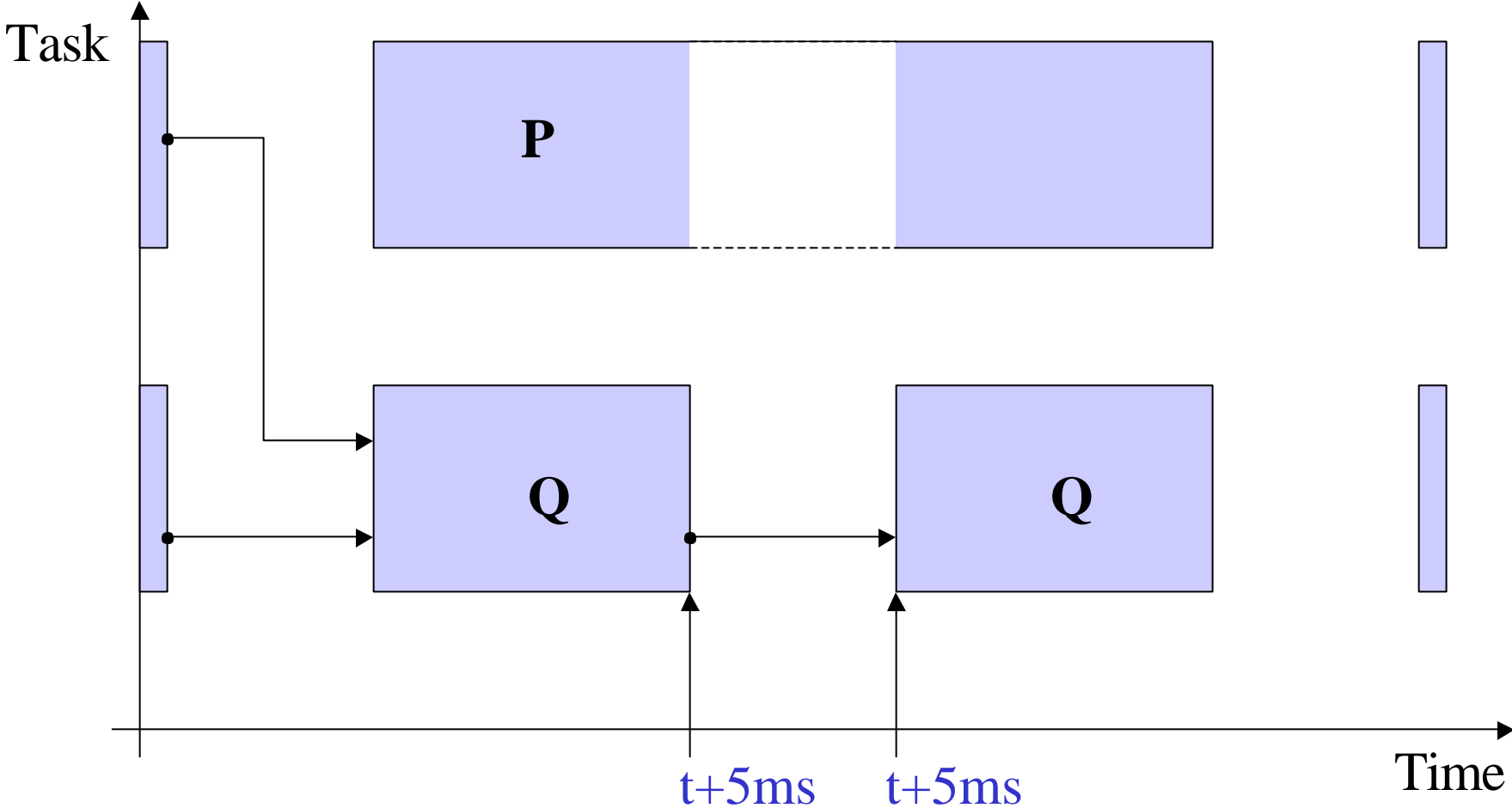
Semantics



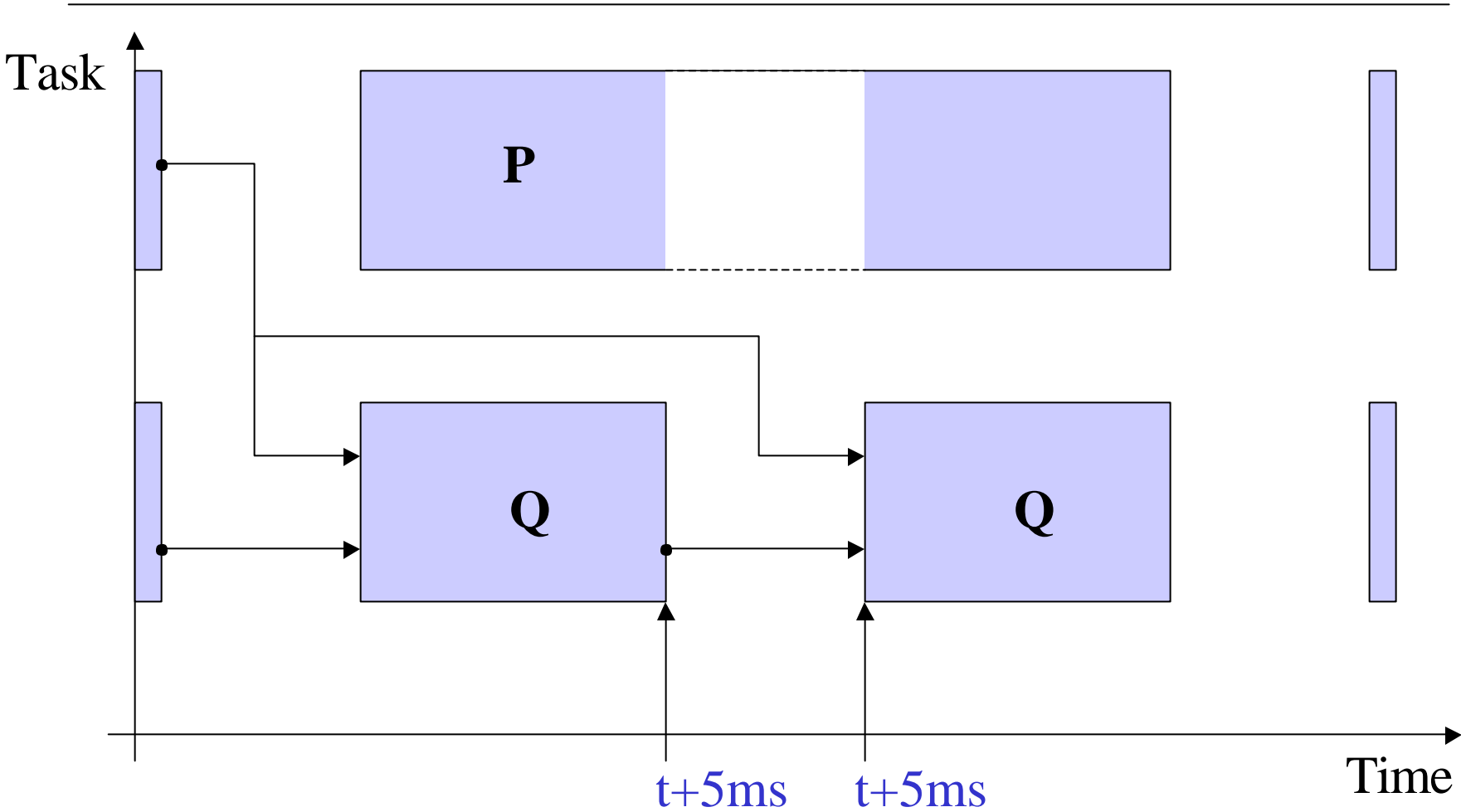
Semantics



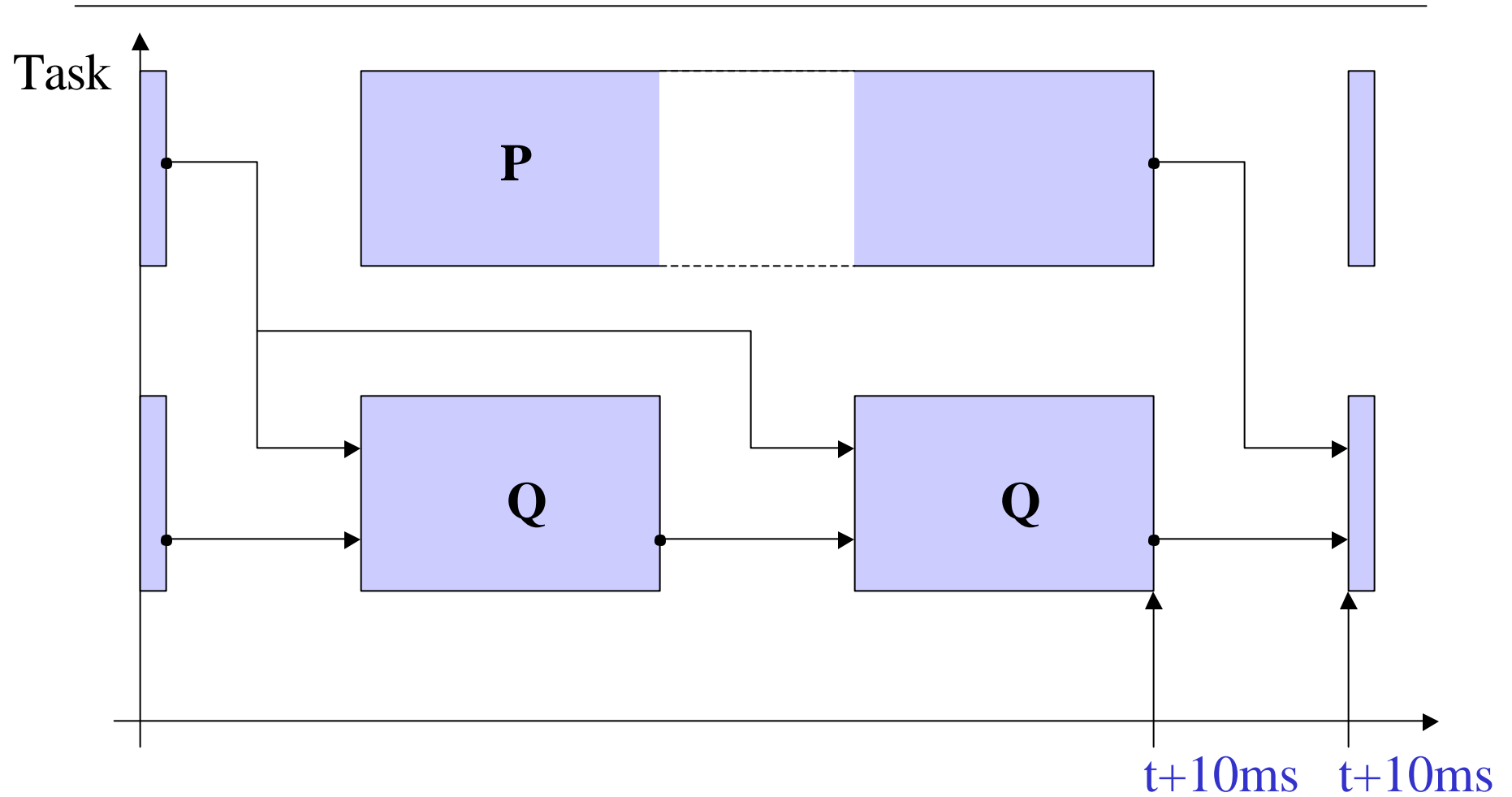
Semantics



Semantics



Semantics



Embedded System Development

High-Level
Programming

Our Approach

Functionality



Input/Output Ports

Timing



Don't Care Computation,
Zero-Delay Communication

Decomposition: Giotto Modes

Some Motivations:

- Multi-modal control
- Fault tolerance
- Events
- Resource sharing
- Uncertain environments

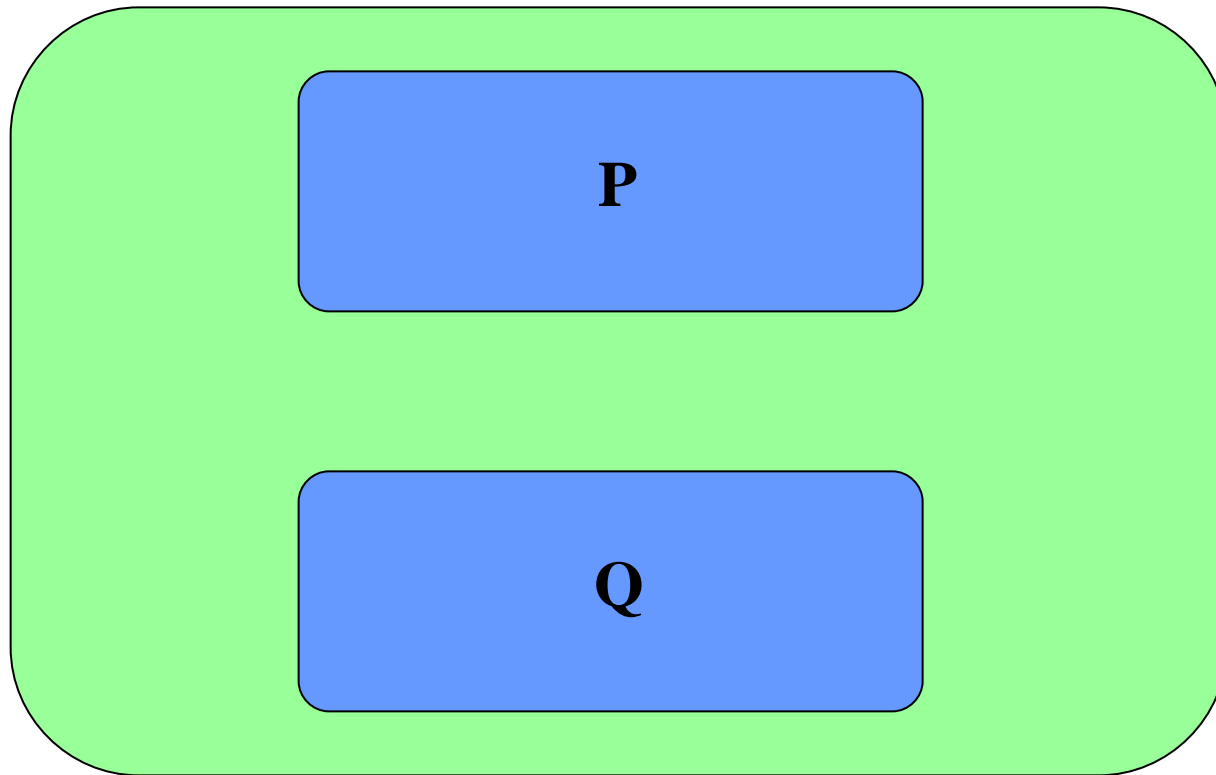
Modes

- A mode is a parameterized **set** of tasks
- A Giotto program consists of a **set** of modes and mode switches
- A Giotto system is in a **single** mode at the same time

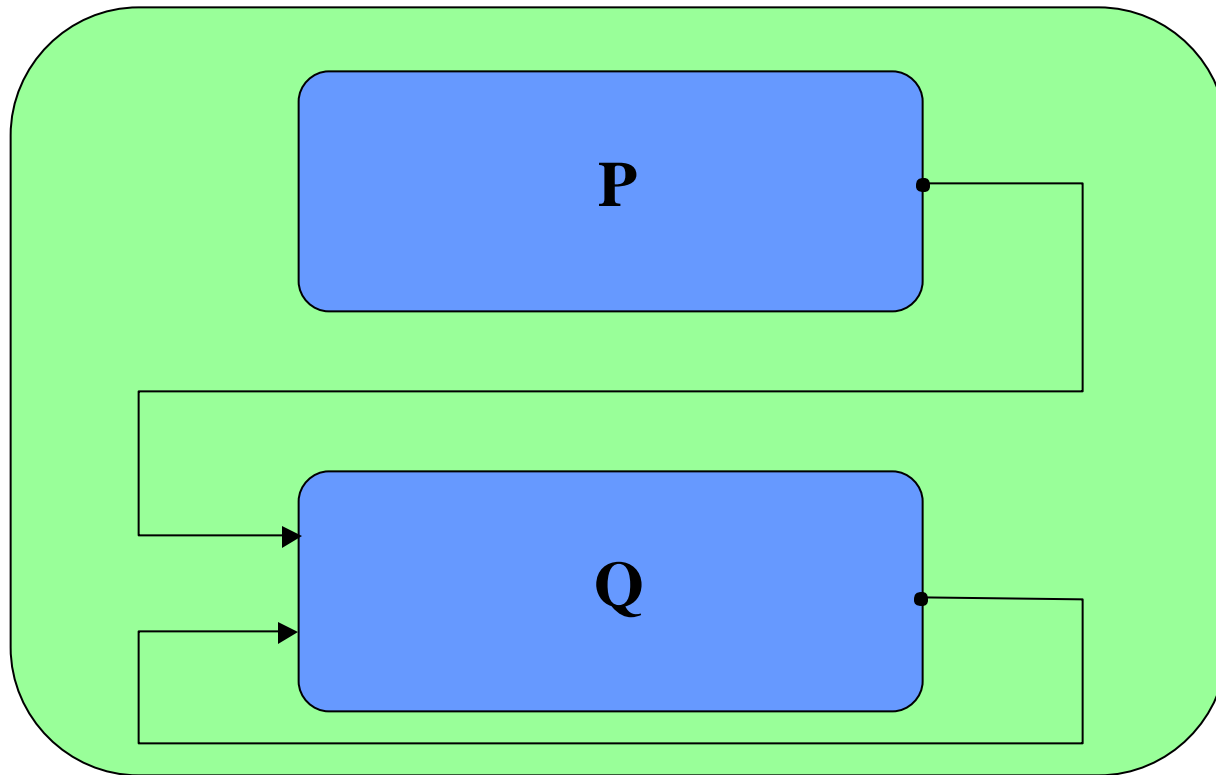
A Mode



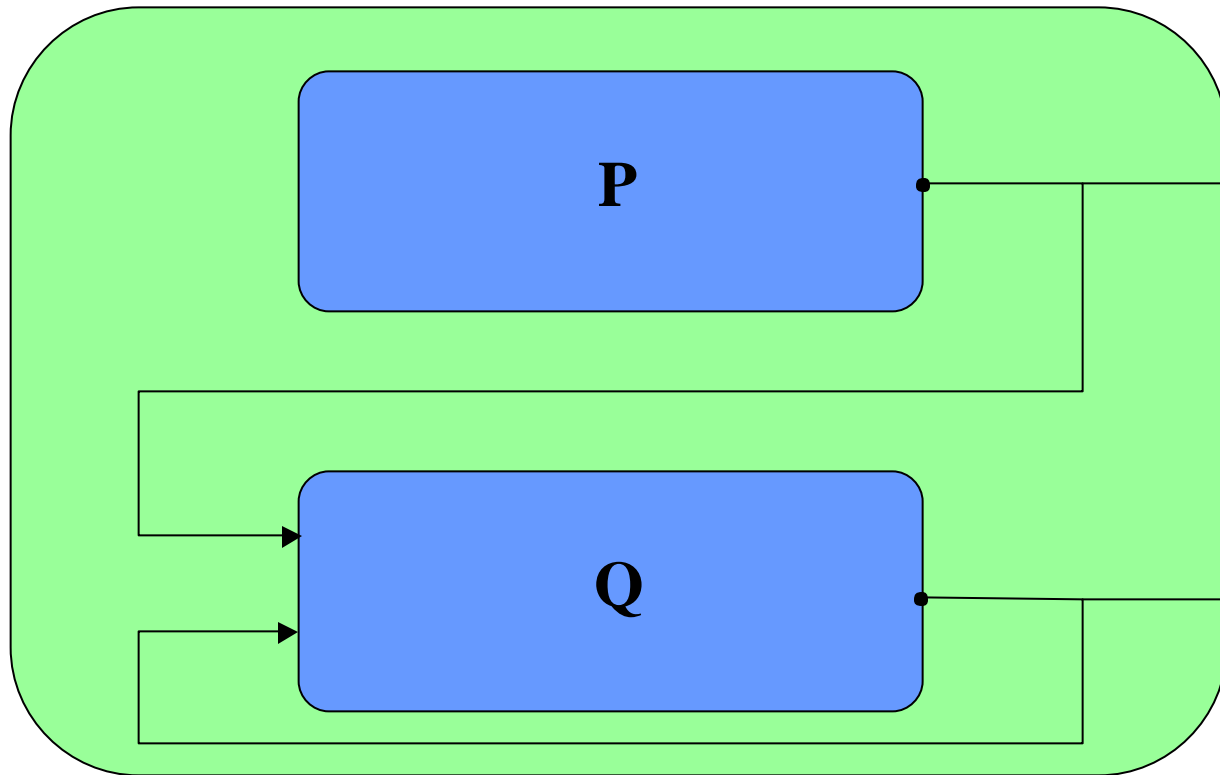
Abstract Syntax of a Mode



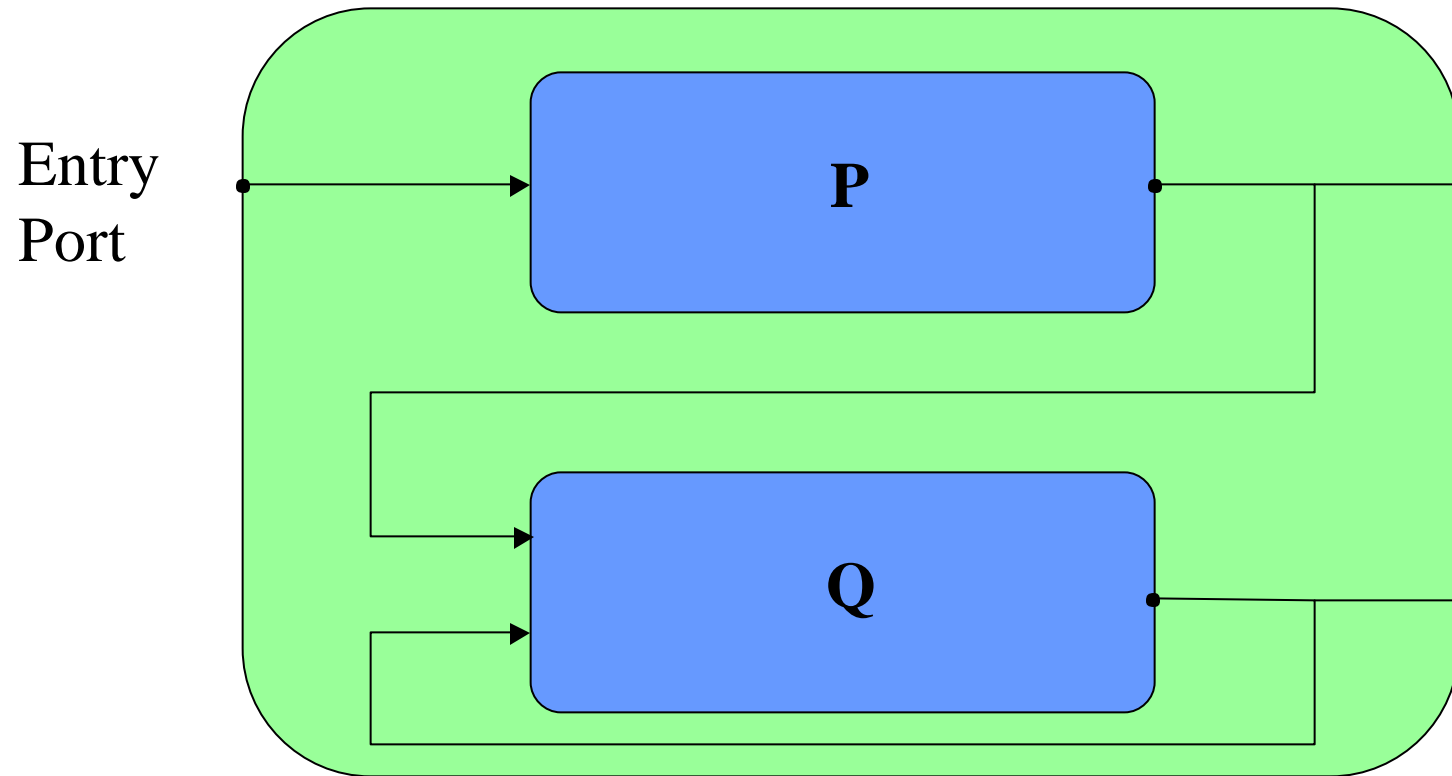
Abstract Syntax of a Mode



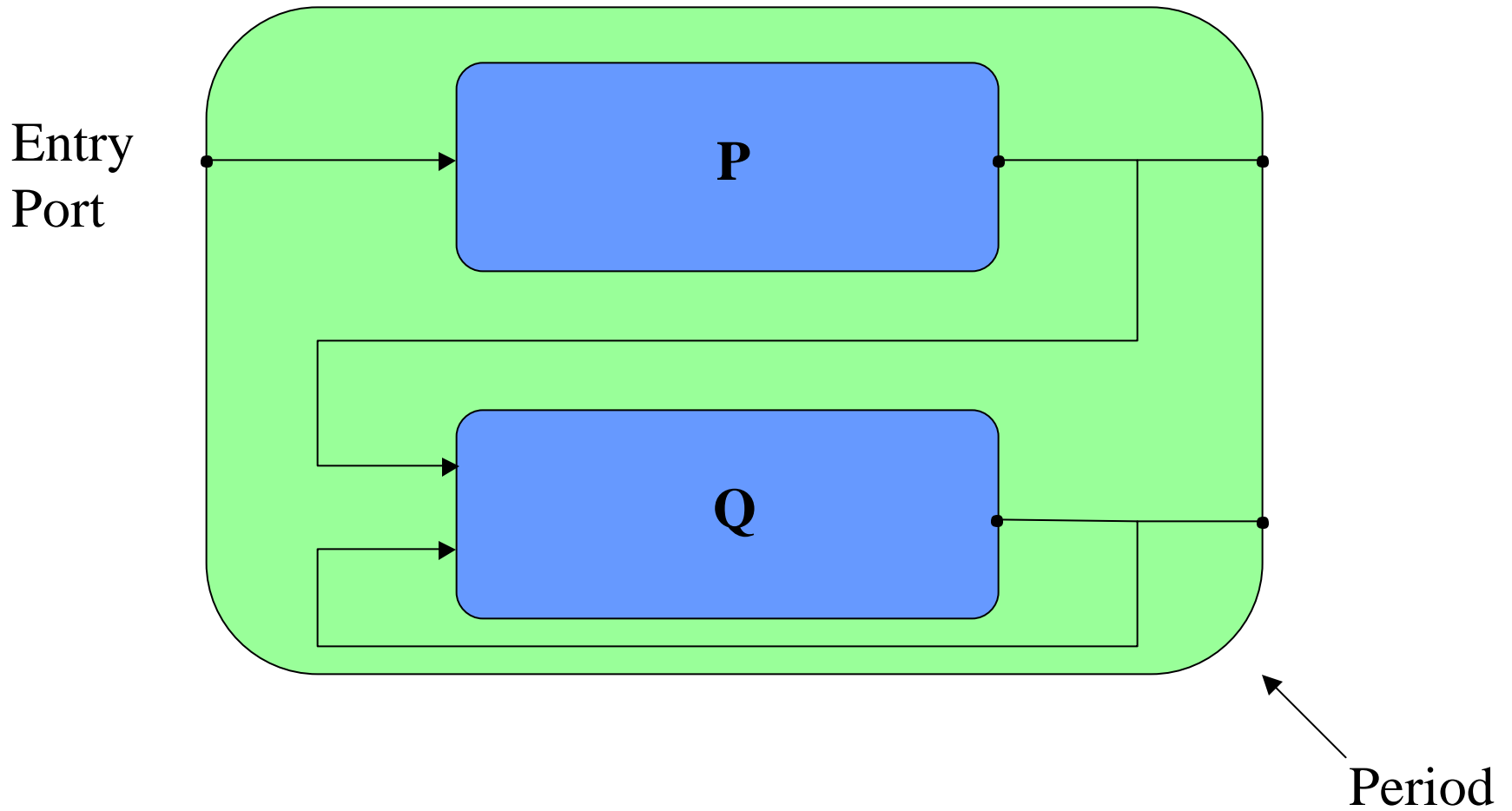
Abstract Syntax of a Mode



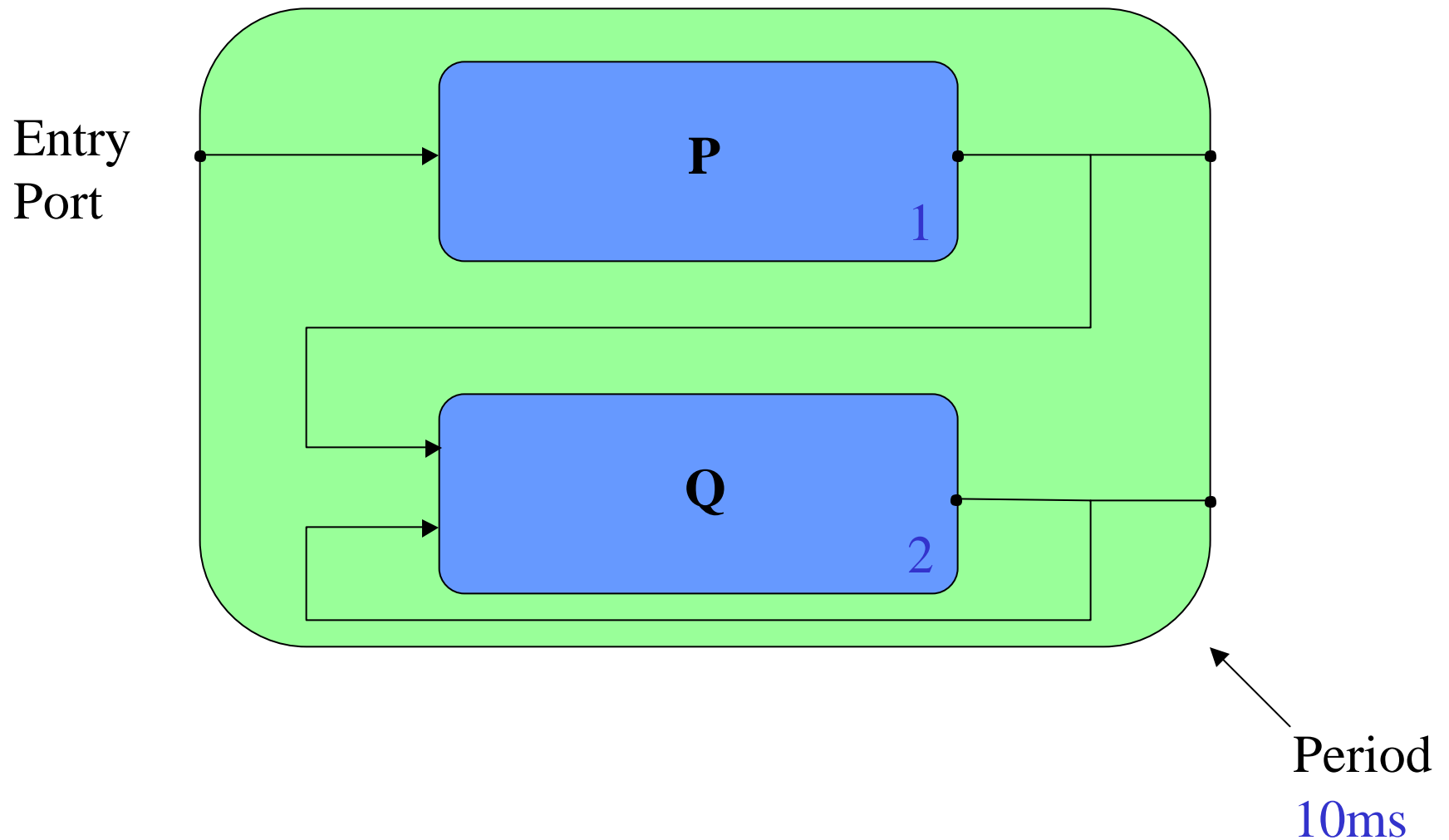
Abstract Syntax of a Mode



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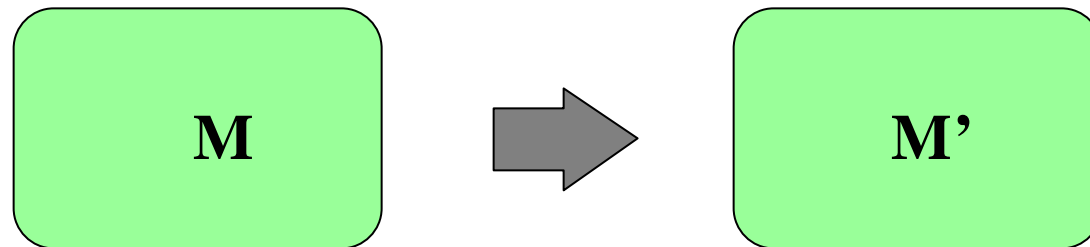
Semantics of a Mode



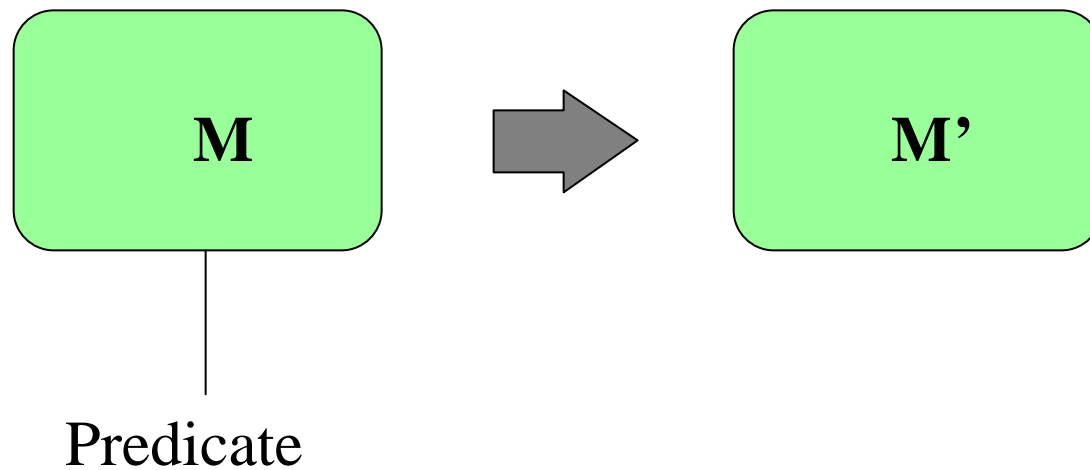
Concrete Syntax

```
mode m ( ) period 10 ms
{
    taskfreq 1 do int x = P ( ) ;
    taskfreq 2 do int y = Q ( x, y ) ;
}
```

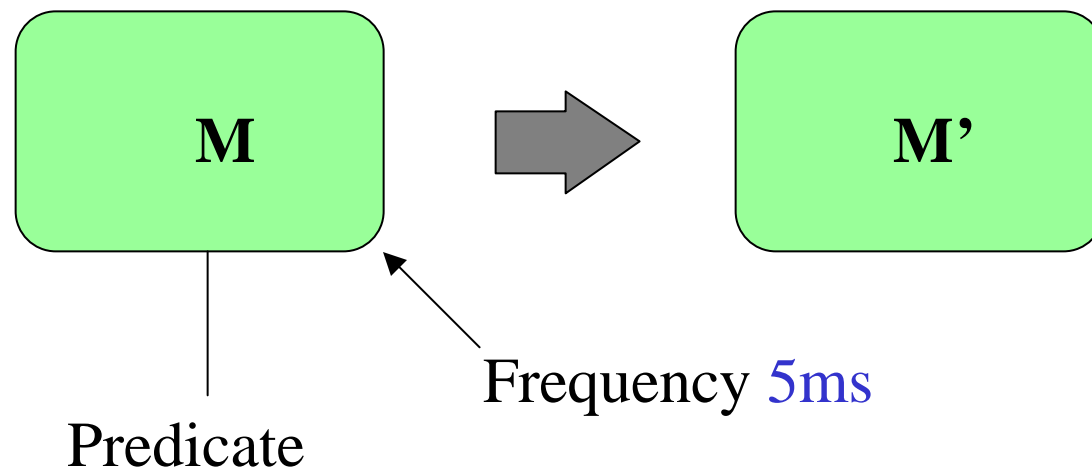
A Mode Switch



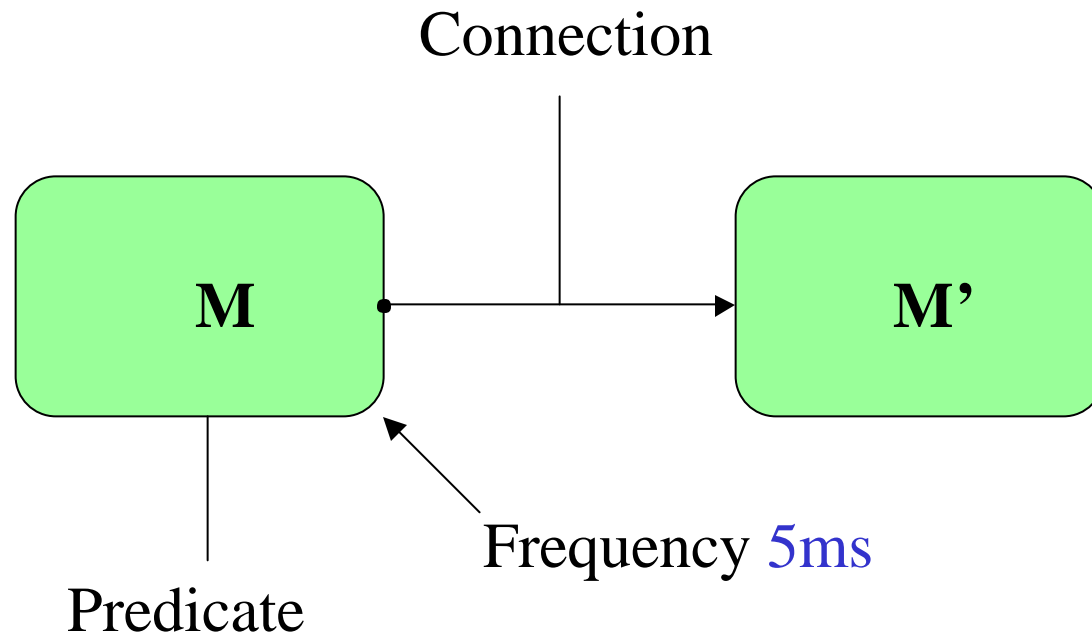
Abstract Syntax of a Mode Switch



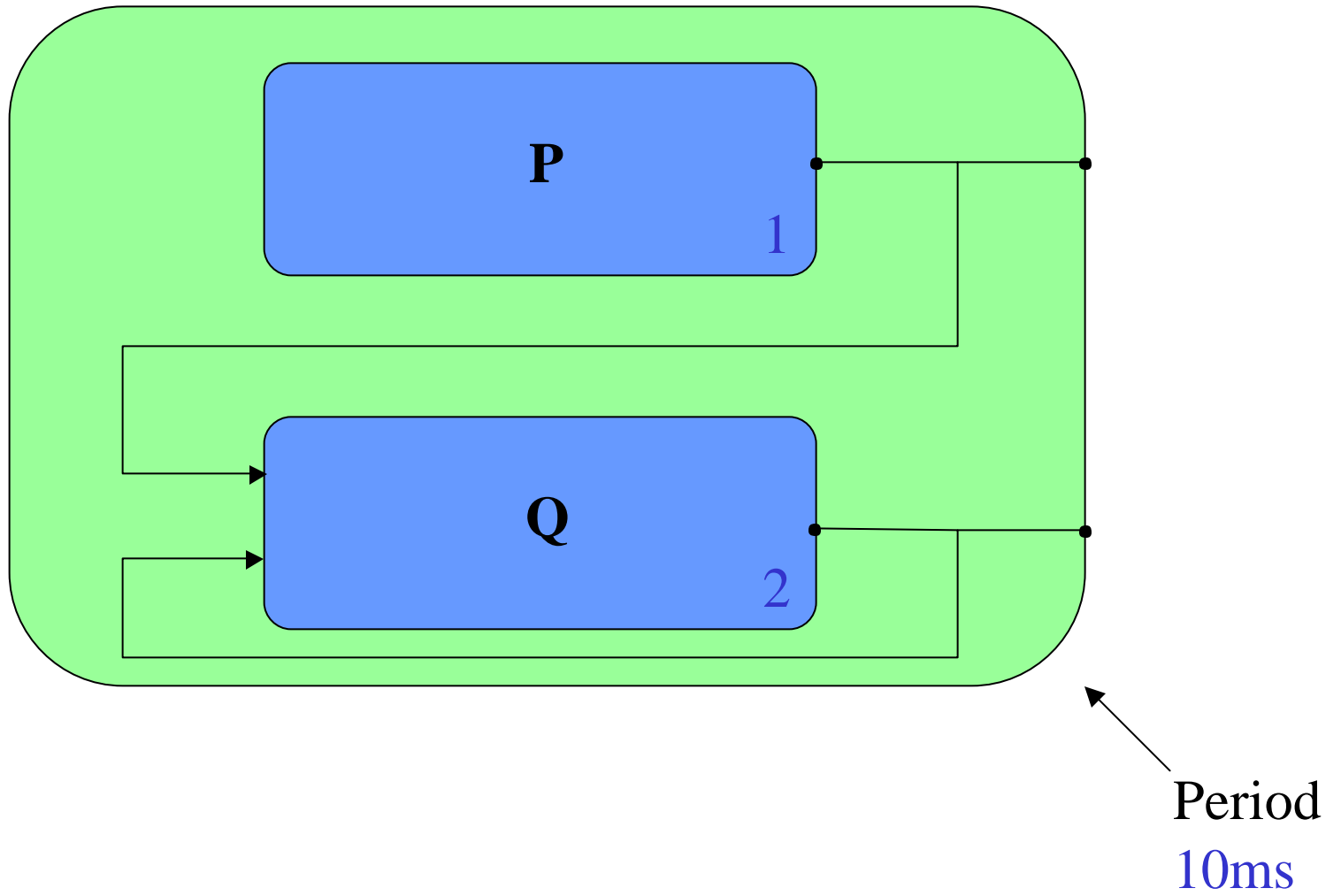
Abstract Syntax of a Mode Switch



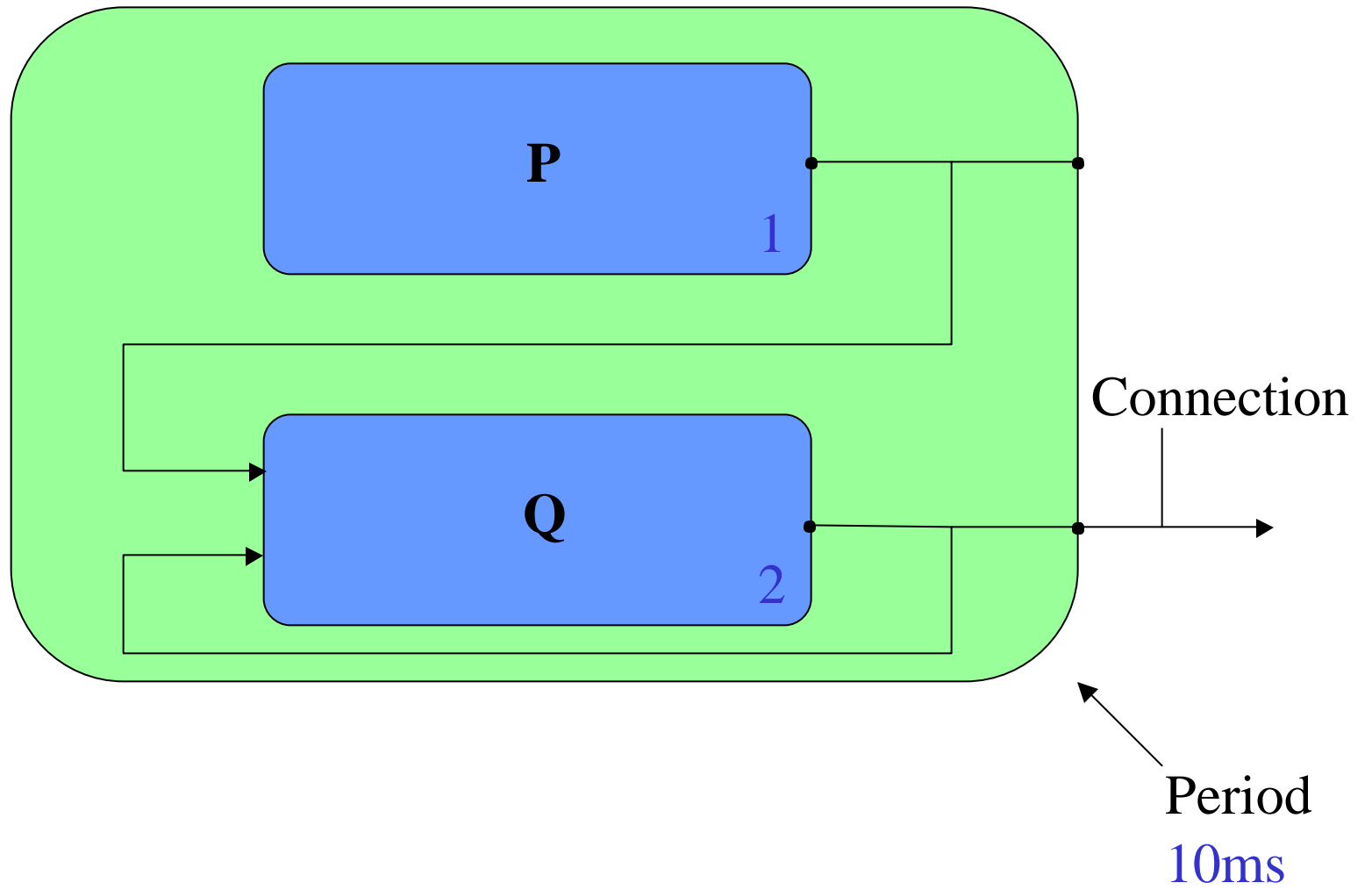
Abstract Syntax of a Mode Switch



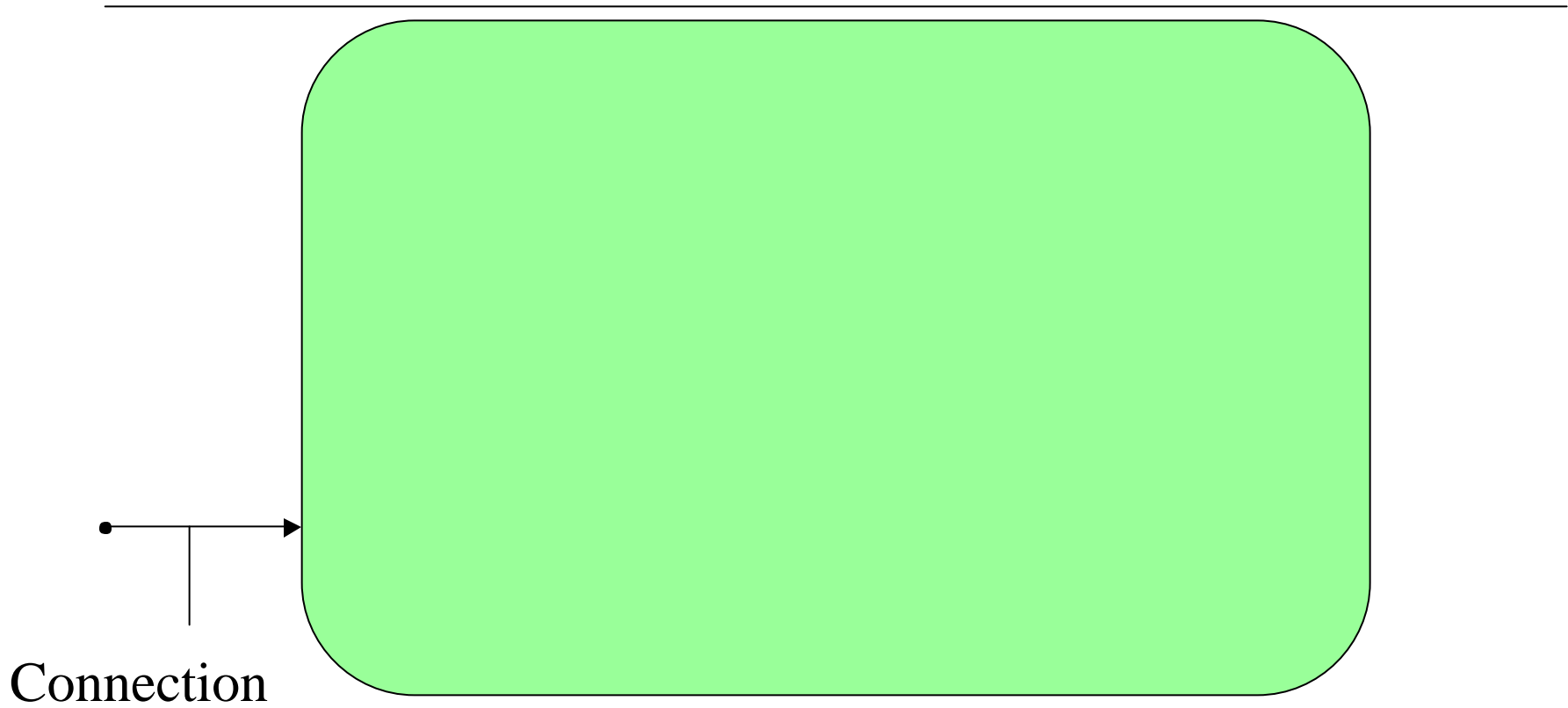
Mode M



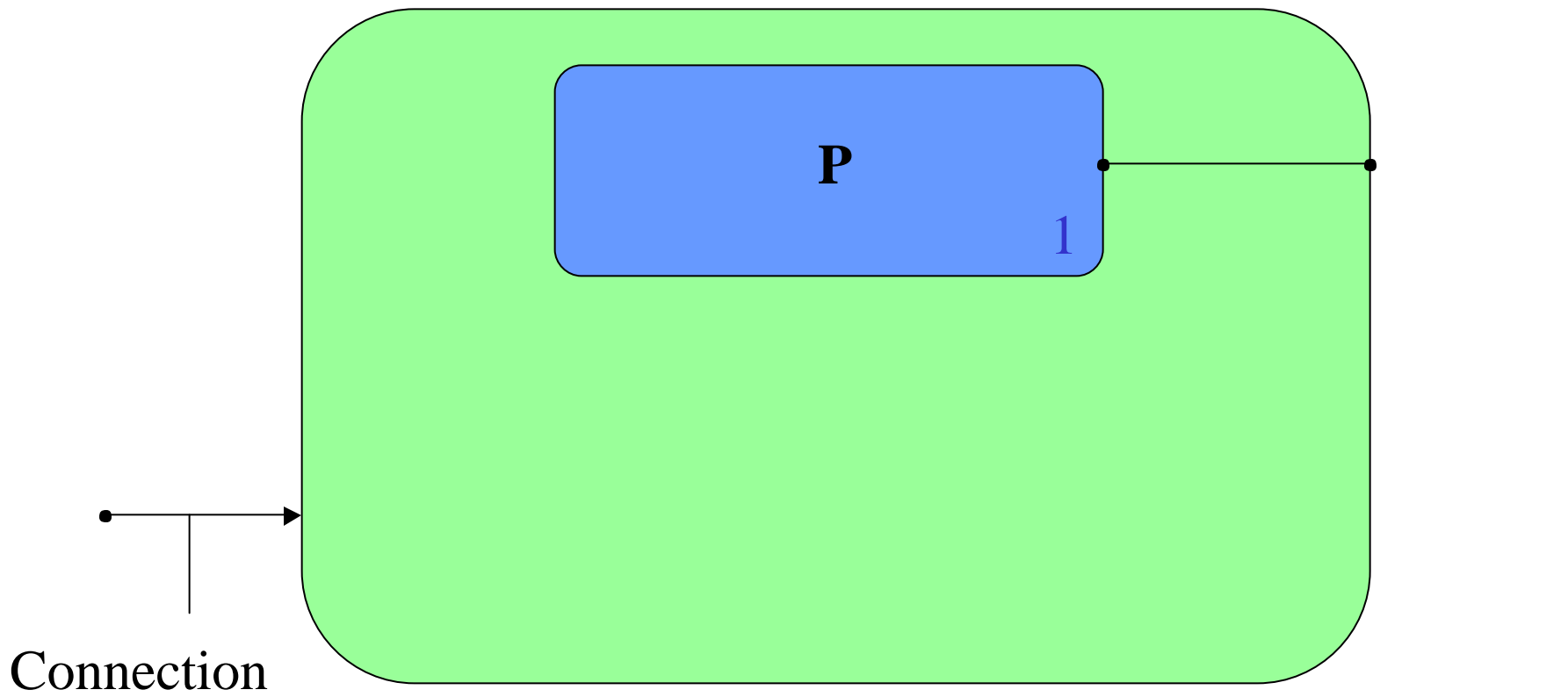
Mode M



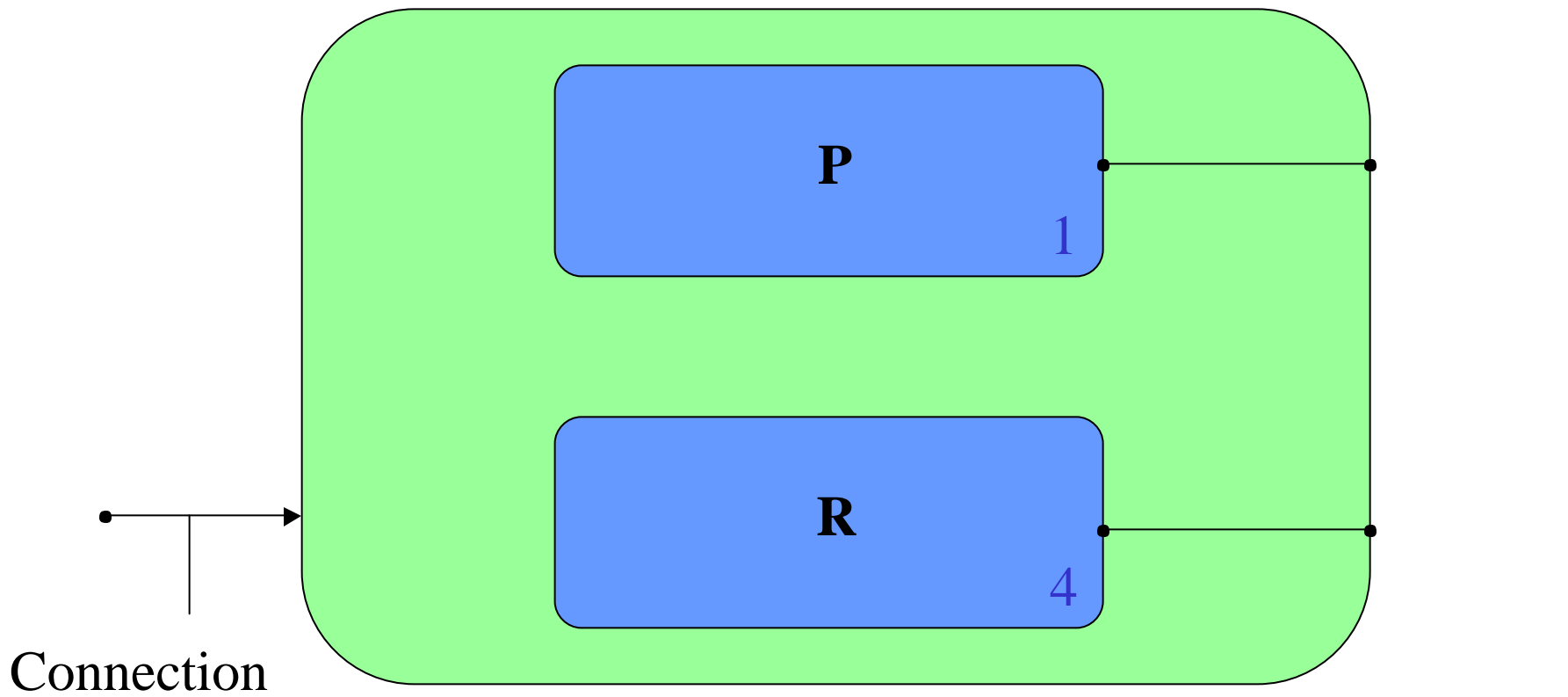
Mode M'



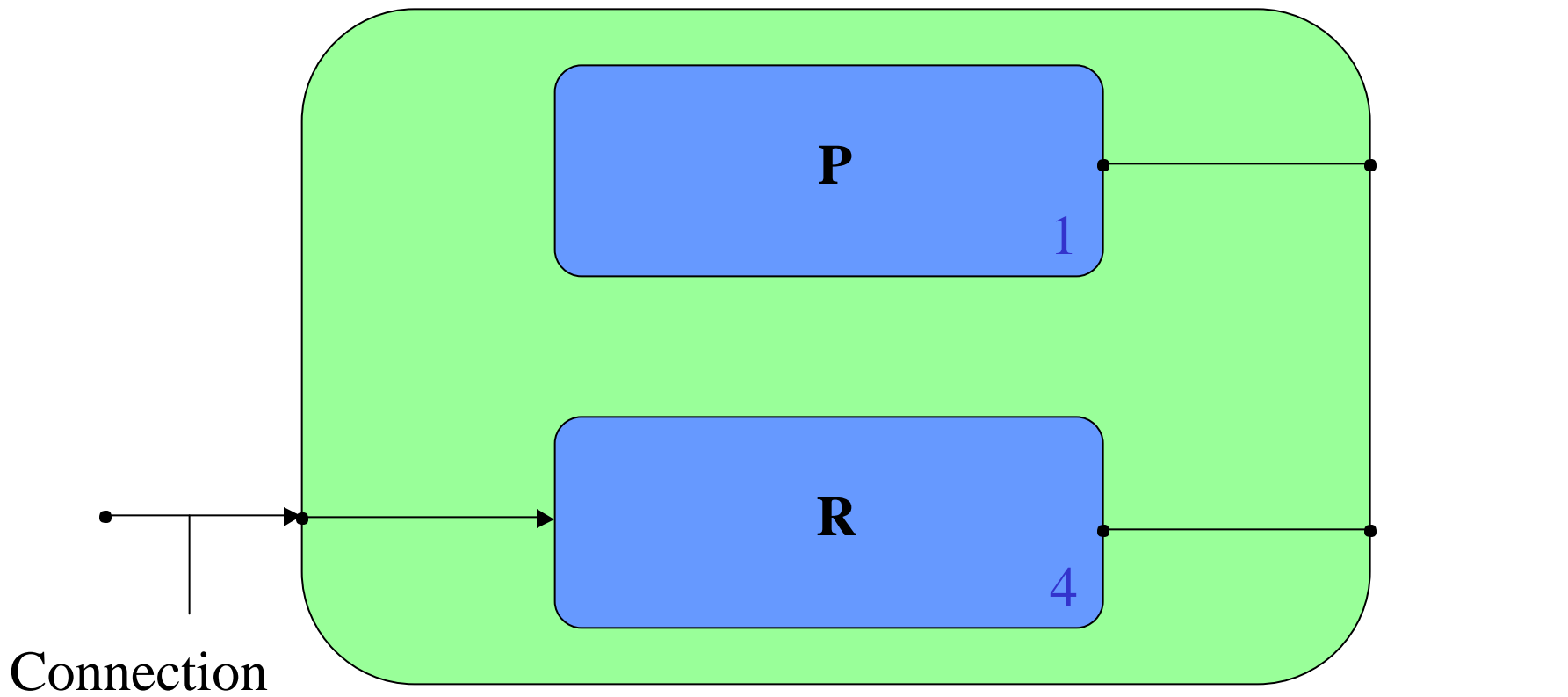
Mode M'



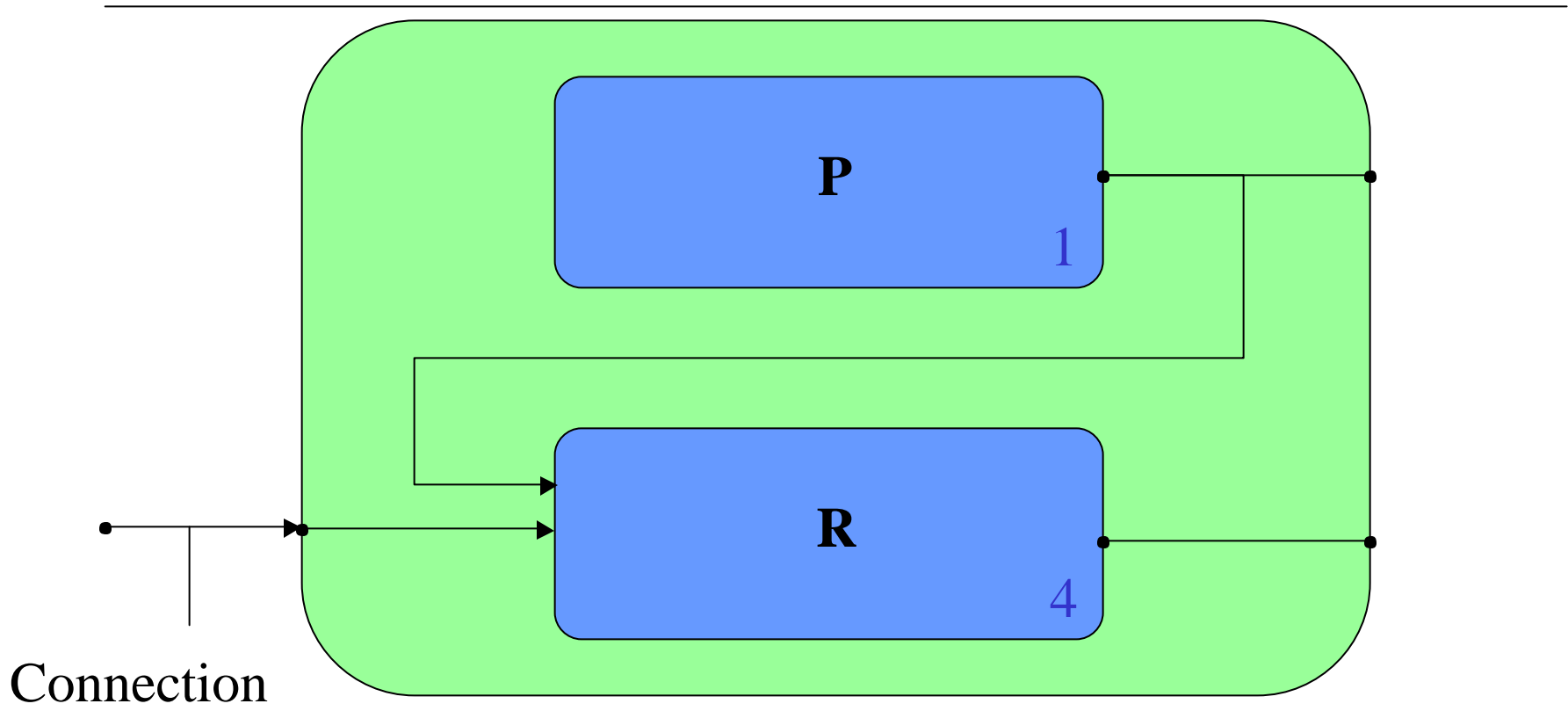
Mode M'



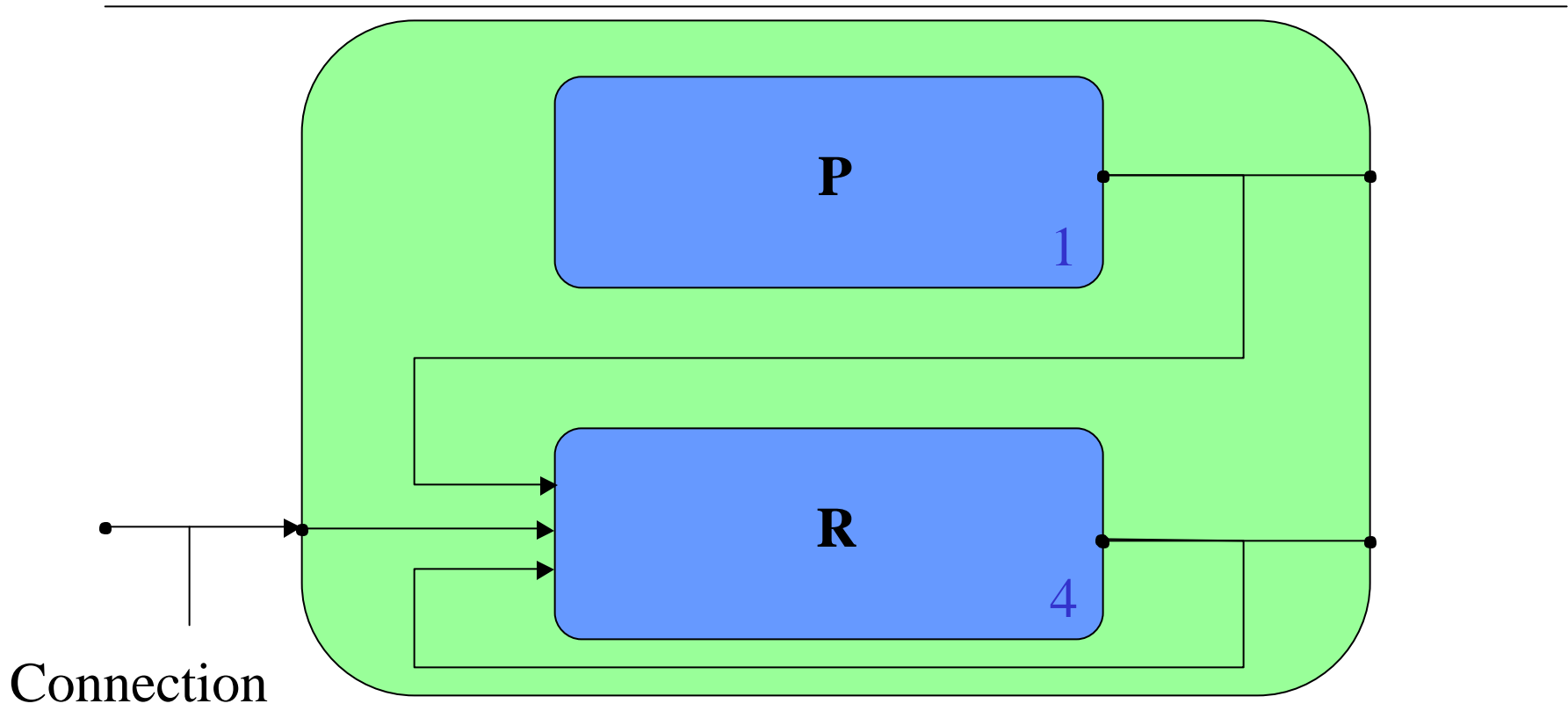
Mode M'



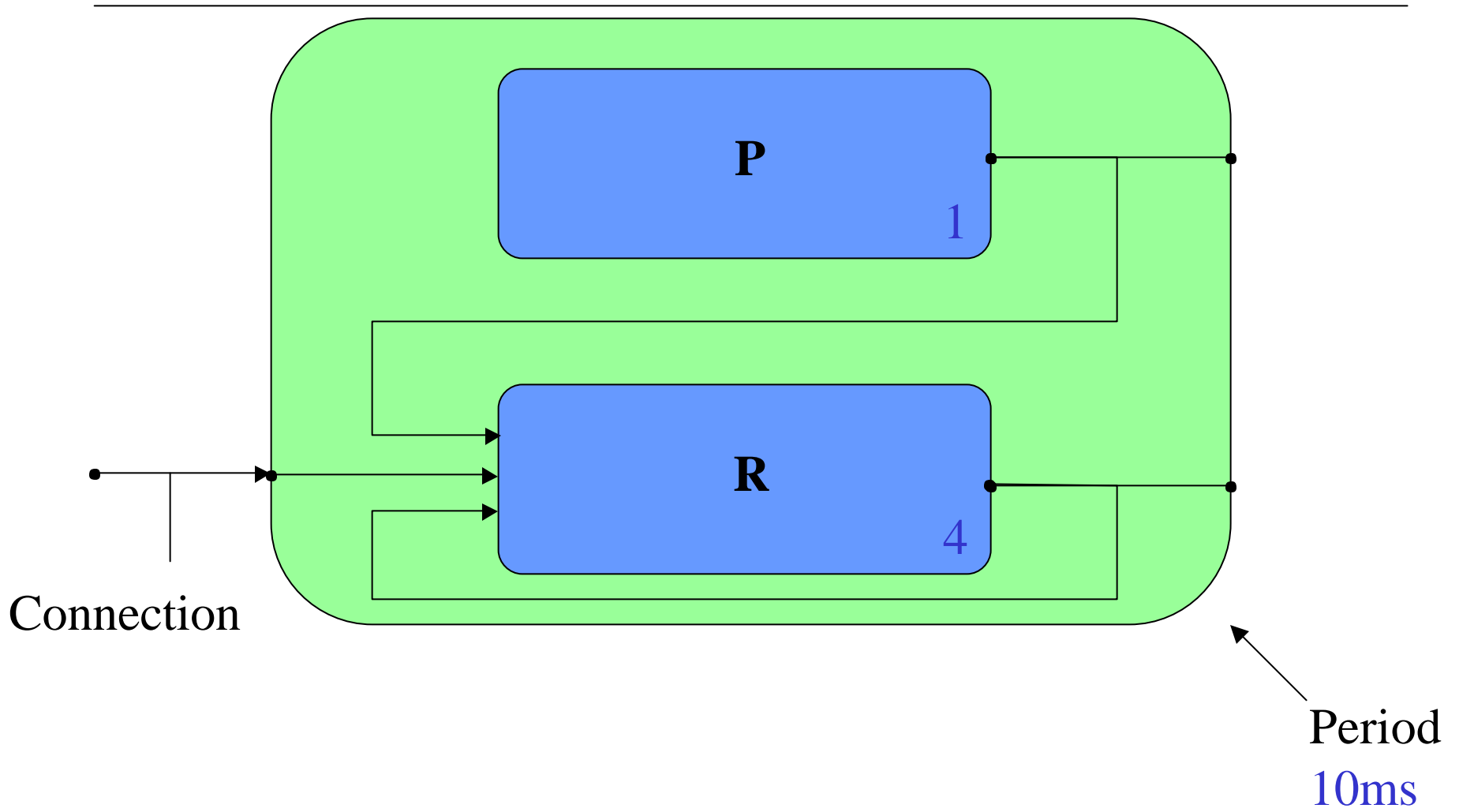
Mode M'



Mode M'



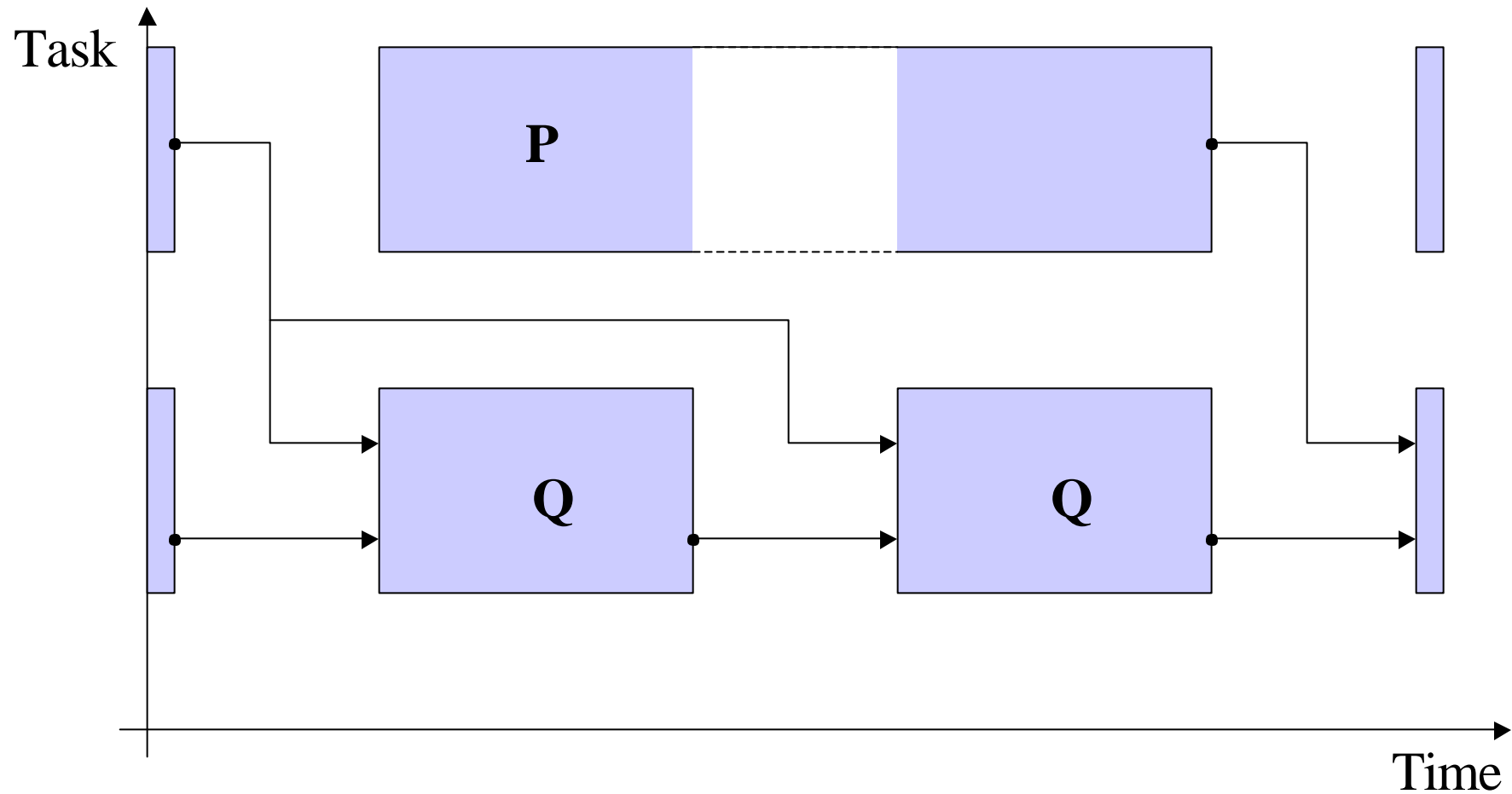
Mode M'



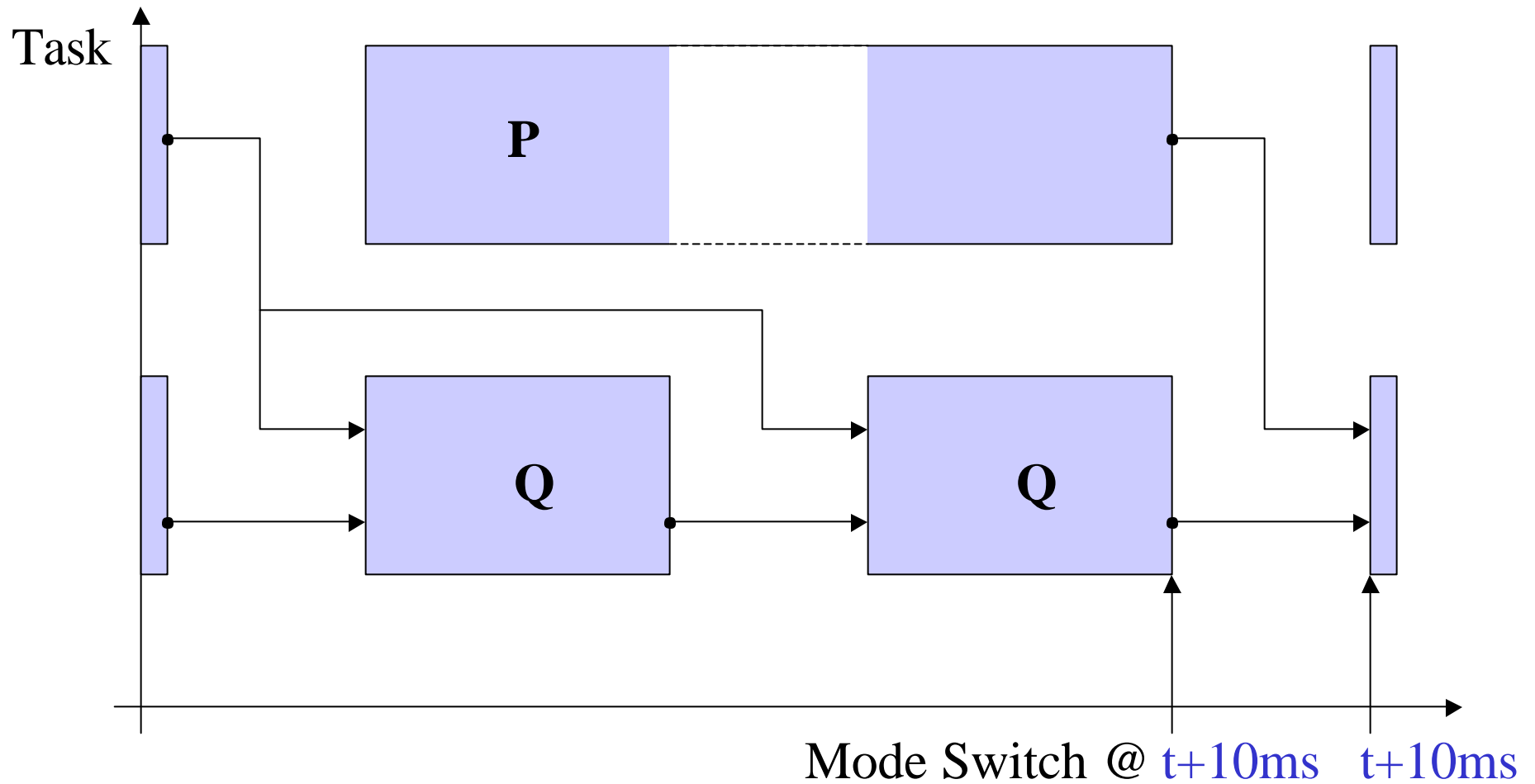
Concrete Syntax

```
start m ( ) {  
    mode m ( ) period 10 ms entryfreq 1 {  
        taskfreq 1 do int x = P ( ) ;  
        taskfreq 2 do int y = Q ( x, y ) ;  
  
        exitfreq 2 if y = 5 then m' ( y ) ;  
    }  
    mode m' ( int z ) period 10 ms entryfreq 2 {  
        taskfreq 1 do int x = P ( ) ;  
        taskfreq 4 do int u = R ( x, z ) ;  
    }  
}
```

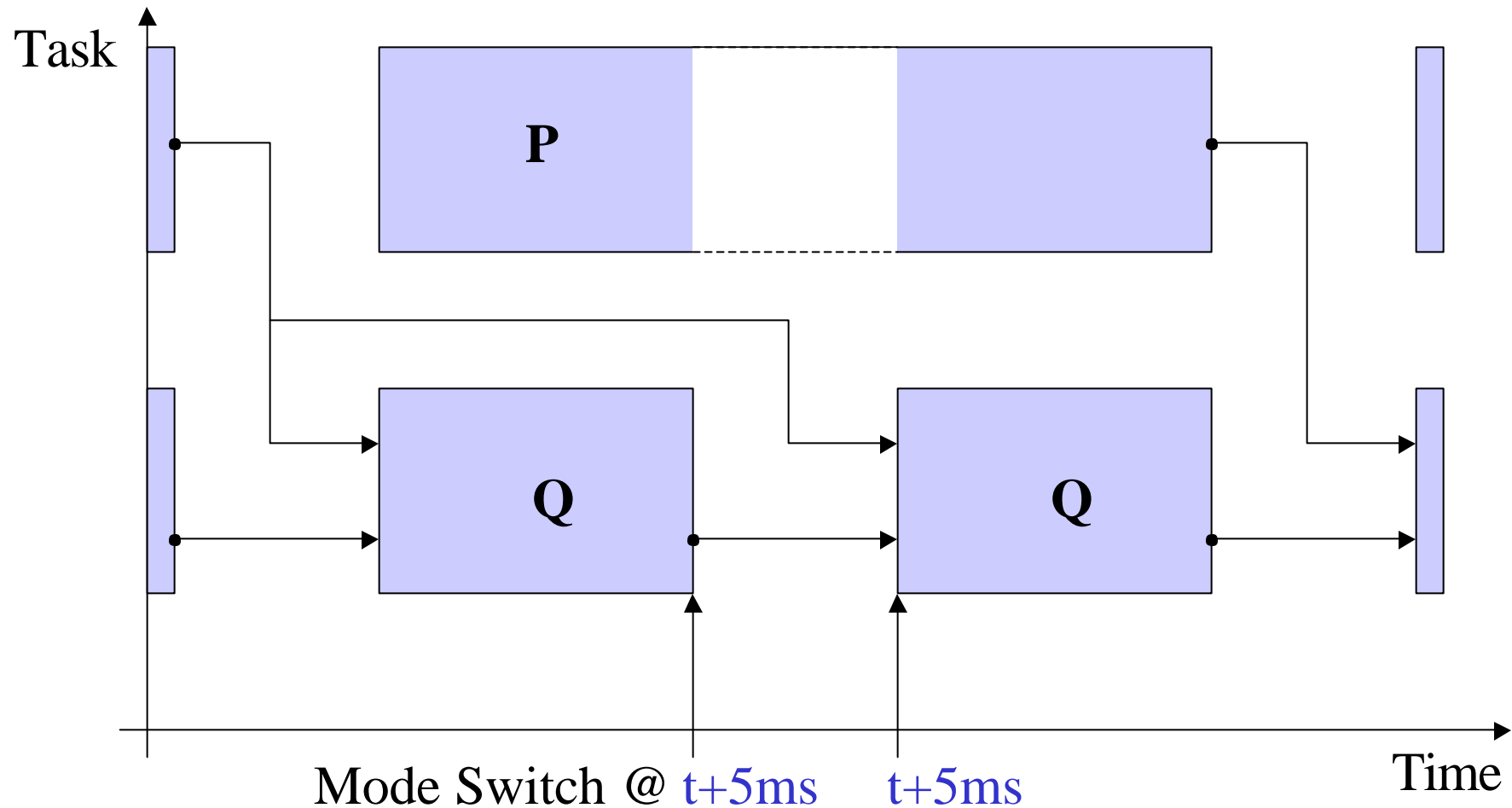
Semantics of a Mode Switch



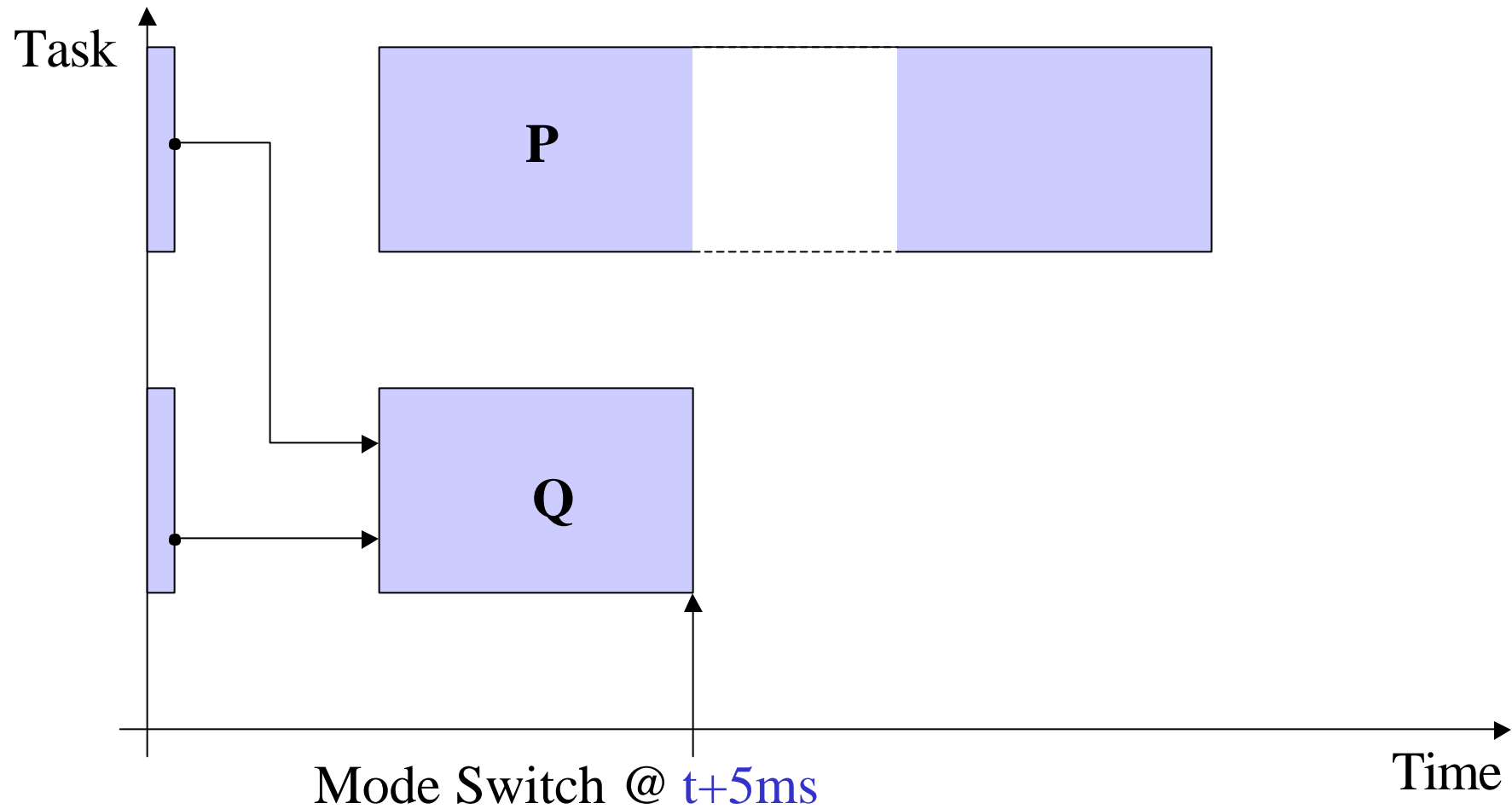
Semantics of a Mode Switch



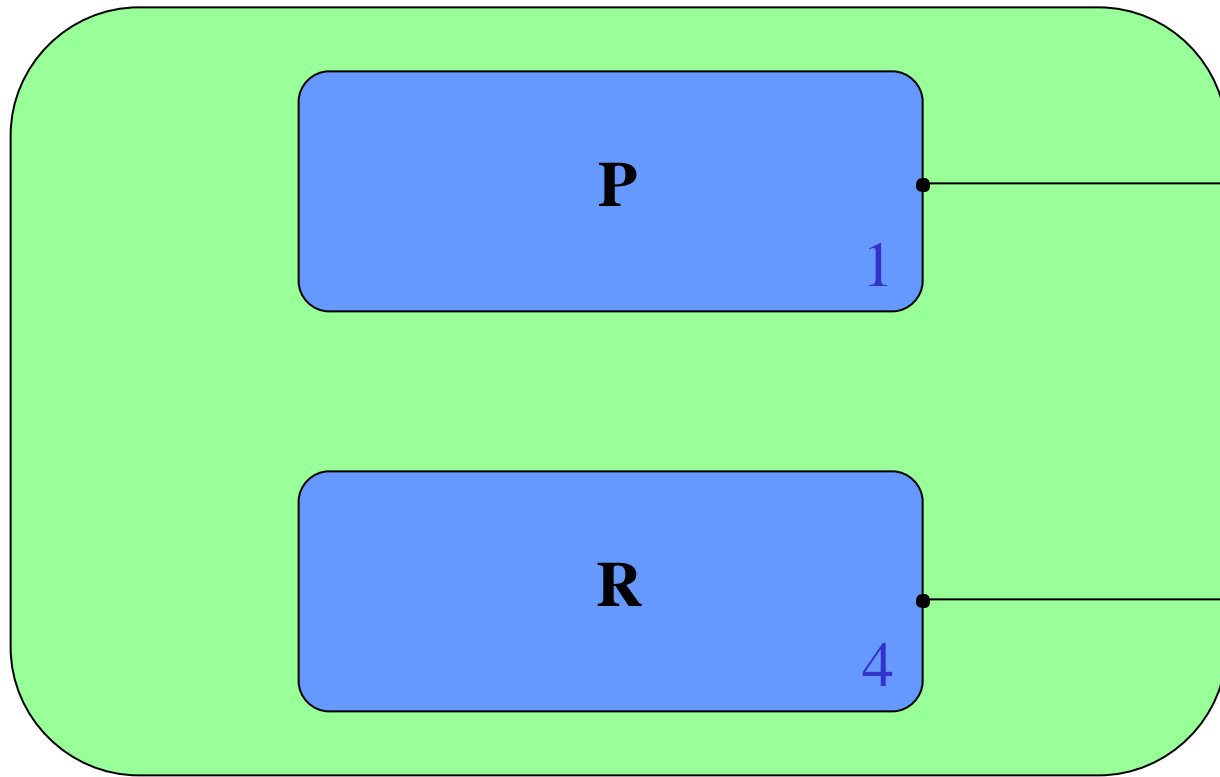
Semantics of a Mode Switch



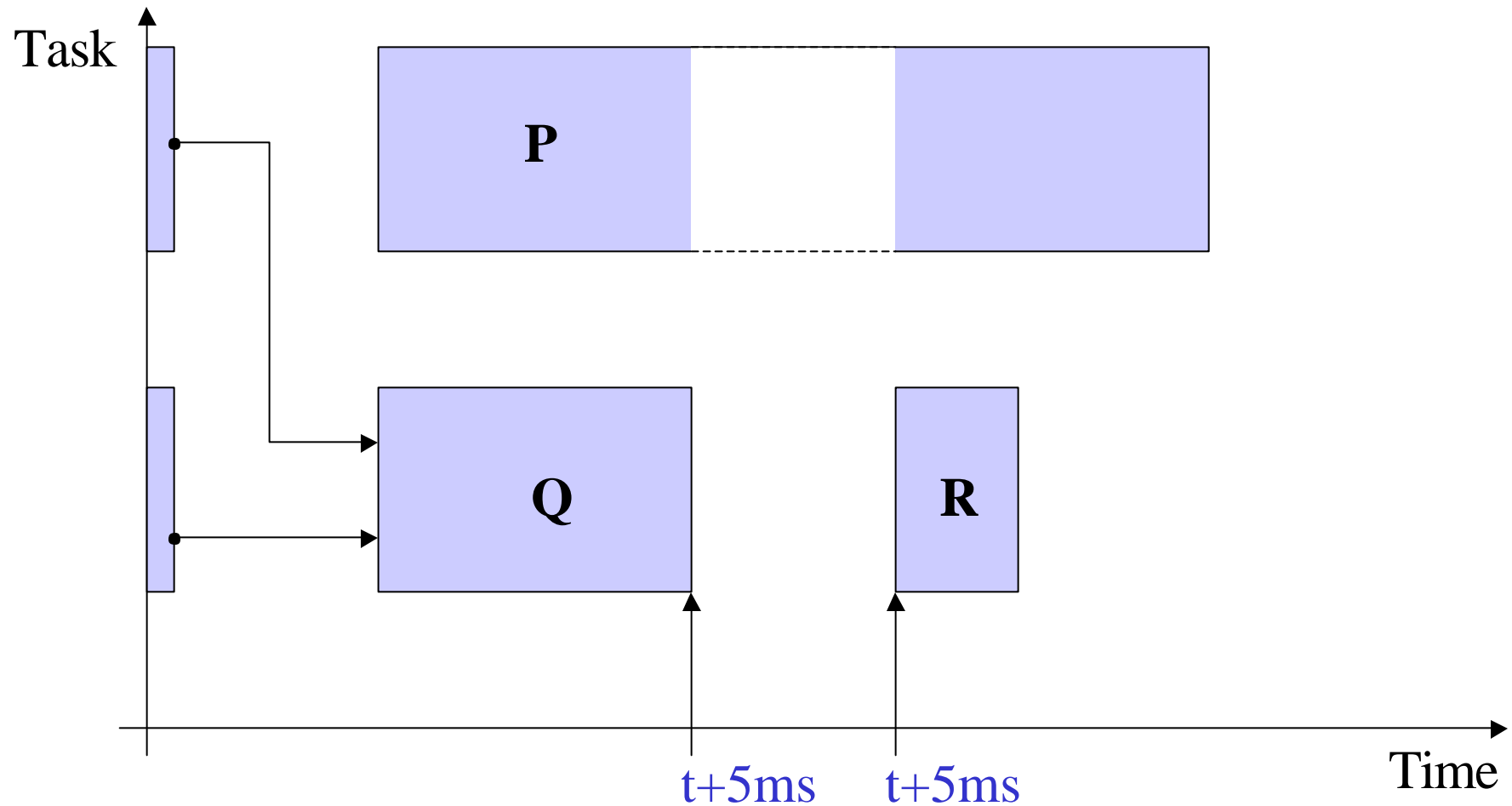
Semantics of a Mode Switch



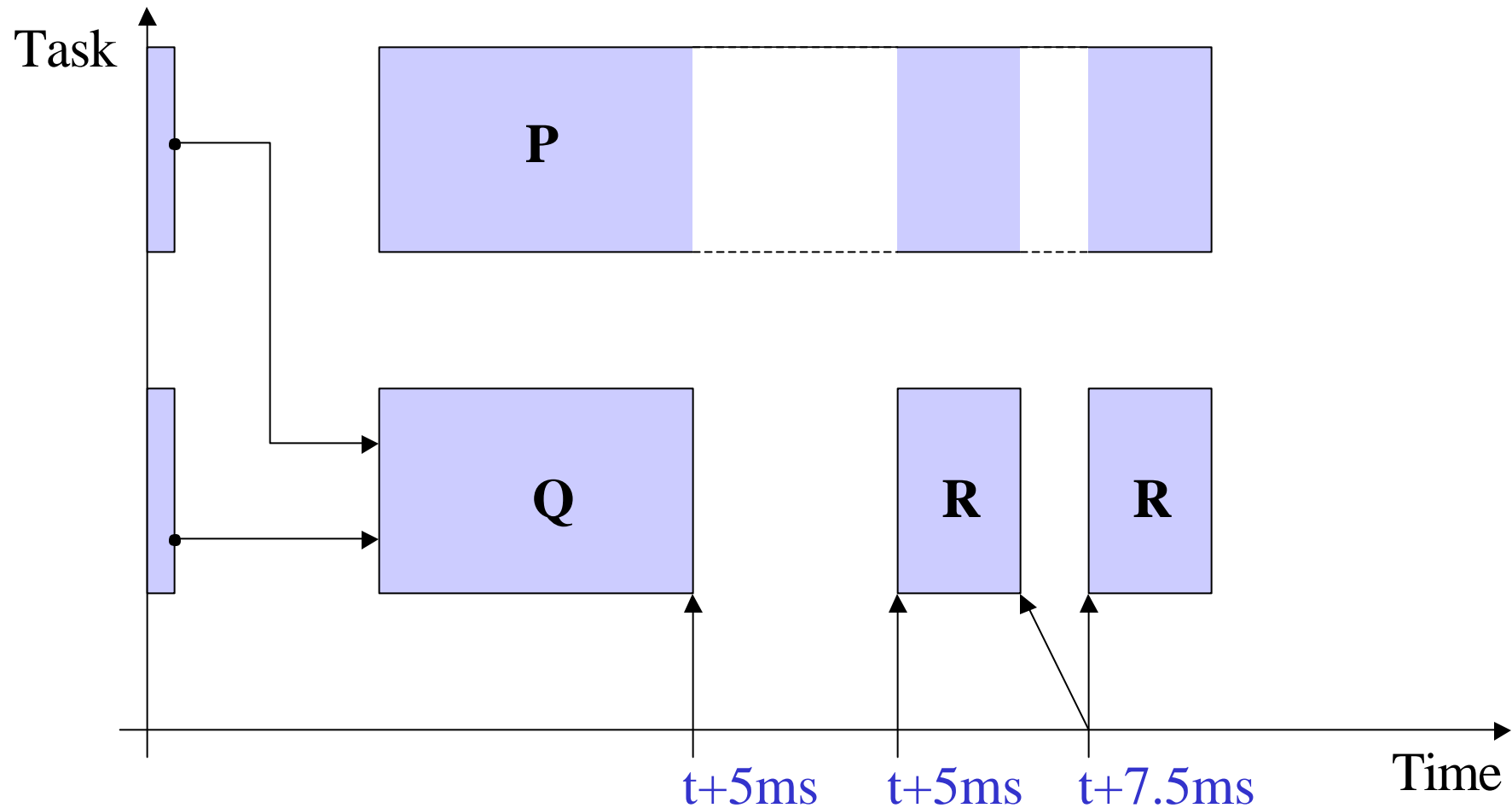
Mode M'



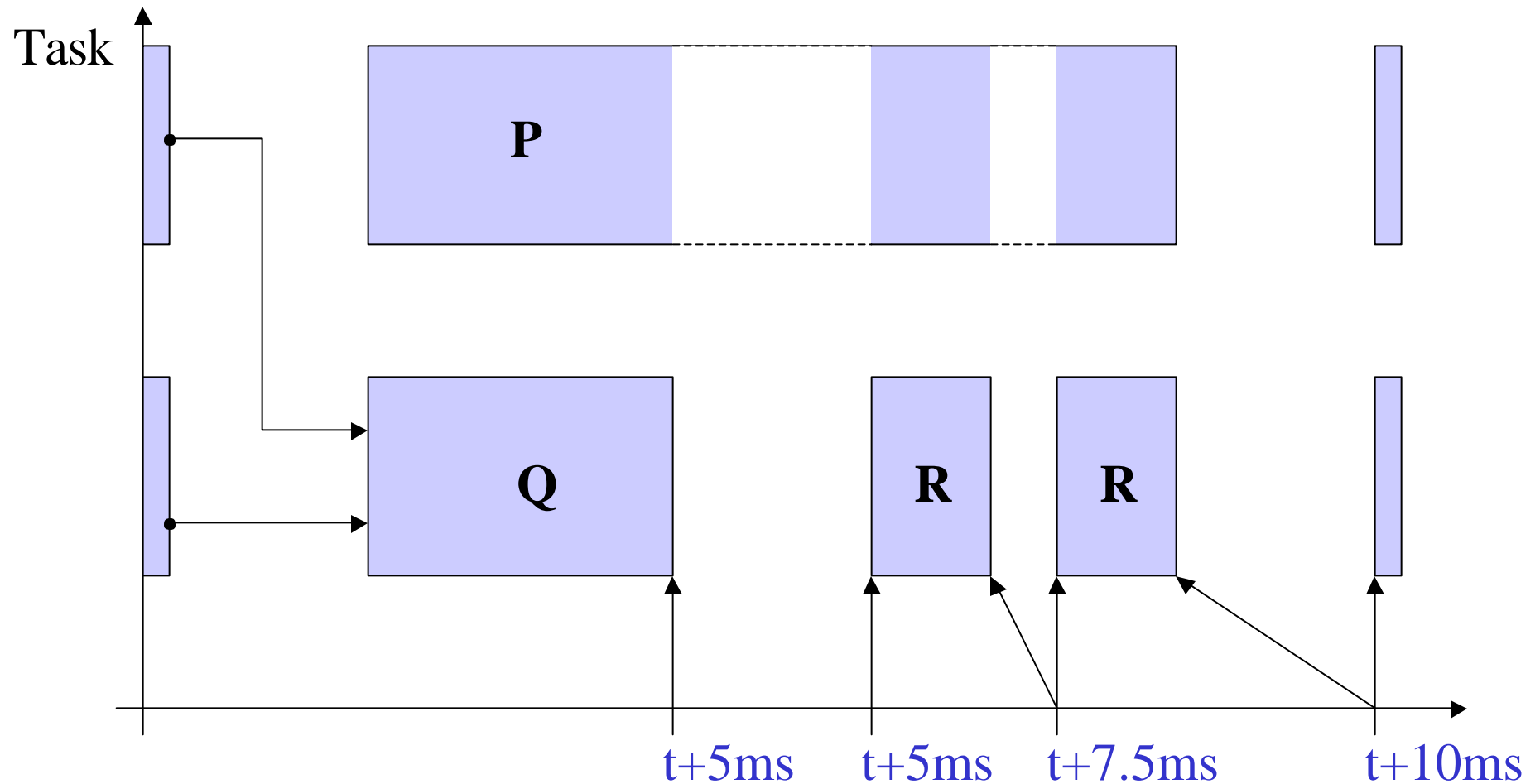
Semantics of a Mode Switch



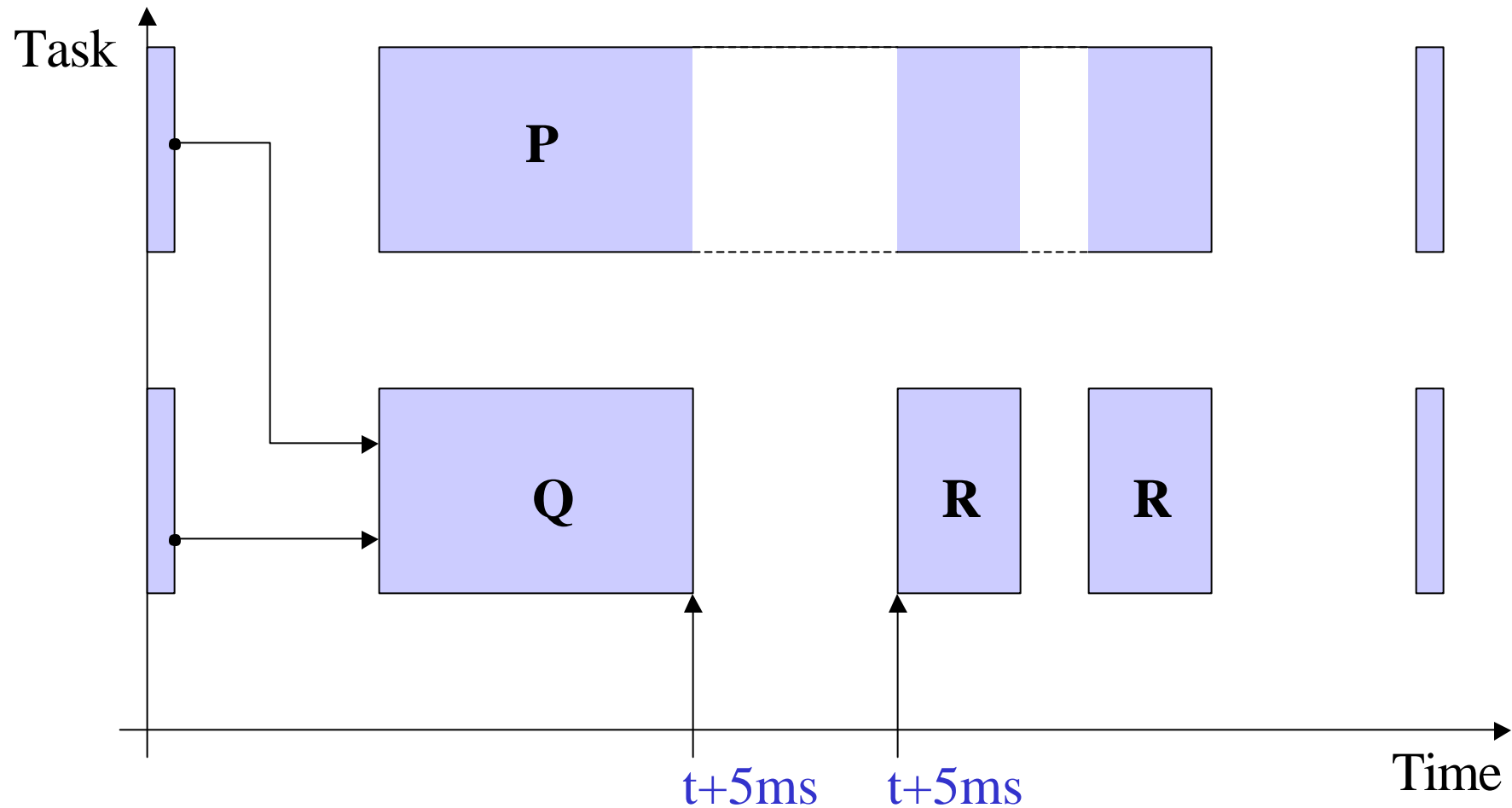
Semantics of a Mode Switch



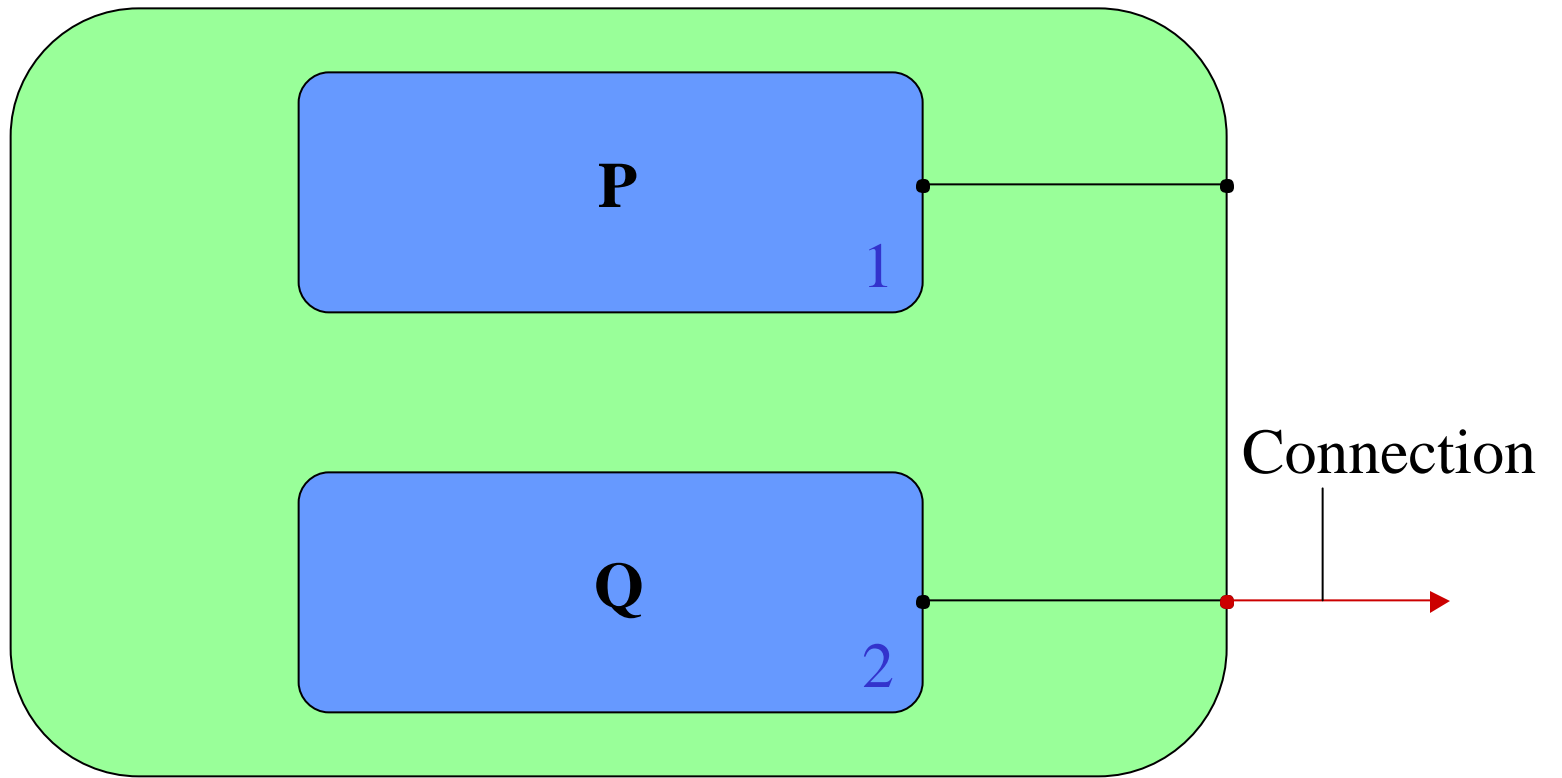
Semantics of a Mode Switch



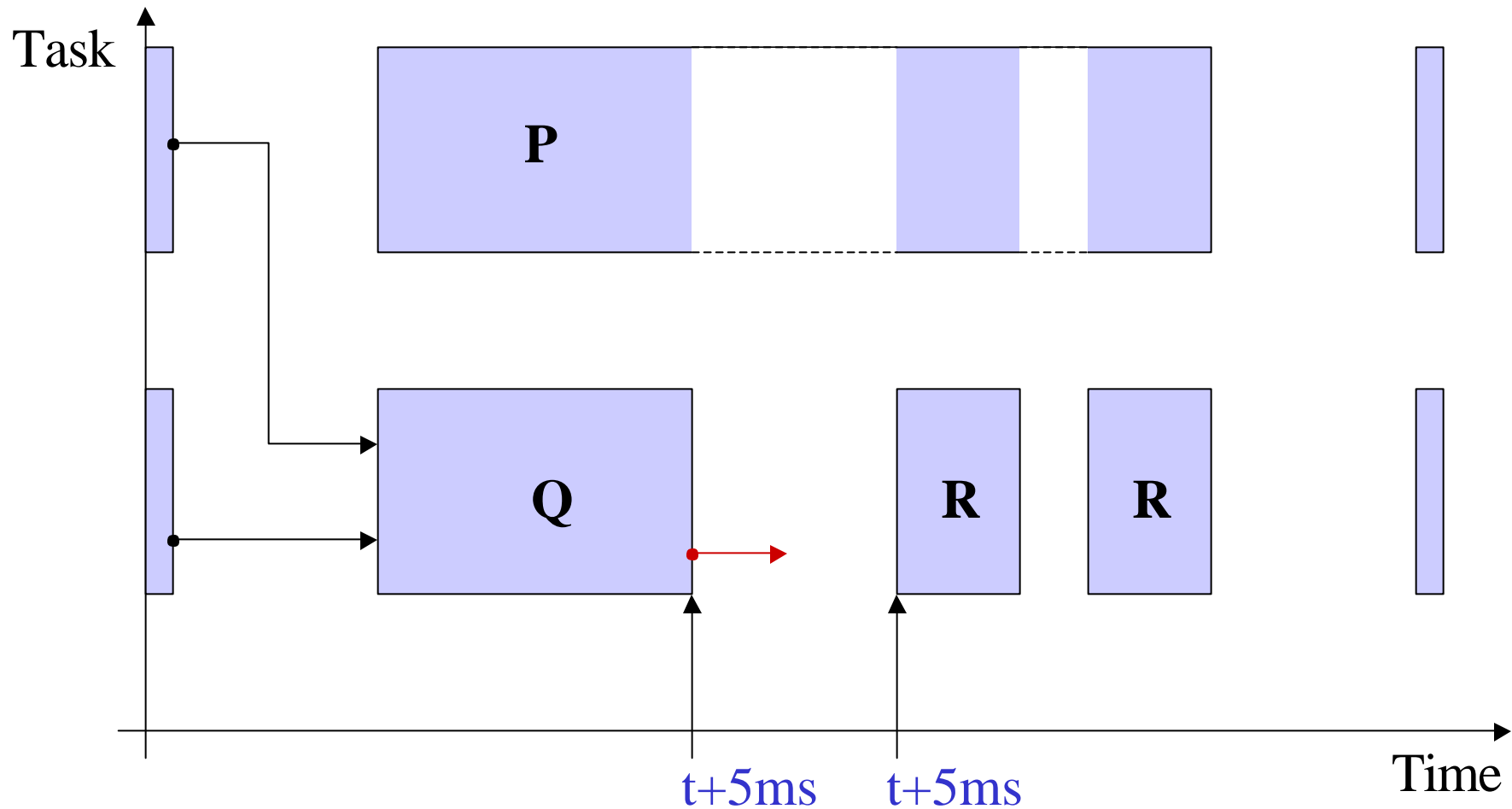
Semantics of a Mode Switch



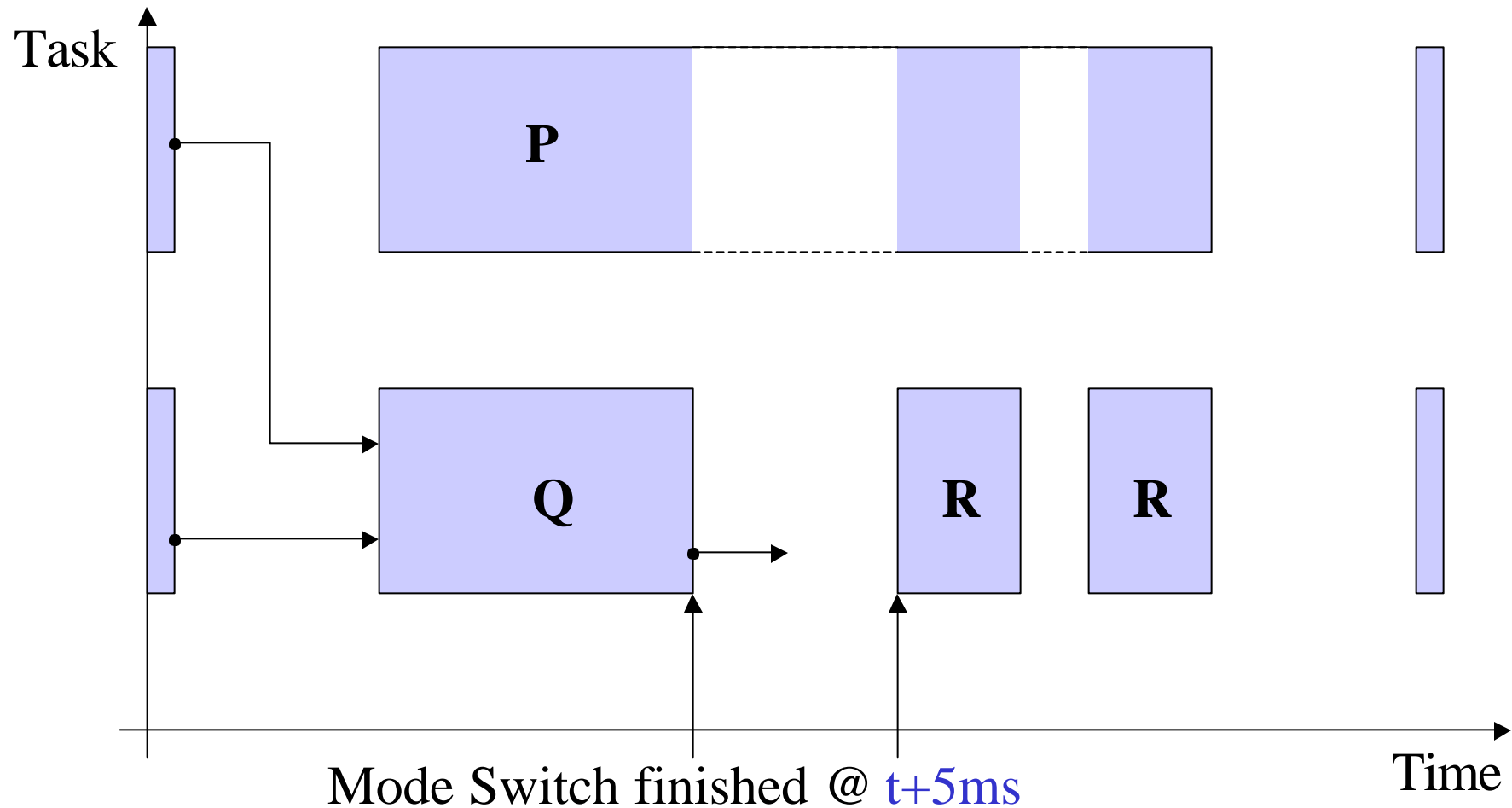
Mode M



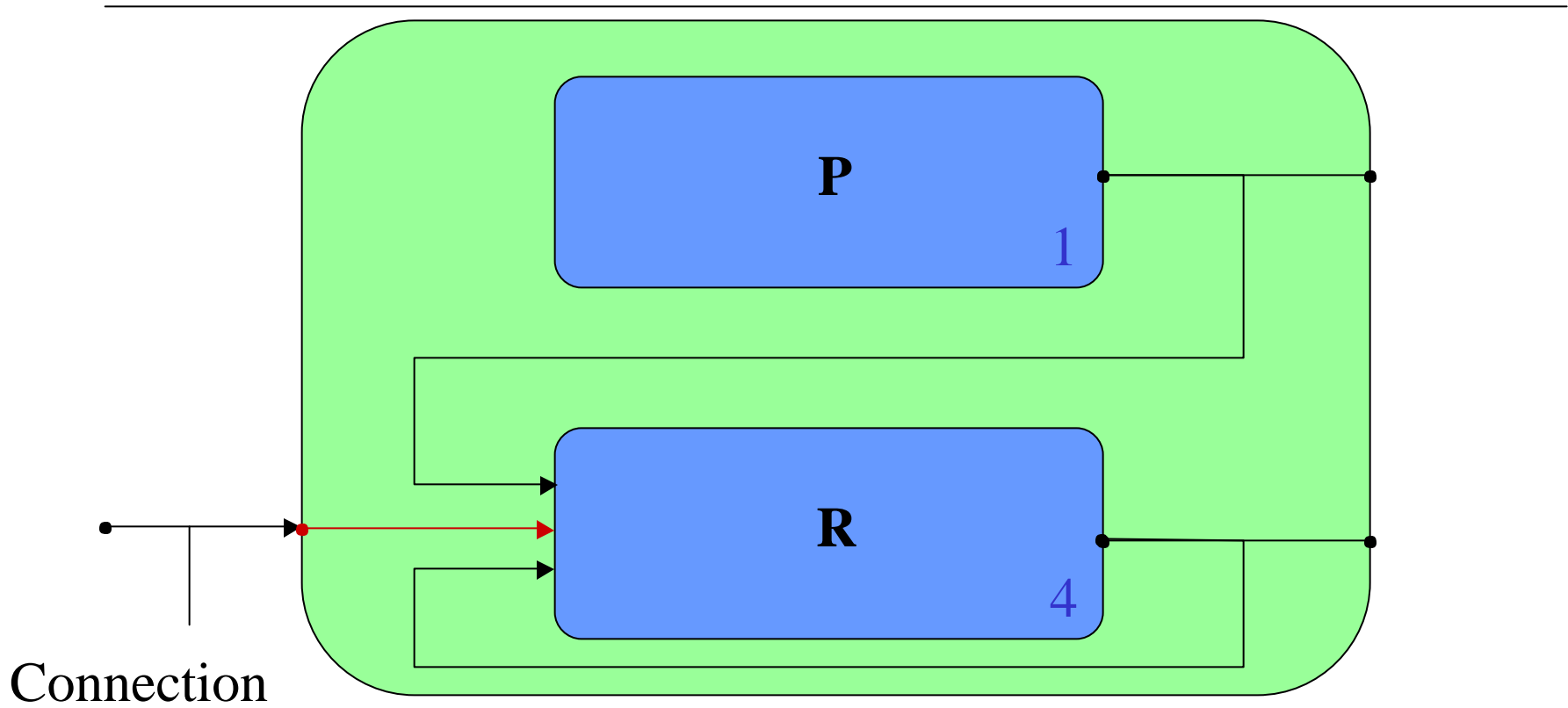
Semantics of a Mode Switch



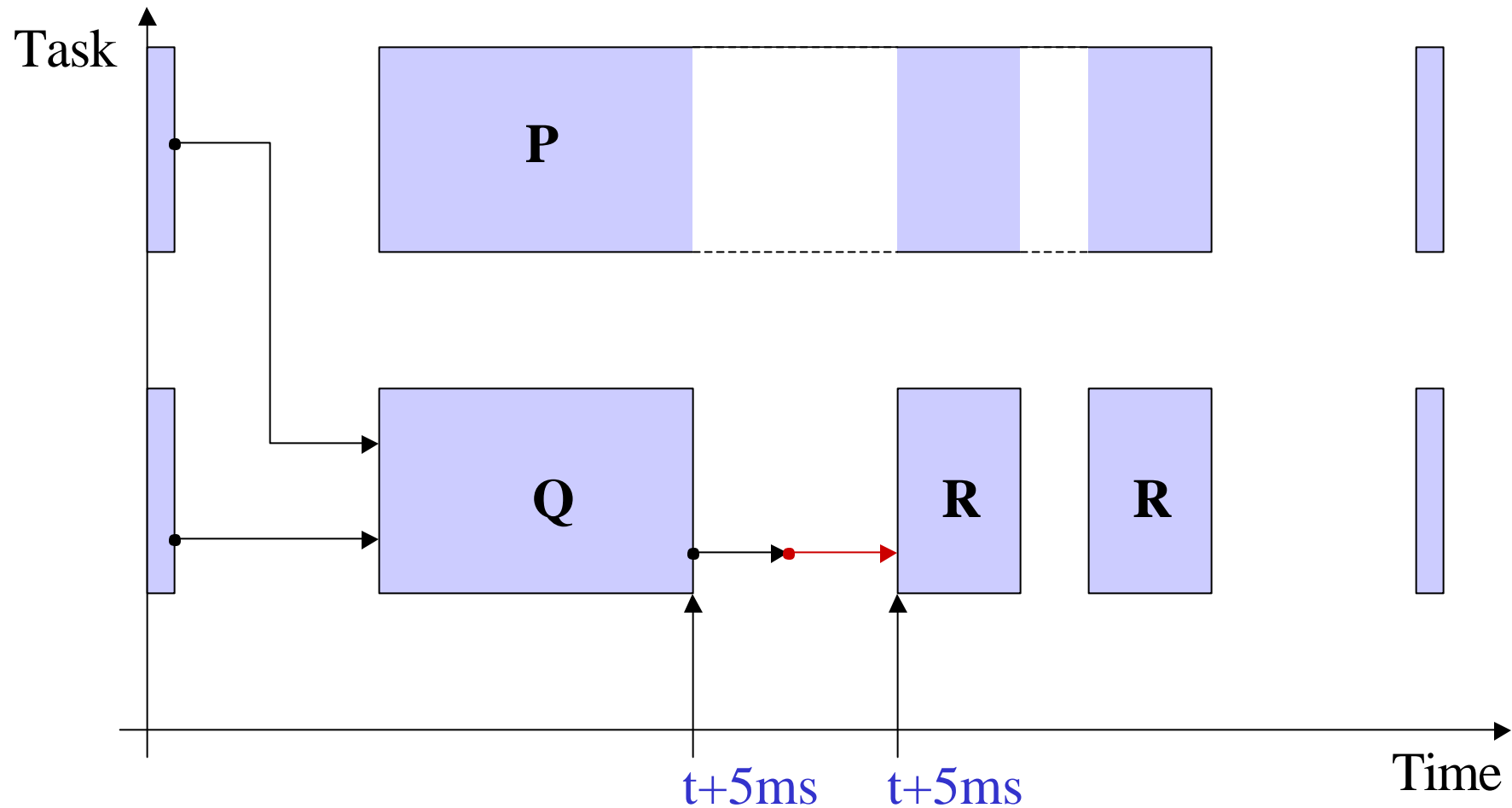
Semantics of a Mode Switch



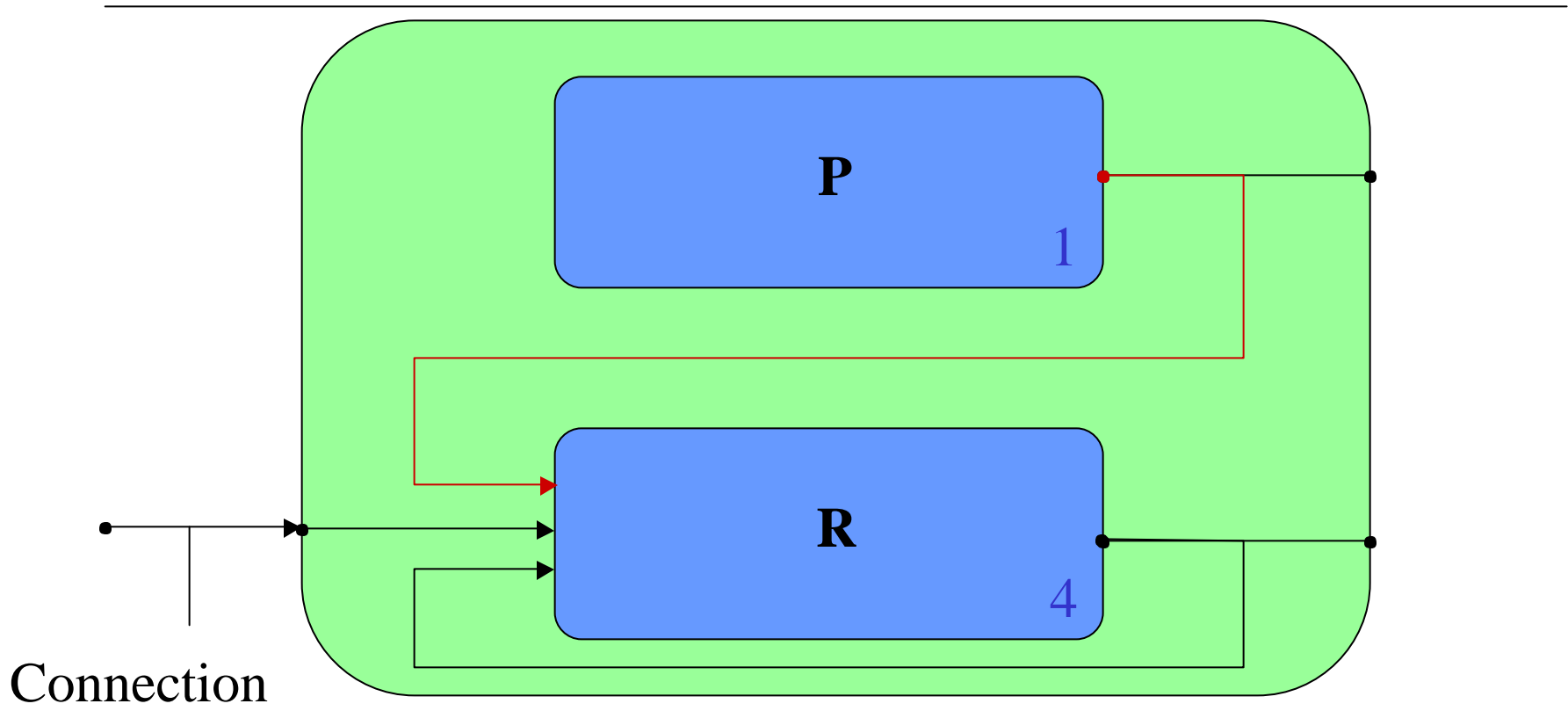
Mode M'



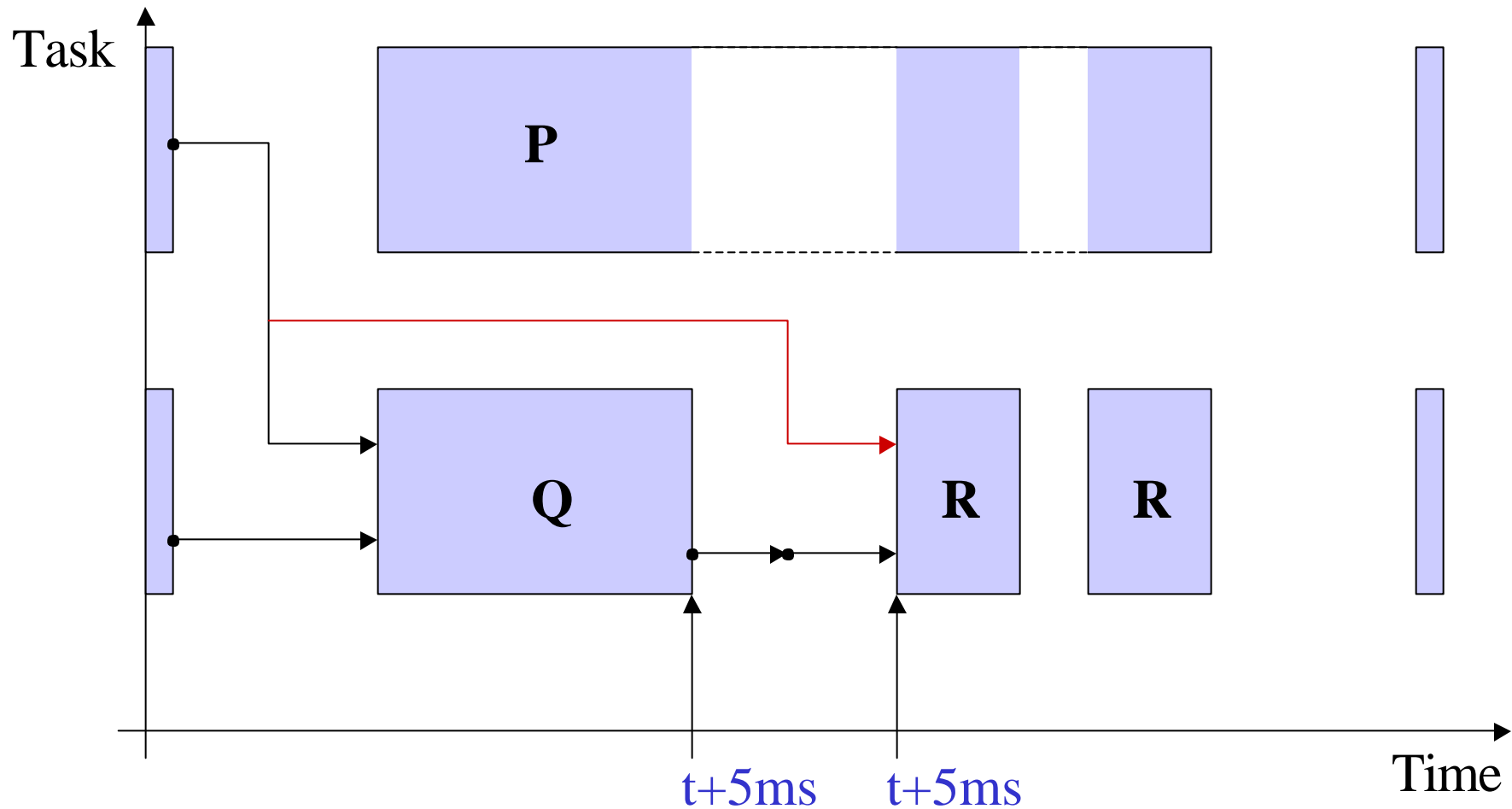
Semantics of a Mode Switch



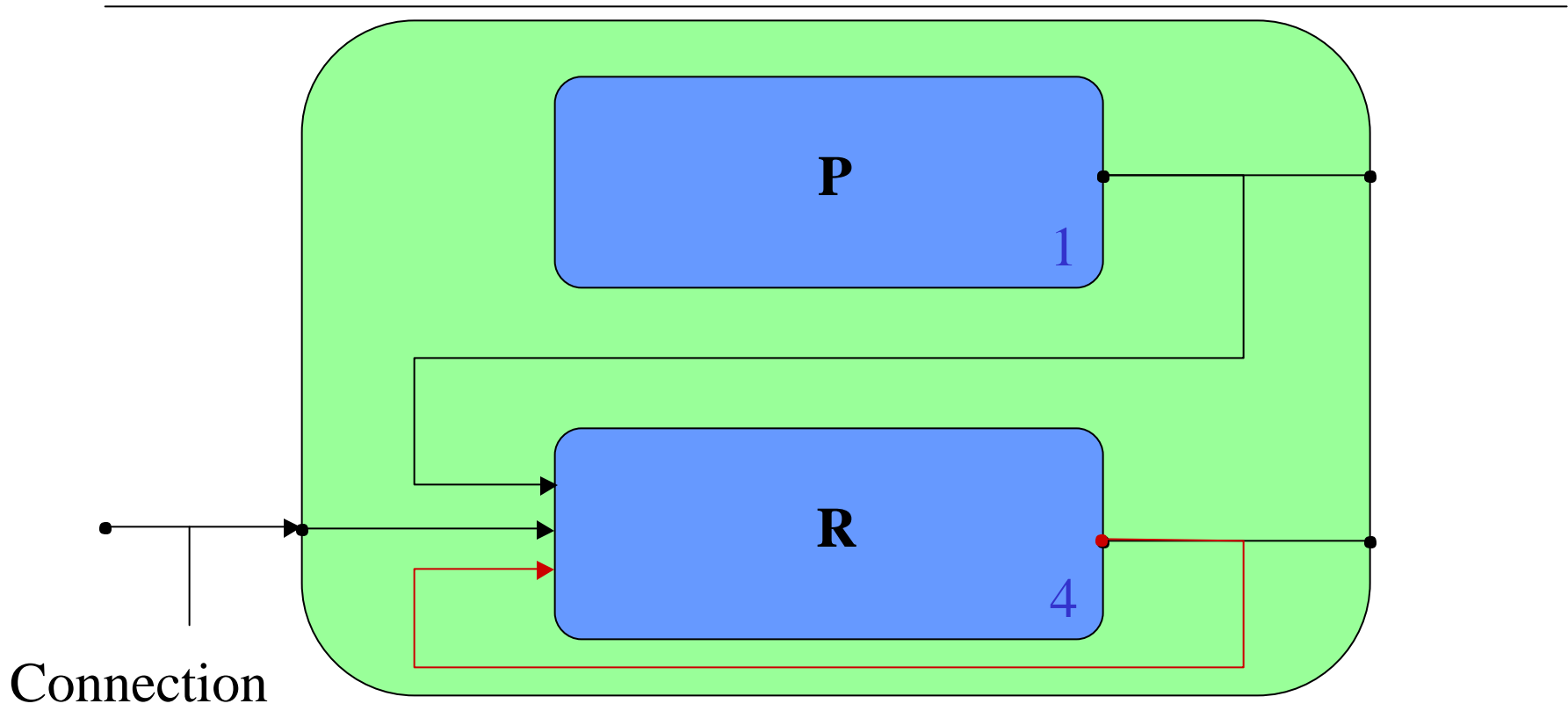
Mode M'



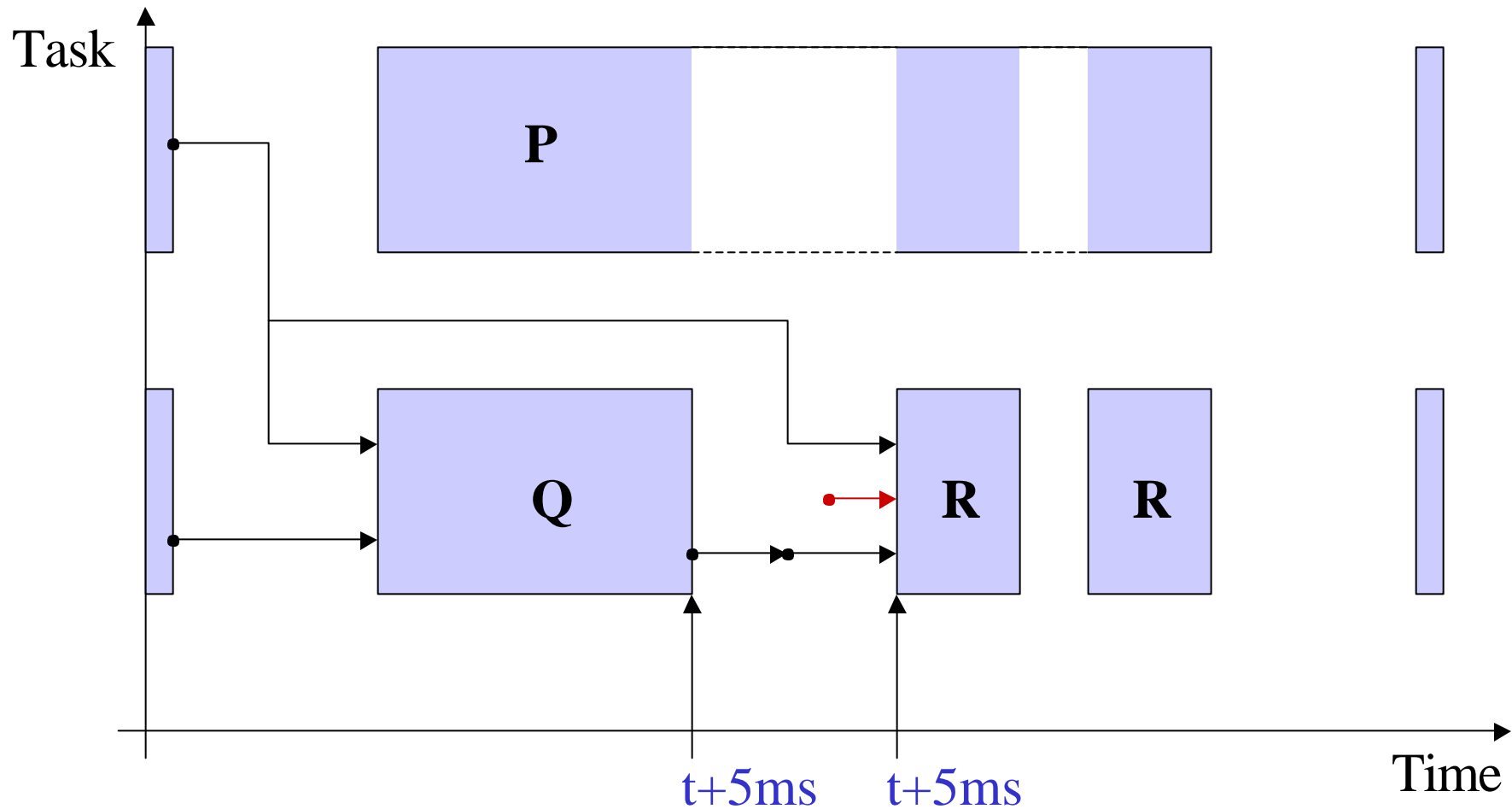
Semantics of a Mode Switch



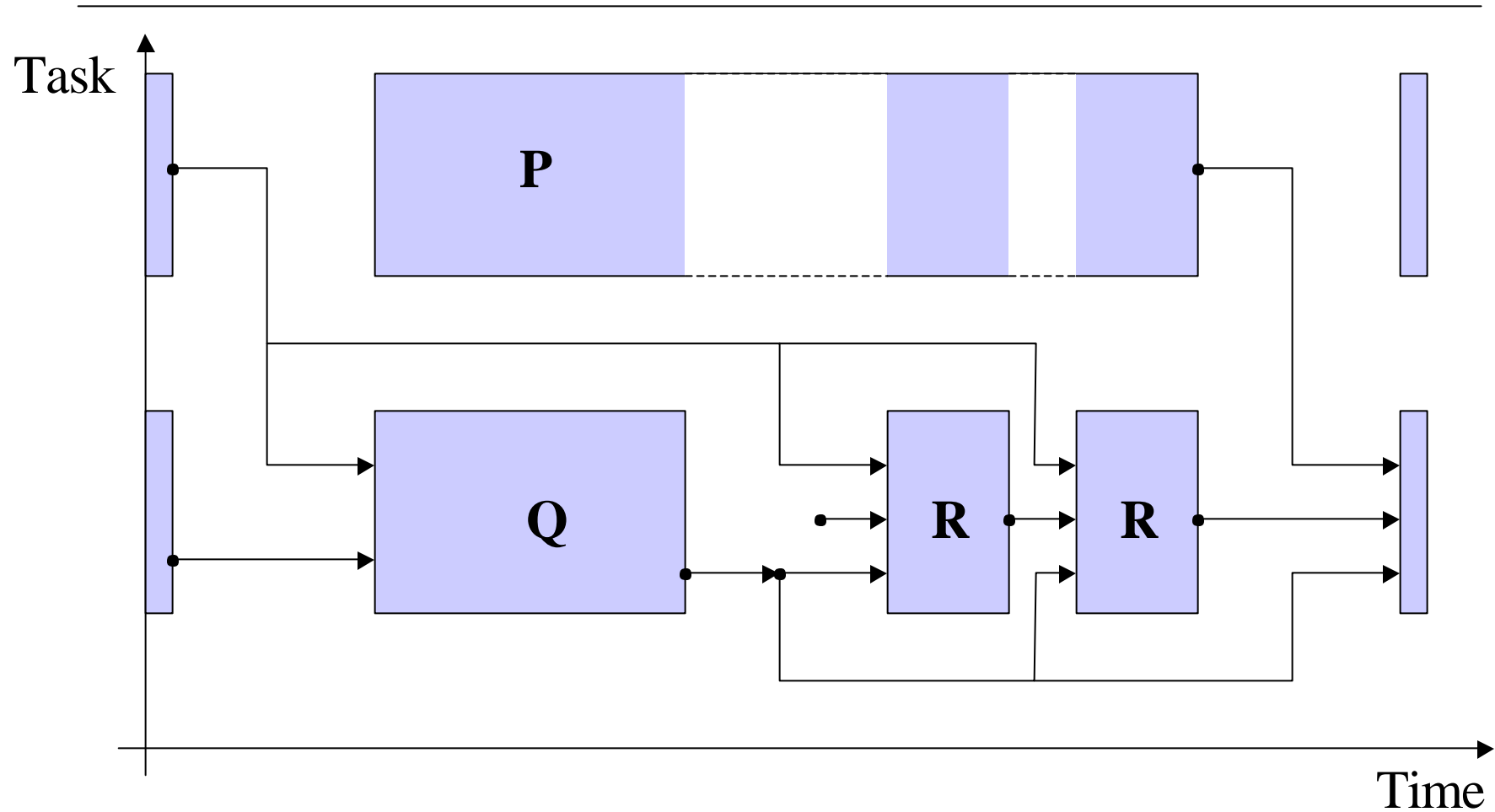
Mode M'



Semantics of a Mode Switch



Semantics of a Mode Switch



Decomposition: Giotto Modes

Preserving Structure

Our Approach

Decomposition



Modes

Compilation

The Giotto Compiler:

- Automatic code generation
- Stepwise program refinement with annotated Giotto for distributed platforms

The Giotto Compiler

Giotto Program

Giotto Compiler



Possible Answers:

- Giotto Executable
- Not Schedulable

Giotto Executable

Giotto-P Platform

Giotto Program

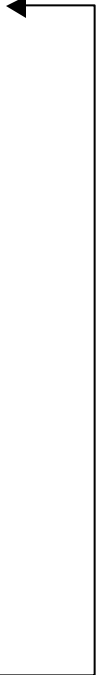
Giotto-P Program

Hosts, Nets, Performance

Giotto Compiler



Distributed Platform



Giotto-Scheduler

Giotto Program

Giotto-**P** Program

Hosts, Nets, Performance ←

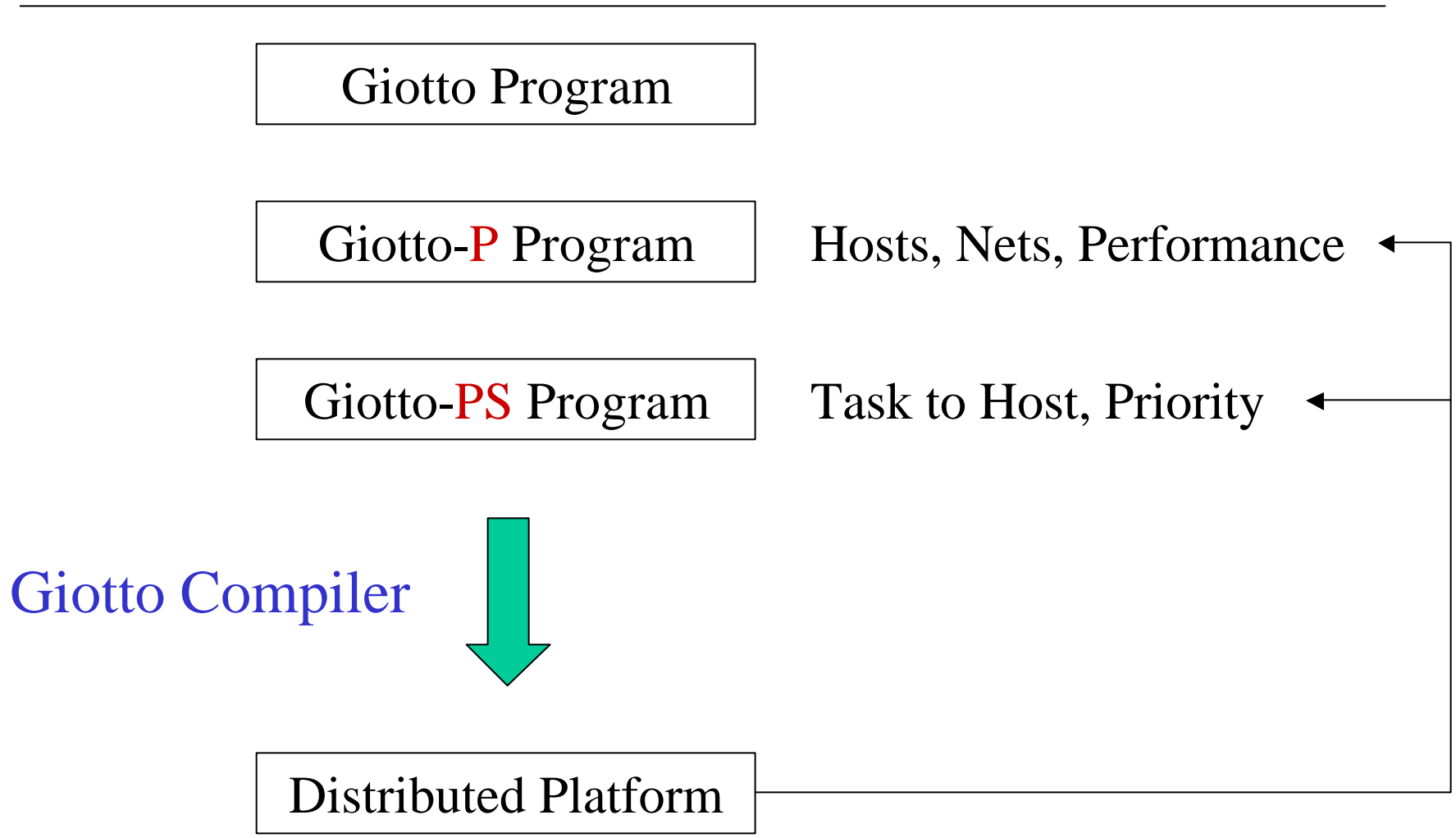
Giotto-**PS** Program

Task to Host, Priority ←

Giotto Compiler



Distributed Platform



Giotto-C Communication

Giotto Program

Giotto-**P** Program

Hosts, Nets, Performance ←

Giotto-**PS** Program

Task to Host, Priority ←

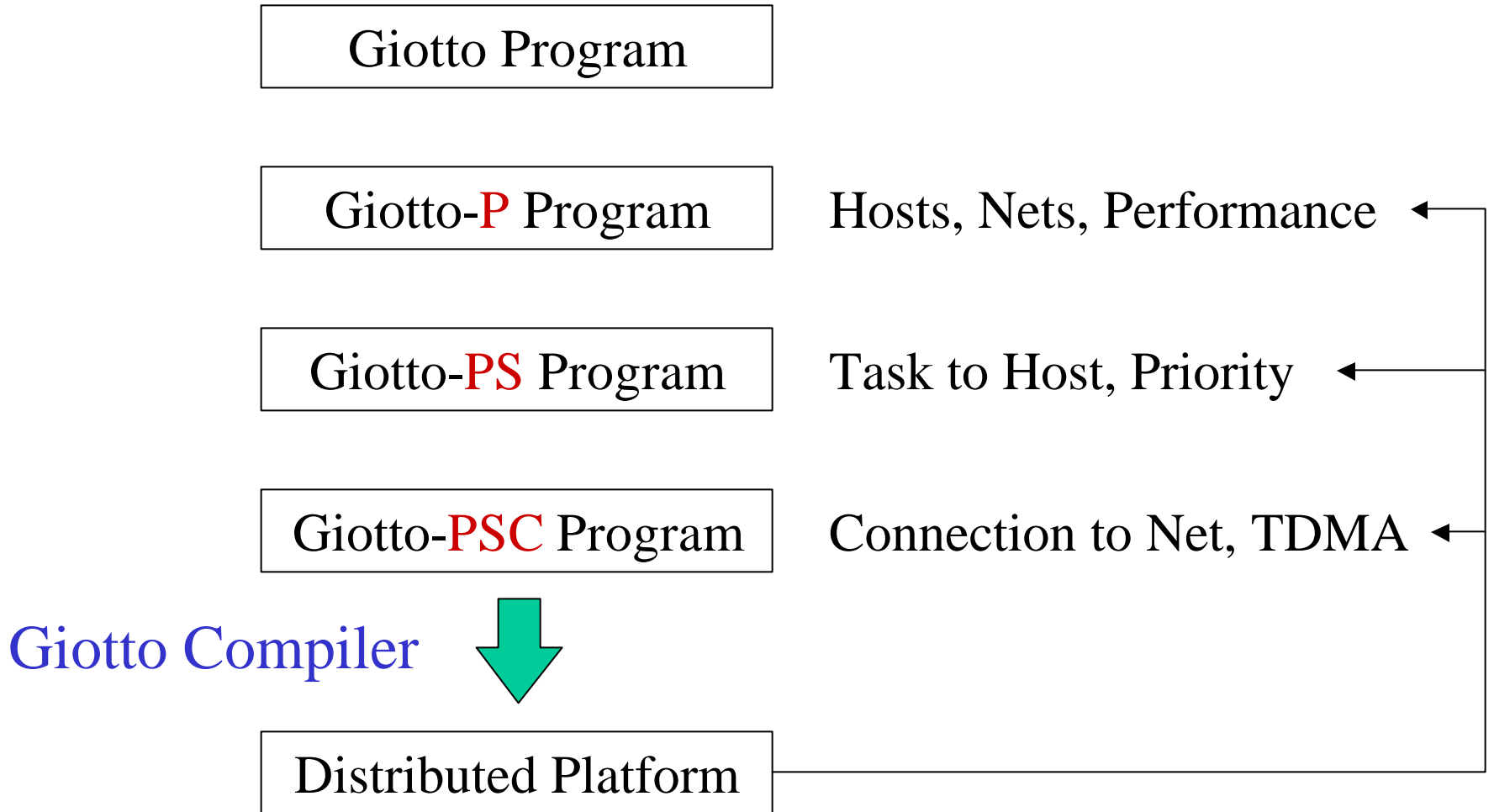
Giotto-**PSC** Program

Connection to Net, TDMA ←

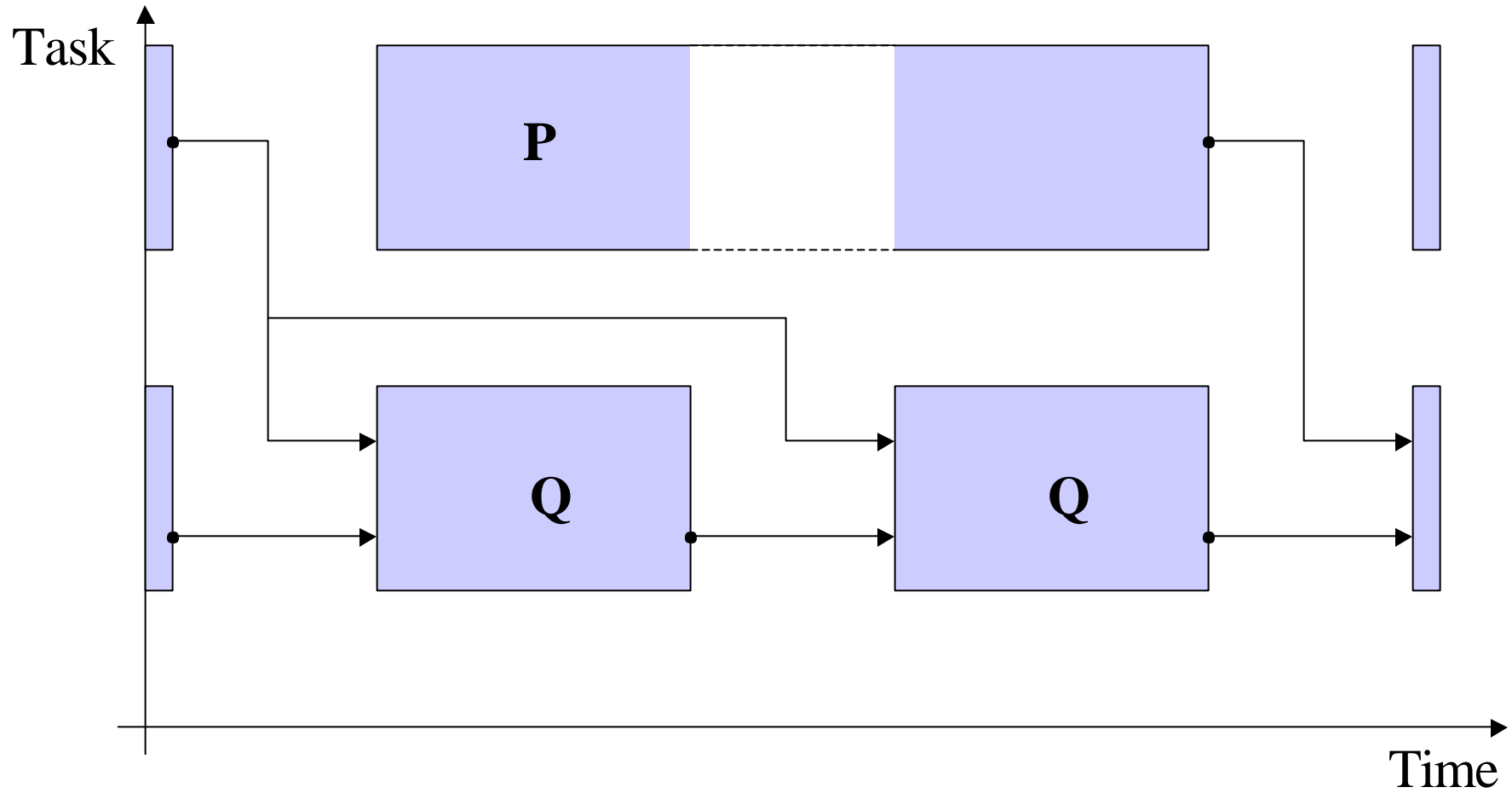
Giotto Compiler



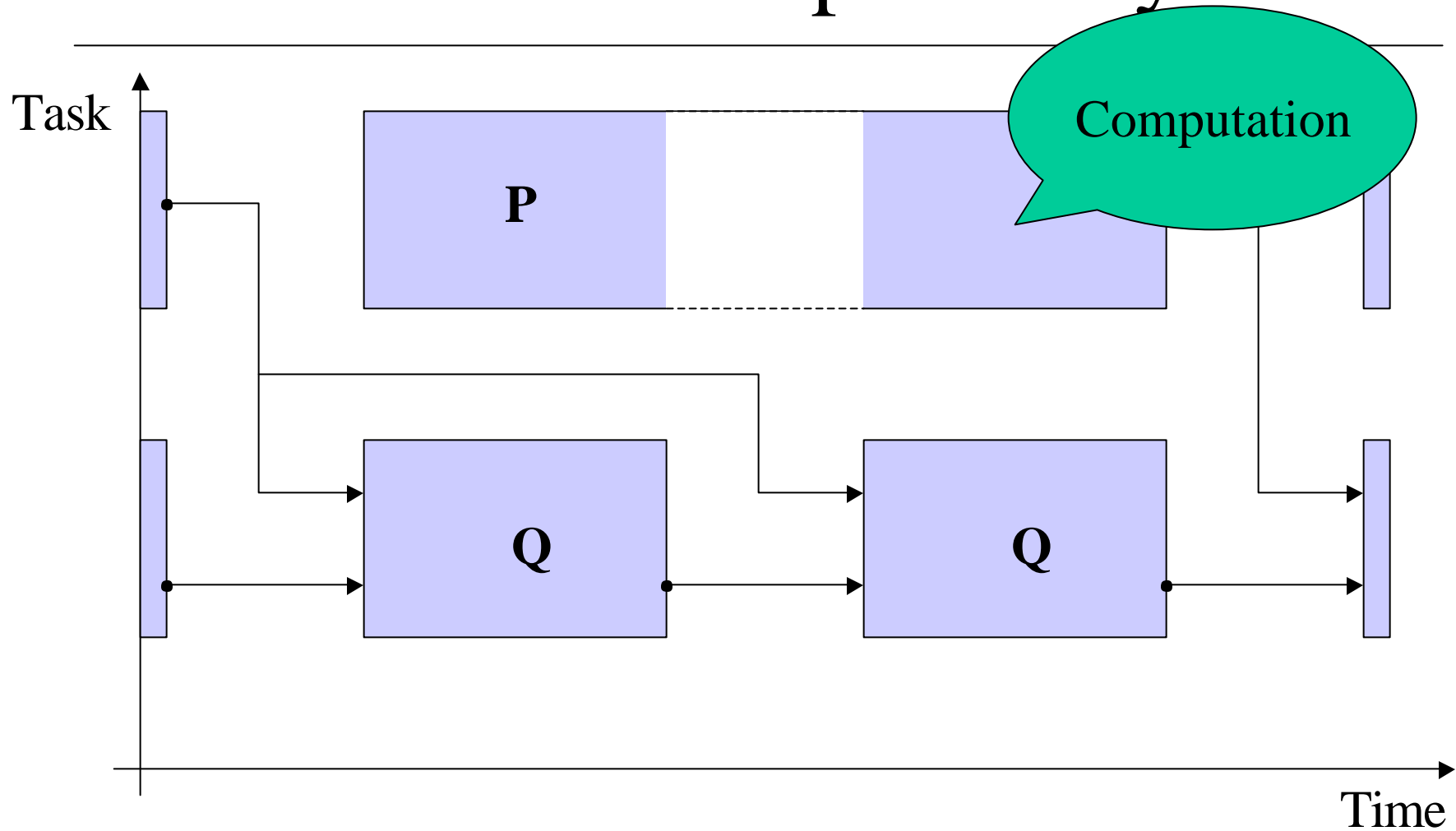
Distributed Platform



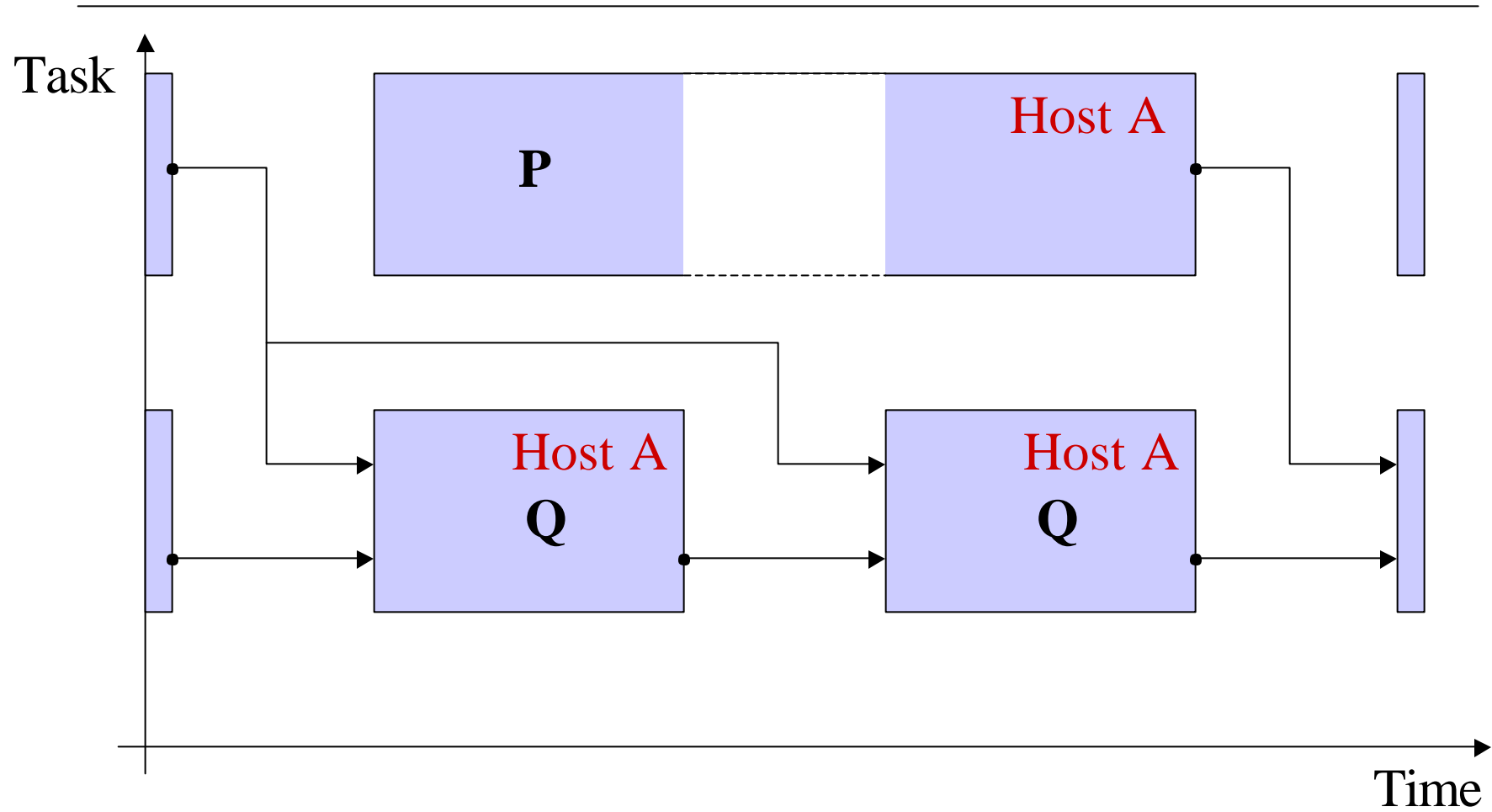
Platform Dependency



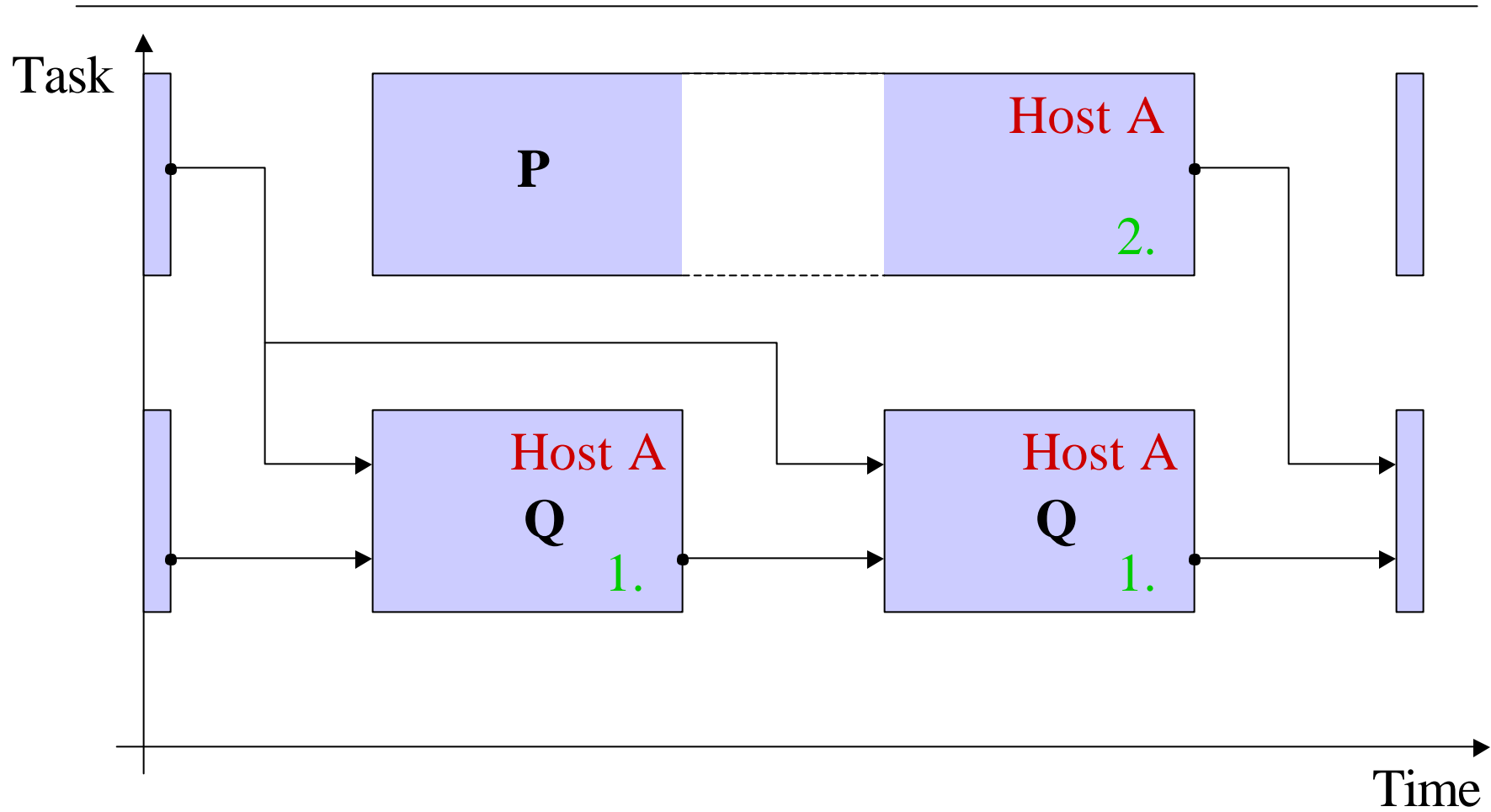
Platform Dependency



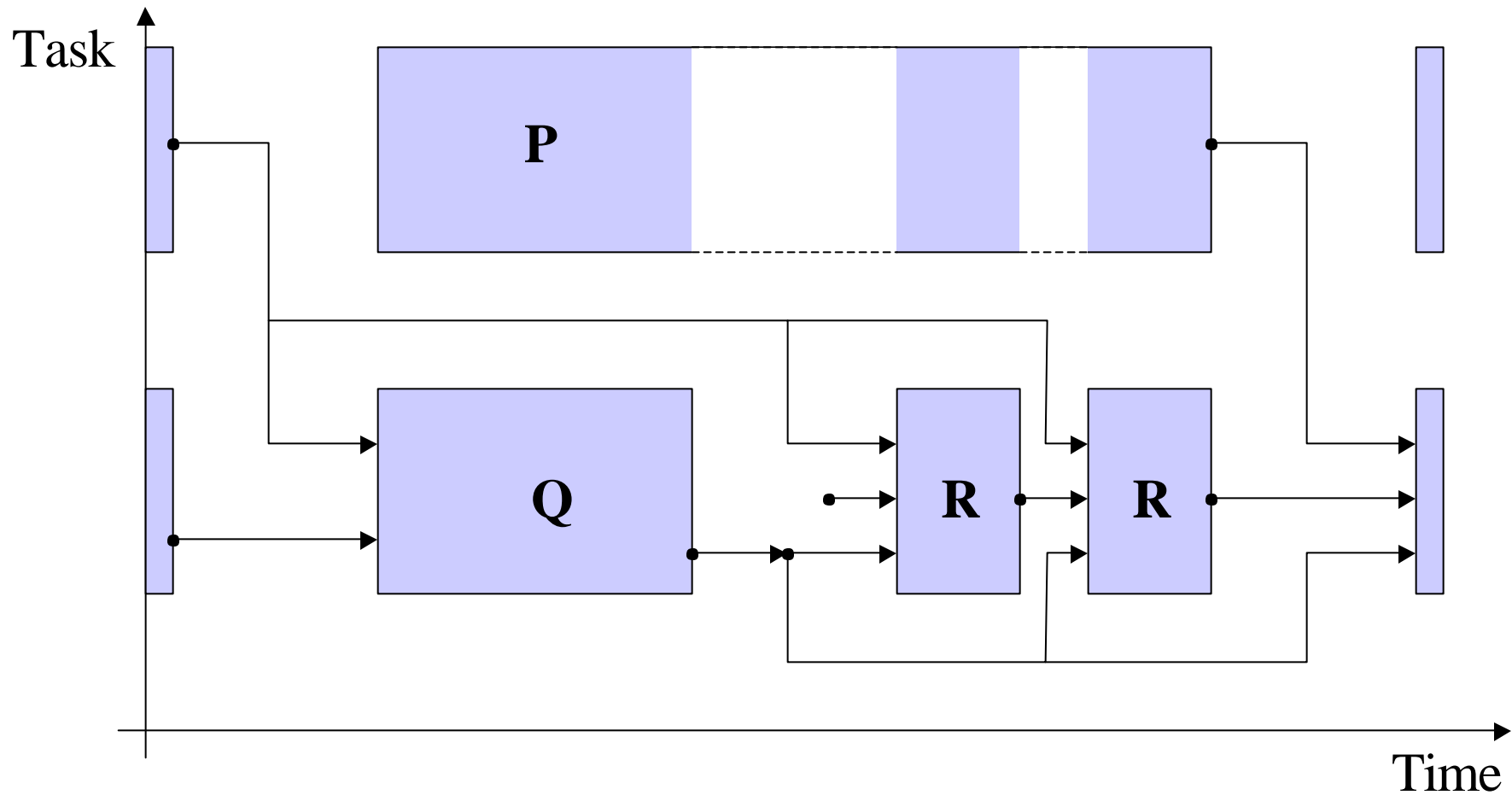
Giotto-PS



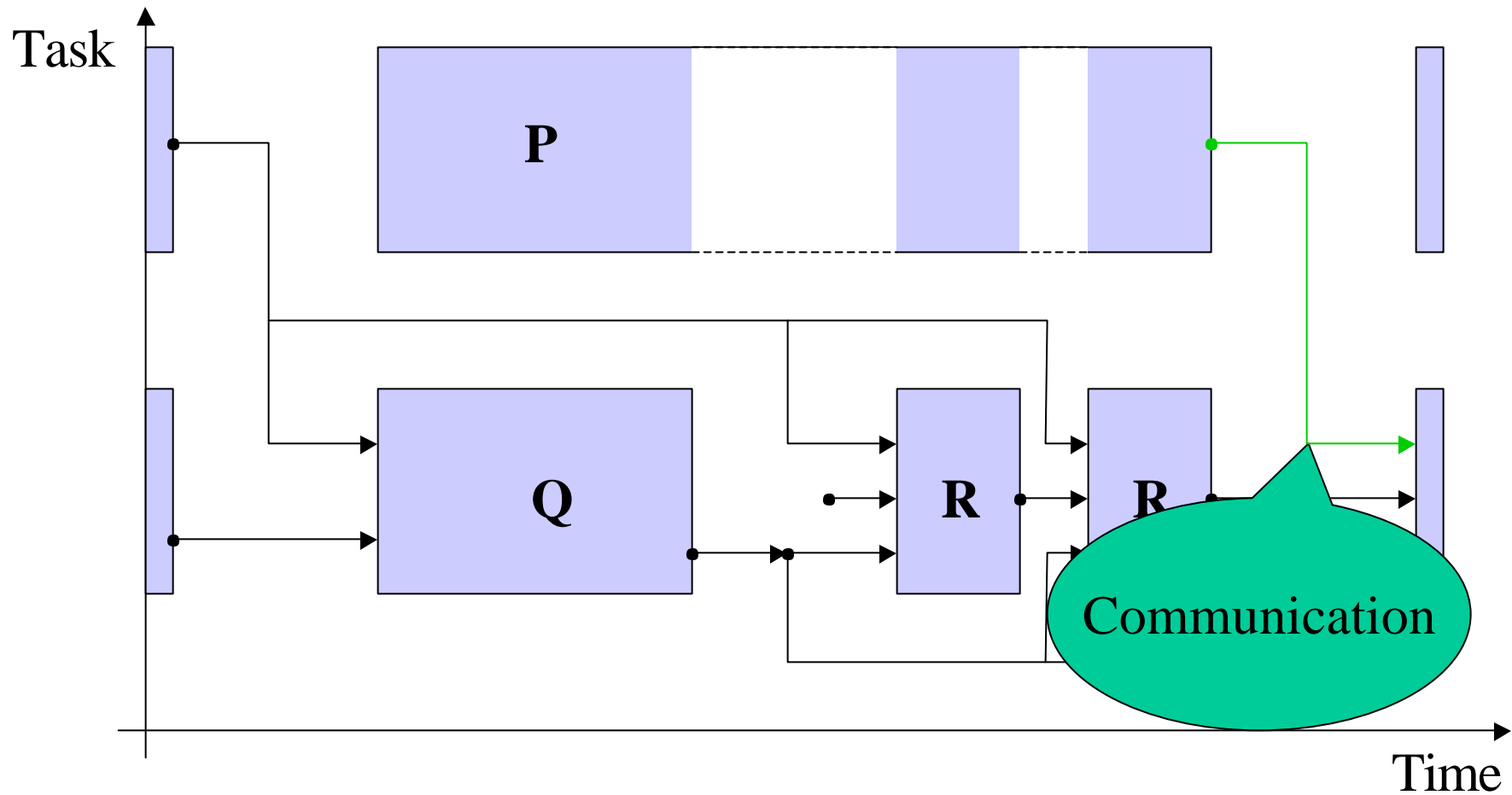
Giotto-PS



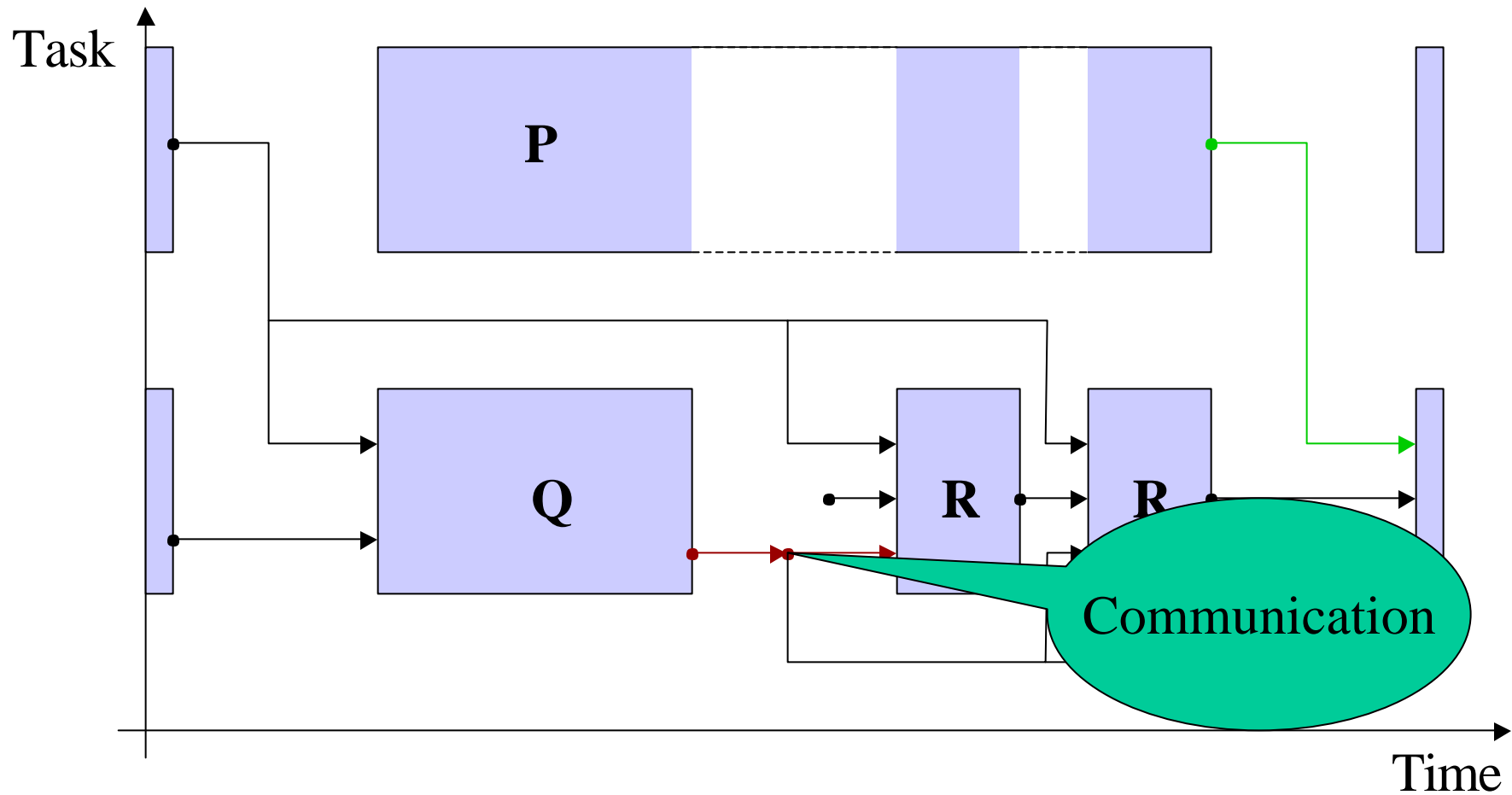
Platform Dependency



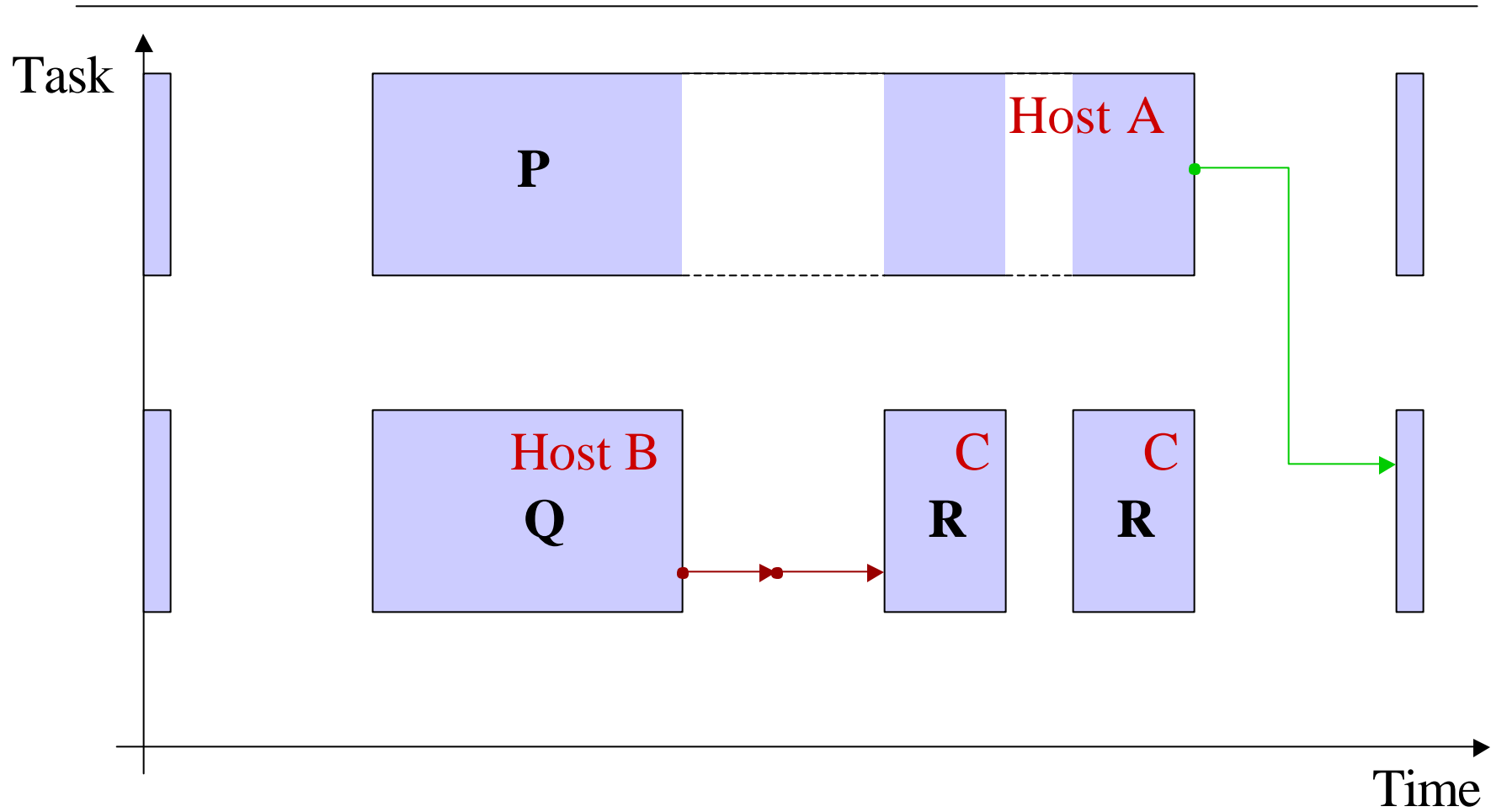
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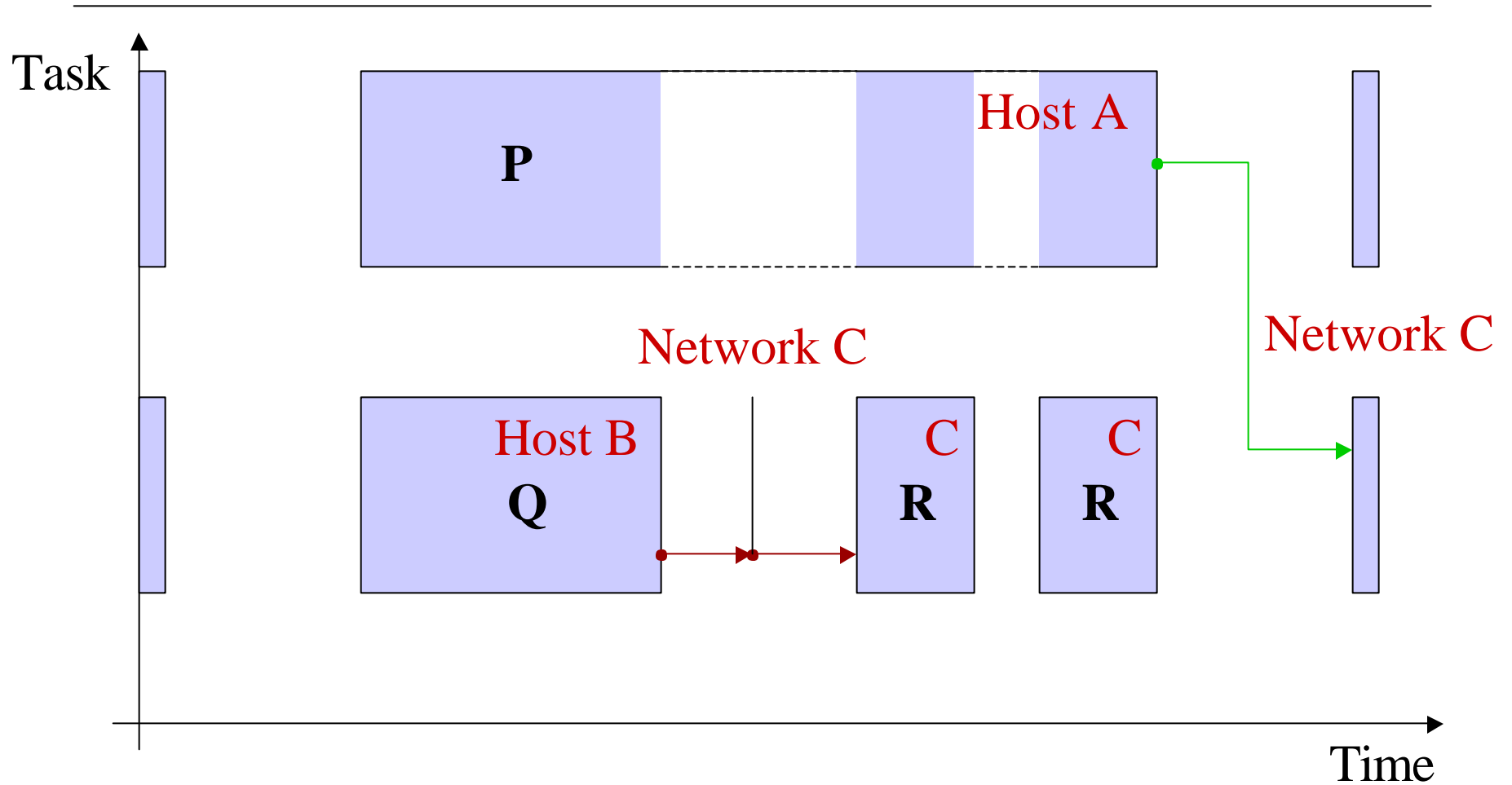
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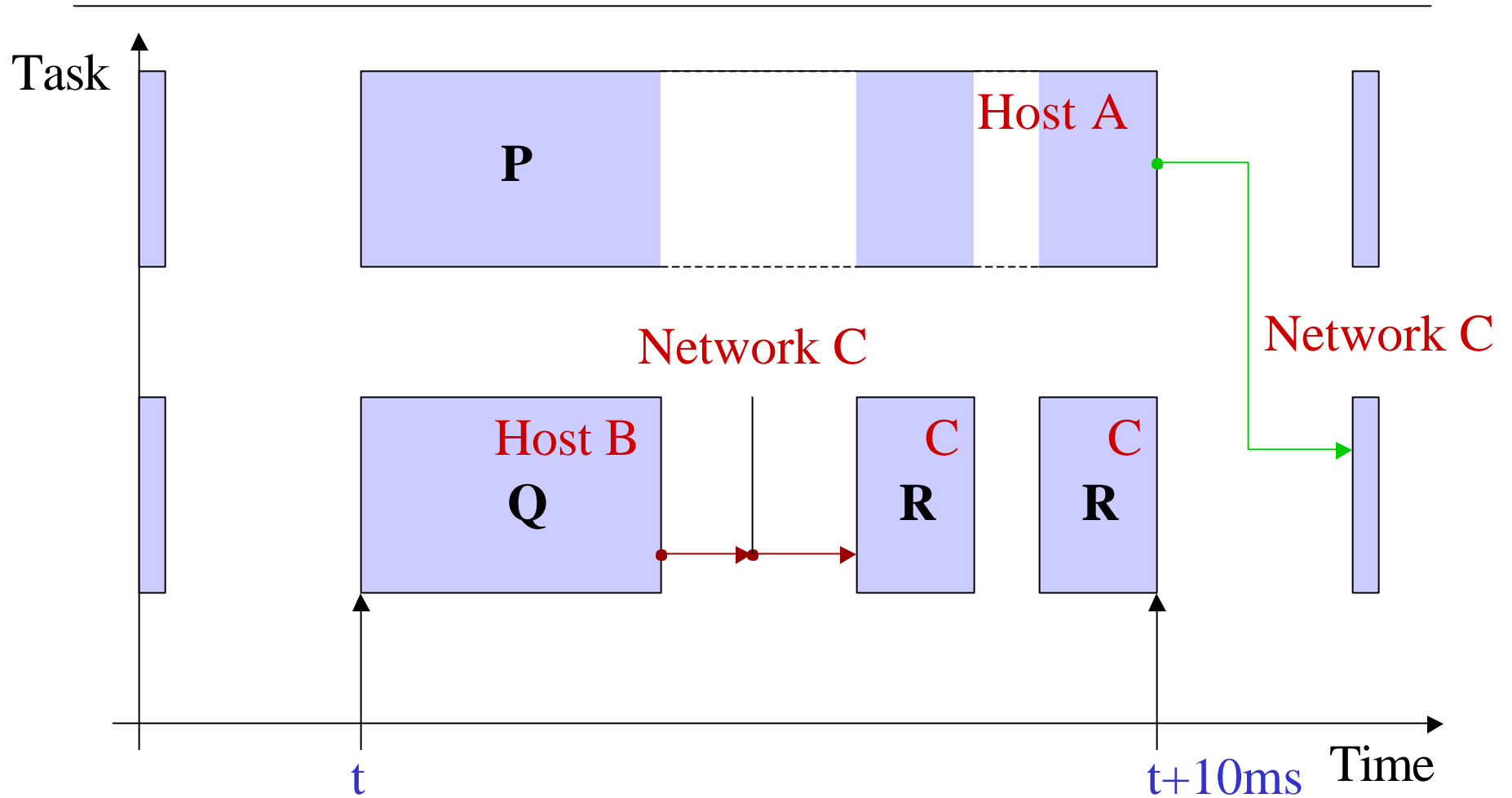
Giotto-PSC



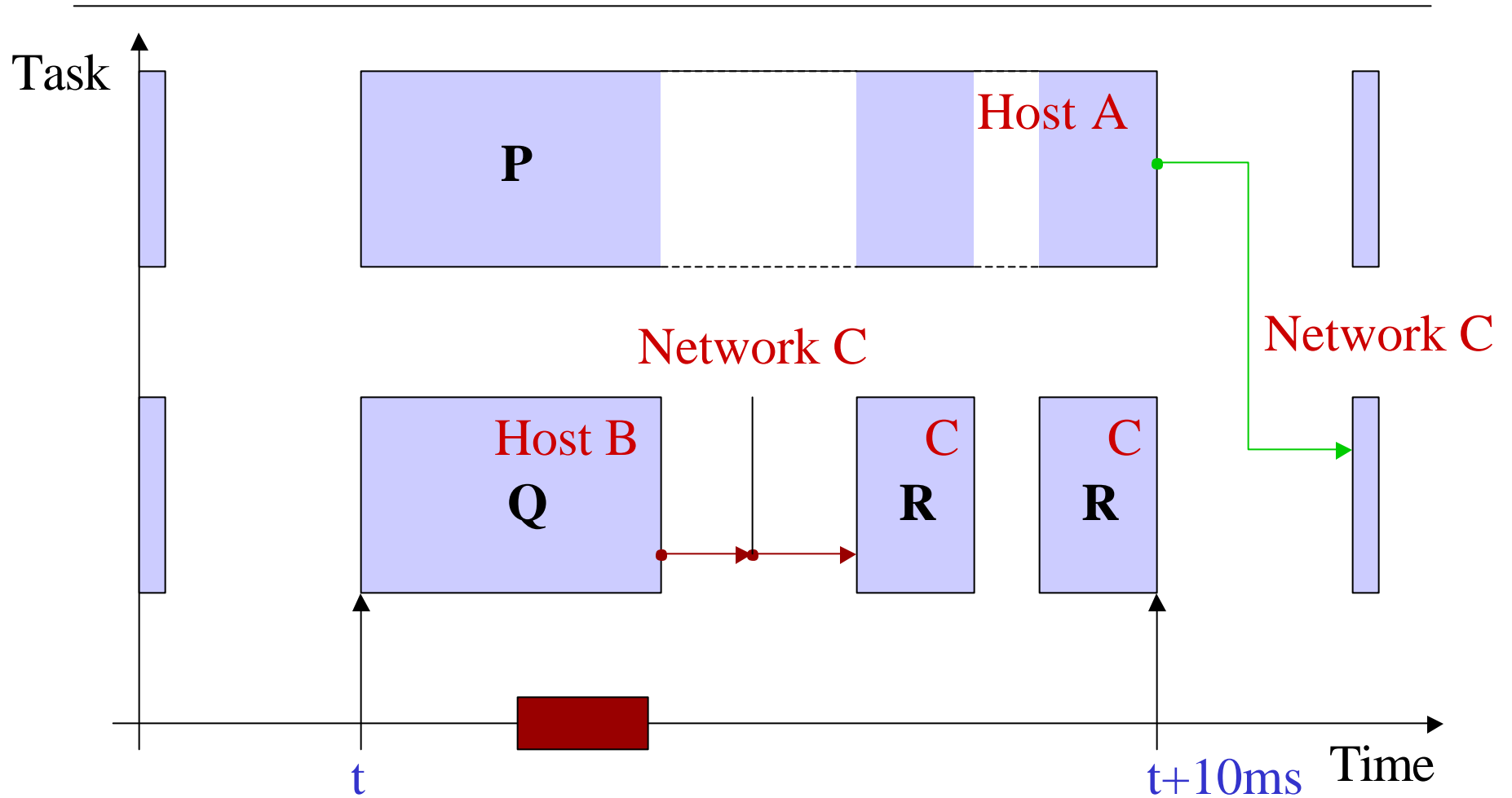
Giotto-PSC



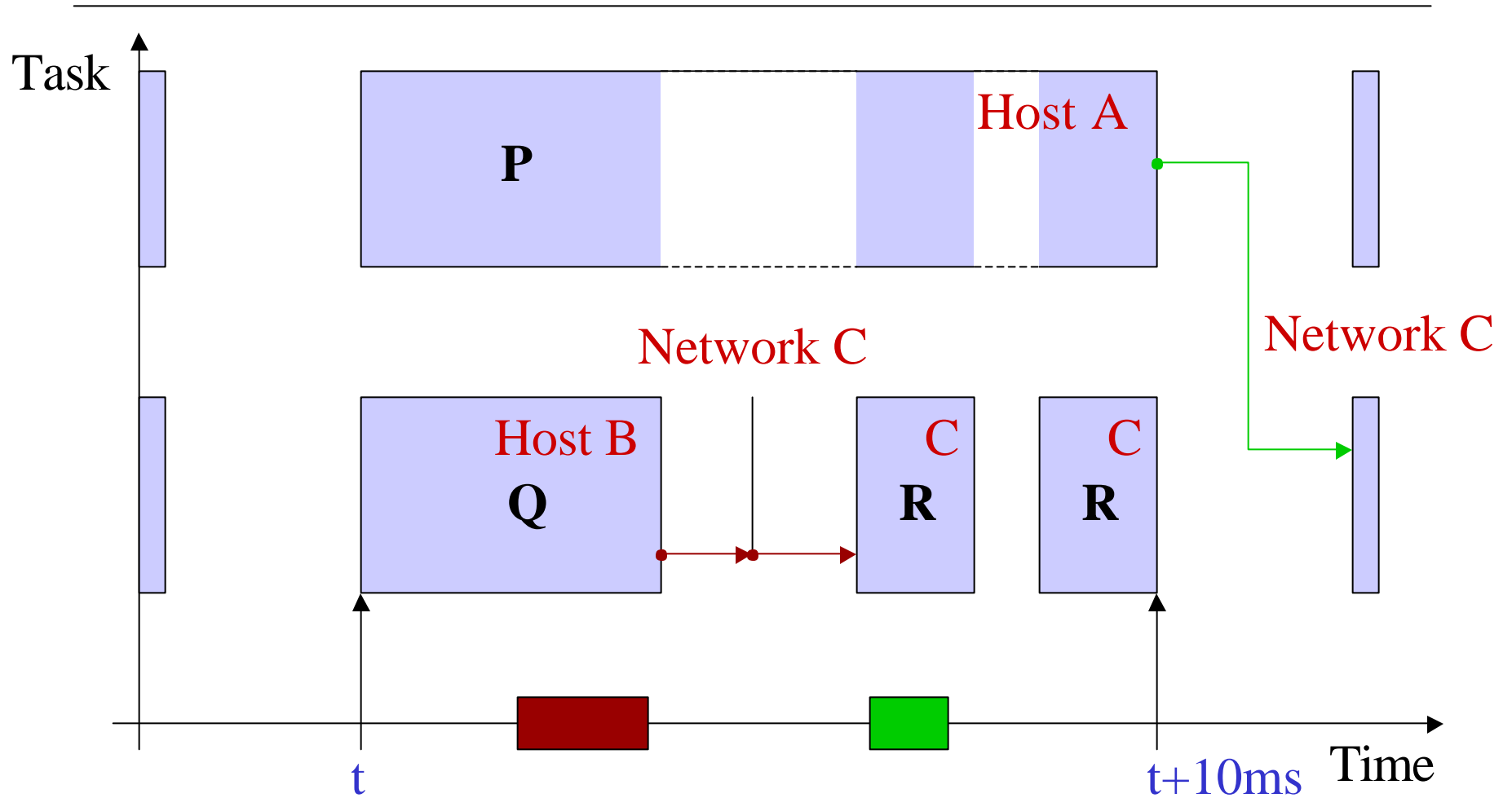
Giotto-PSC



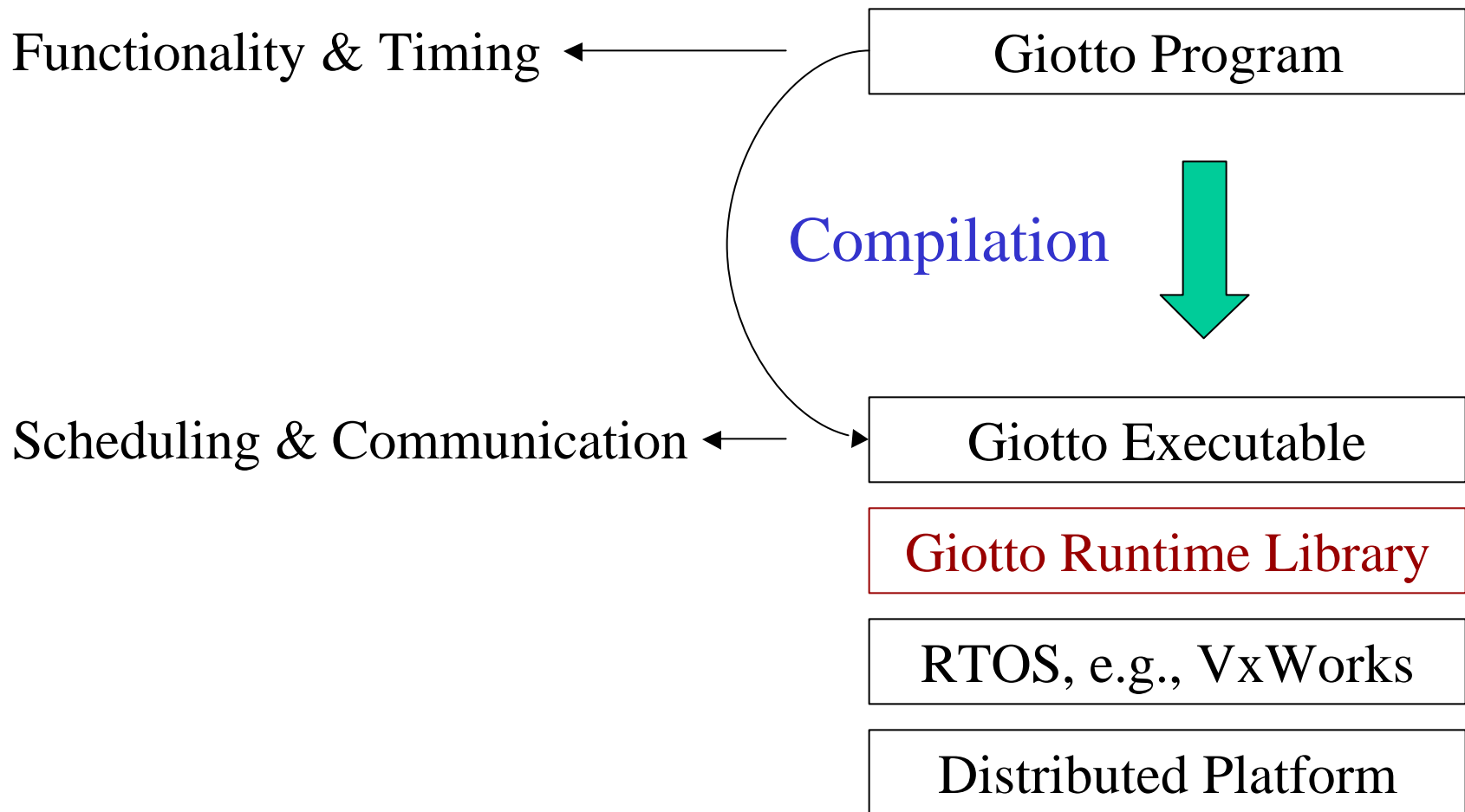
Giotto-PSC



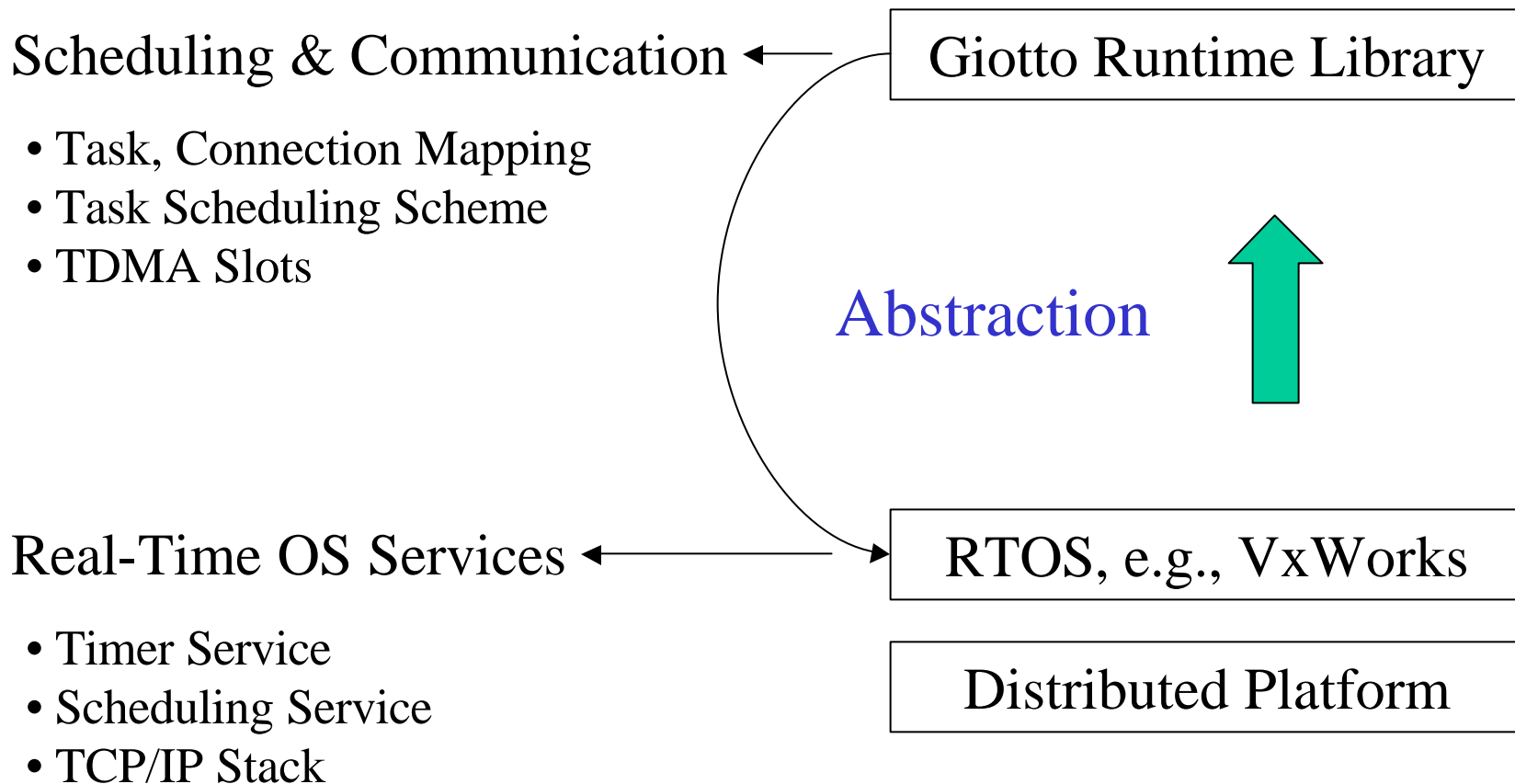
Giotto-PSC



The Giotto Runtime Library



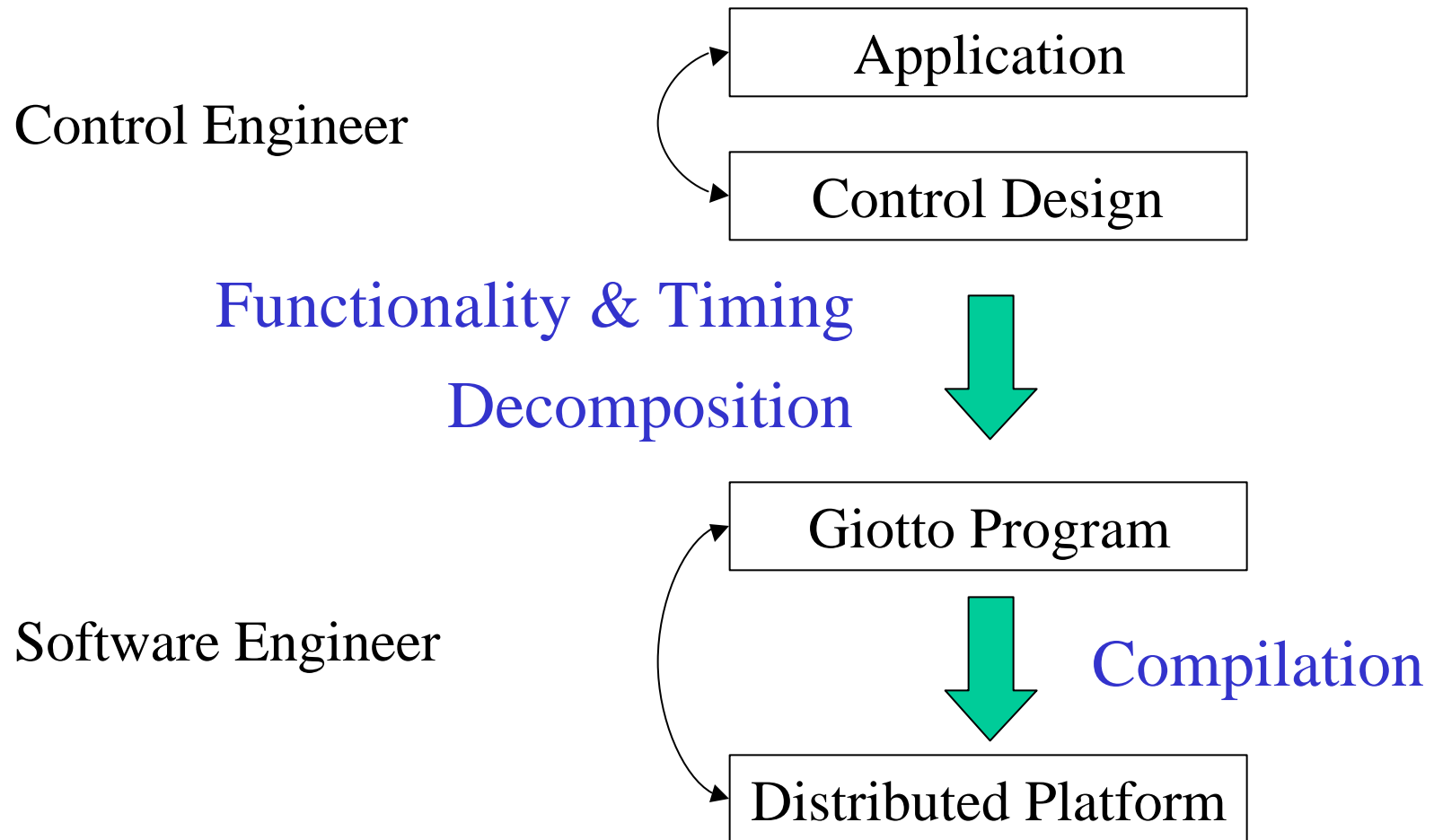
The Giotto Runtime Library



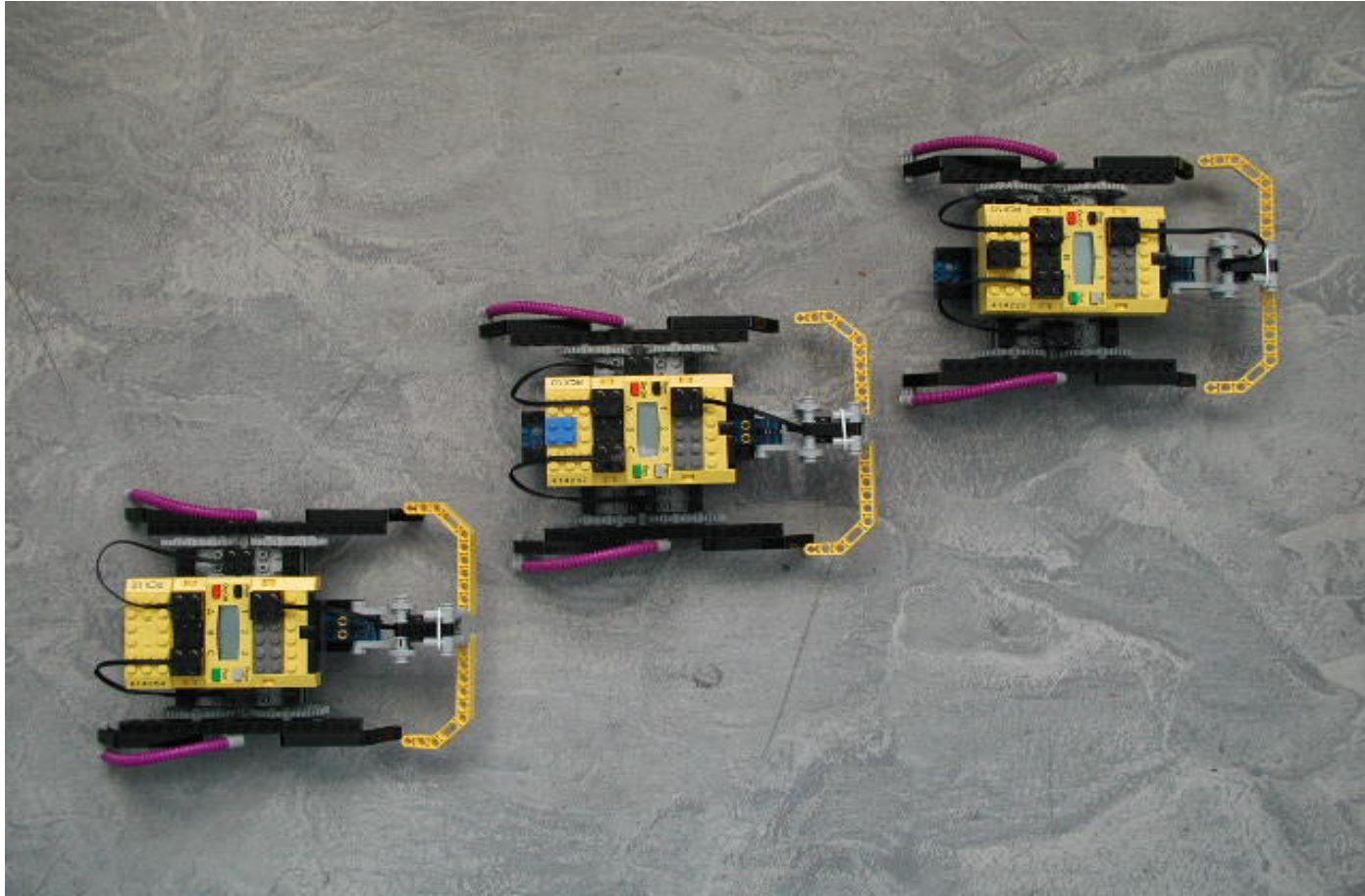
The Giotto Runtime Library

- Available on VxWorks and x86 targets
- Current Experimental Robots:
 - credit card size x86 single board computer running VxWorks
 - wireless Ethernet
 - Lego motors, sensors
- Next Experimental Platform:
 - unmanned Yamaha helicopters
 - PC 104 single board computer running VxWorks
 - wireless Ethernet, GPS, inertial navigation sensor, ...

Summary



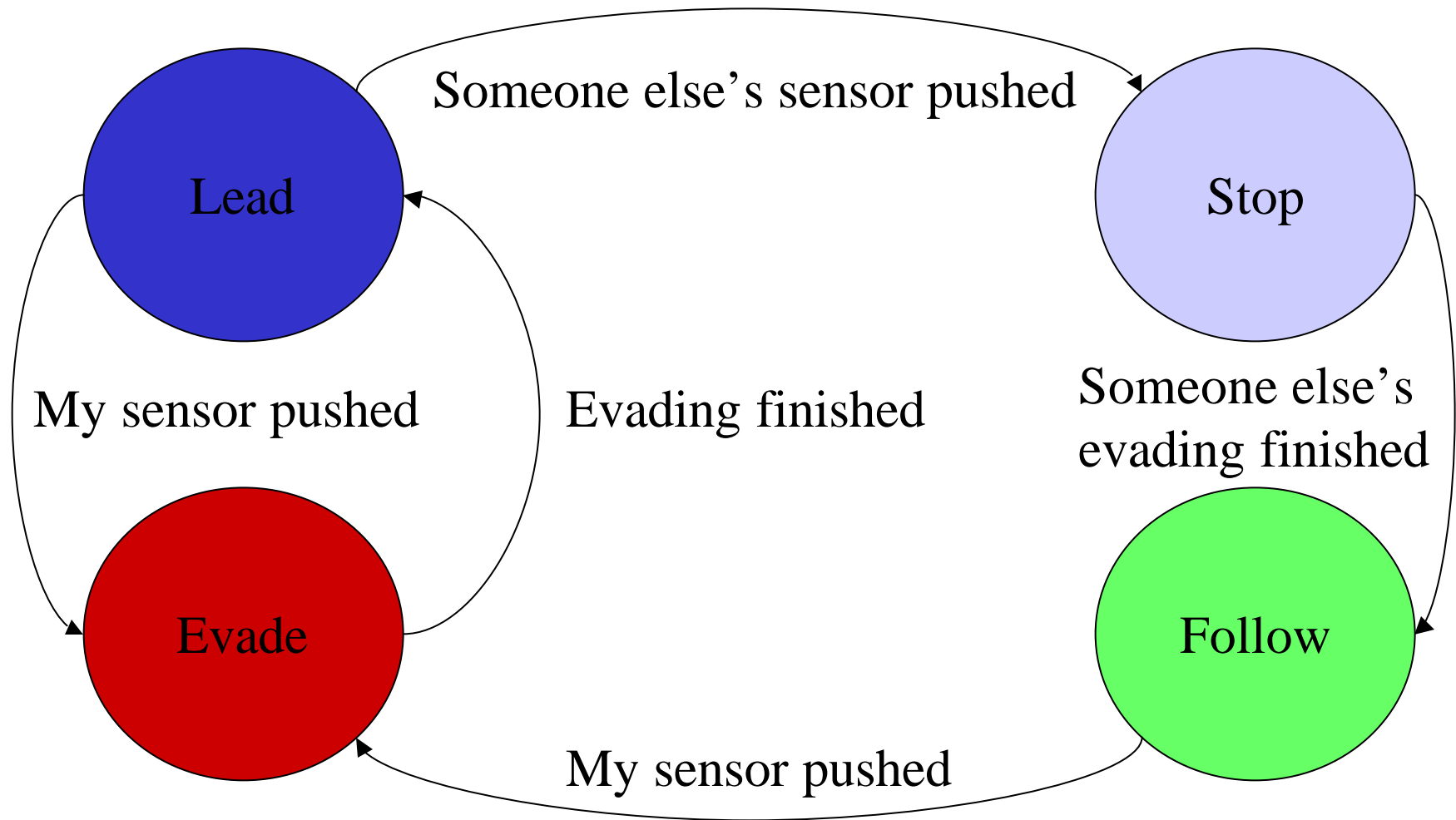
Demo



Demo

- Giotto on Lego Mindstorms:
Concurrent distributed execution
- Giotto on Lego Mindstorms and x86 bots
running VxWorks:
Heterogeneous platforms
- Giotto in Ptolemy:
Design and simulation of Giotto programs

Behavior of a Bot



Demo

- Giotto on Lego Mindstorms:
Concurrent distributed execution

Christoph Meyer Kirsch

Heterogeneous Platforms

1. Lego Mindstorms: [Lego Firmware](#), Hitachi Microcontroller, [Infrared Link](#)
2. x86 bots: [VxWorks](#), x86 single board computer, [Wireless Ethernet](#)
3. Infrared – Wireless Ethernet Bridge:
Laptop

Demo

- Giotto on Lego Mindstorms and x86 bots running VxWorks:
Heterogeneous platforms

Dmitry Derevyanko

Benjamin Horowitz

Christoph Meyer Kirsch

Win Williams

Ptolemy Simulation

Ptolemy is a software package supporting design and simulation of concurrent, real-time, embedded systems:

Giotto defines a model of computation

1. Ptolemy simulates bot example
2. Lego Mindstorms display simulation

Demo

- Giotto in Ptolemy:
Design and simulation of Giotto programs

Christoph Meyer Kirsch

Edward A. Lee

Xiaojun Liu

End

